





University of Victoria
Department of Mechanical Engineering & Institute for Integrated Energy Systems


UVic Green Vehicle Research Program and Student Team Work

- Model and Optimization Based Design and Control


Dr. Zuomin Dong
MECH459 and MECH580

Advance of Hybrid Electric Powertrain Technology


Series → Parallel → Series/Parallel (THS/1-Mode) → Series/Parallel (GM/2-Mode) → Advanced Series/Parallel with Real-time Optimal Control (PHEV, EV and FCEV)





Toyota THS




Volt









GM 2-Mode









University of Victoria Green Vehicle Research & Development

Multi-Mode/Regime Real-time Optimal Control




UVic EcoCAR1 2011




UVic EcoCAR2 2014

Advanced Series/Parallel Real-time Optimal Control



UVic EcoCAR1 2011

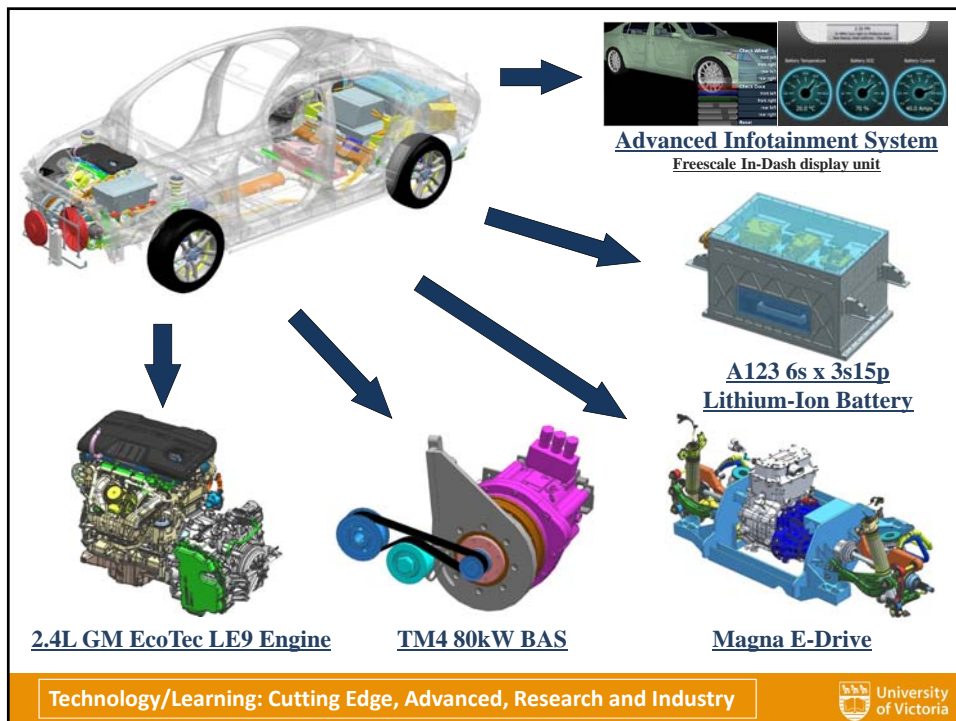


UVic EcoCAR2 2014

Key Technology – Model Based Design, Design Optimization and Optimal Control

EcoCAR – Next Challenge

EcoCAR 2 – Plugging in to the Future



Major Groups

- Modeling/Simulation/System Design
- Mechanical Design, Analysis and Manufacturing
- Power Electronics and Electric Machines
- Control and Embedded System
- Programming
- CAN Bus Communication and Infotainment System
- Prototyping and Retrofitting
- Project Management
- Business Outreach

People/Experience: Multidisciplinary and Ability Training

<http://www.ecocar.uvic.ca>

EcoCAR and EcoCAR 2



- Government and Leading Industry Sponsored Elite Student Design Competition (15 Universities Selected in US/Canada)
- Development of Future Hybrid Electric Vehicle (HEV) Technology by Designing, Modeling, Simulating, Testing, and Retrofitting a 2013 GM Malibu with a Newly Developed Hybrid Powertrain
- Open to Both Undergraduate and Graduate Students
- Getting Training and Experiences on Advanced HEV Technology, Mechatronics and Project Management
- Working with Leading Experts Worldwide through Direct Contacts with Major Industrial Sponsors
- Closely Supervision by Faculty Members with Related Background and Interests

Why It Is Unique and Exciting?

- Urgently Needed, Advanced Technology
- Well Funded Developments:
 - Federal (US, Canadian) and Provincial Supports
 - Extremely Strong Industrial Industry Sponsorship
- Integrated to Academic Program
 - Open to Undergraduate and Graduate Students
 - 3 Year Development Program
- Advanced Research and Training
 - Mechatronics, Hybrid Vehicle, Control, Modeling, System Design, Simulation, Instrumentation, Embedded Systems, CAD/CAE/CAM, Team Work, Project Management, etc.
- Hands on Experiences
 - Advanced Software Tools
 - Advanced Hardware Tools
- **Great Career Opportunities in High-tech and HEV Industry**

The Perks



What We Do

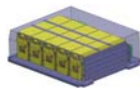
| YEAR & OBJECTIVE | MECHANICAL | ELECTRICAL | CONTROLS |
|--------------------------------------|-----------------------------------------------------------------------------|--------------------------------|----------------------------------------------------------|
| Year 1: Design | Lifecycle analysis, vehicle architecture selection and performance modeling | | |
| | CAD - Component | Define Electrical Requirements | Control System Design |
| | CAD - Routing and Integrations | HIL Design/Setup | Simple Control and SIL/Prelim HIL |
| Year 2: Mule Vehicle | Finalized Component Selection | | |
| | Vehicle Modification | Vehicle Harness/Systems Design | HIL Finalization & Communication Setup |
| | Component Integration | Vehicle Harness Setup | HIL Testing - Safety and Fault Mitigation Implementation |
| Year 3: Optimization & Refinement | Controls Integration and Vehicle Troubleshooting | | |
| | Aero and Lightweighting, R&H, NVH | Refinement and Optimization | Refinement and Optimization |
| | 99% Buyoff - Vehicle Ready for Production | | |

Related Courses and Training (Rewards)

- [MECH459/558 - Fundamentals of Hybrid Vehicles](#) (Technical Elective and Graduate Course) 5:30 - 8:20 pm; Wednesdays; ECS104
Instructor: Dr. Z. Dong (Open to All in the Faculty)
- [MECH497 Green Vehicle Technology Project](#) (3 Units, Crawford & Dong)
- [MECH499 Design Project](#) (ME Faculty Members)
- [ECE499 Design Project](#) (Dr. K. Li)
- [ENGR466 Mechatronics System Design](#) (Dr. D. Constantinescu)
- [MECH499 Honour Thesis](#) (3 Units, ME Fac.)
- [EcoCAR 2 Co-op Terms](#)
- EcoCAR 2 Trainings (at Sponsors' sites) and EcoCAR 2 Developments
- [Graduate Studies at M.A.Sc. And Ph.D. Levels](#)

New UVic Green Vehicle Research, Testing and Training Centre

- **First Class Green Vehicle Development and Testing Facilities**
 - Computer Modeling, Design and Simulation
 - Hardwire in Loop Testing
 - Advanced Battery Pack Development
 - 4WD, Active Braking Enabled Chassis Dynamometer
 - Engine Dynamometer
 - Emission Measurement
- **Hands on Shop**
 - Automotive Shop
 - Small Machine Shop
 - Small Electronics Shop

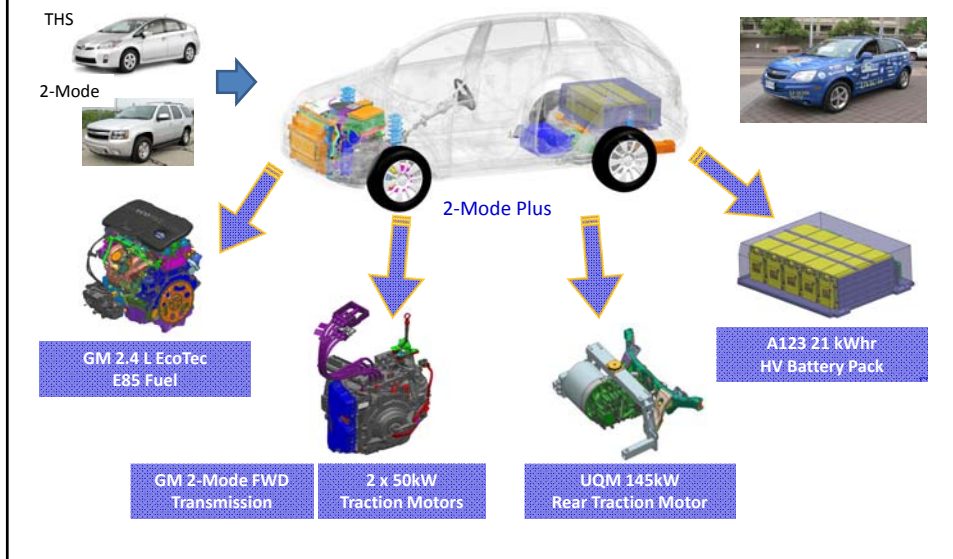


University of Victoria EcoCAR – the NEXt Challenge 2009-2011



- **Team Leaders**
 - Jeremy Wise and Jeffery Walden
- **Faculty Advisors**
 - Dr. Zuomin Dong (zdong@uvic.ca)
 - Dr. Curran Crawford (ccrawford@uvic.ca)
- **Website and contact:** <http://www.ecocar.uvic.ca>

UVic EcoCAR 1 – Push the HEV Technology Boundary



Results at End (2011)



| Specification | EcoCAR Competition | | UVic EcoCAR1 | | |
|--------------------|----------------------|--------------------------------------------------------------------|---------------------|------------------------------------------|---------------------|
| | GM Production VUE | Competition Requirements | Target VTS | Test Result Y2 | Test Result |
| Accel 0-60 | 10.6 s | ≤ 14 s | 7.5 s | 12.36 s | 6.35 s |
| Accel 50-70 | 5.7 s | ≤ 10 s | 5 s | 8.96 s | 3.45 s |
| UF Weighted FE | 8.3 L/100 km | 7.4 L/100 km | 2.5 L/100 km | Test Not Complete | 5.88 (UDDS) |
| Towing Capacity | 680 kg (1500lb) | ≥ 680kg @ 3.5%, 20 min @ 72 km/h (45mph) | 682 kg (1500lb) | ≥ 680kg @ 3.5%, 20 min @ 72 km/h (45mph) | Test Not Complete |
| Cargo Capacity | 0.83 m ³ | Height: 457 mm (18") Depth: 686 mm (27") Width: 762 mm (30") | 0.70 m ³ | 0.83 m ³ | 0.83 m ³ |
| Passenger Capacity | 5 | ≤ 4 | 4 | 5 | 5 |
| Braking 60-0 | 38-43 m (123-140 ft) | < 51.8 m (170 ft) | 48 m | 42m | 46m (152 ft) |
| Mass | 1758 kg (3875 lb) | 2268 kg (5000 lb) | 2145 kg (4729 lb) | 4916 lb | 4982 lb |
| Starting Time | ≤ 2 s | ≤ 15 s | ≤ 2 s | 2 s | 1 s |
| Ground Clearance | 198 mm (7.8 in) | ≤ 2 s | 178 mm (7 in) | 7 in | 7 in |
| Range | ≥ 580 km (360 mi) | ≥ 320 km (200 mi) | ≥ 320 km (200 mi) | Test Not Complete | Test Not Complete |



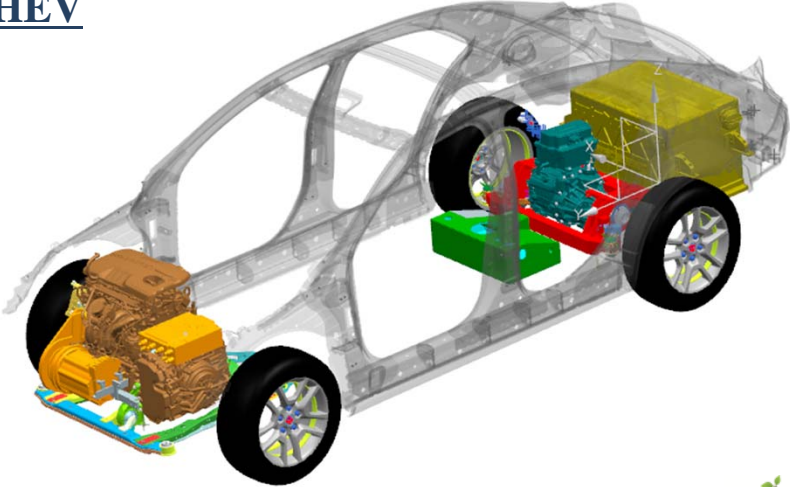


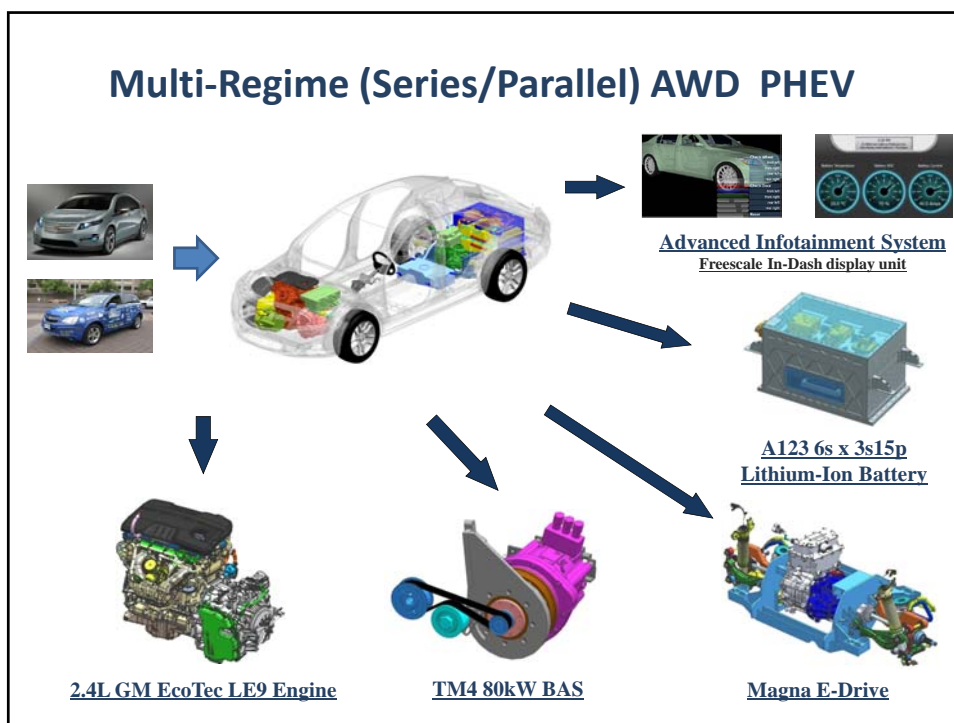
University of Victoria EcoCAR 2 – Plugging in to the Future

- Team Leaders
 - Stefan Kaban/Daniel Prescott/John Walsh/Kevin Andersen
- Faculty Advisors
 - Dr. Zuomin Dong (zdong@uvic.ca)
 - Dr. Curran Crawford (ccrawford@uvic.ca)
- Website and contact: <http://www.ecocar.uvic.ca>



AWD Series-Parallel PHEV

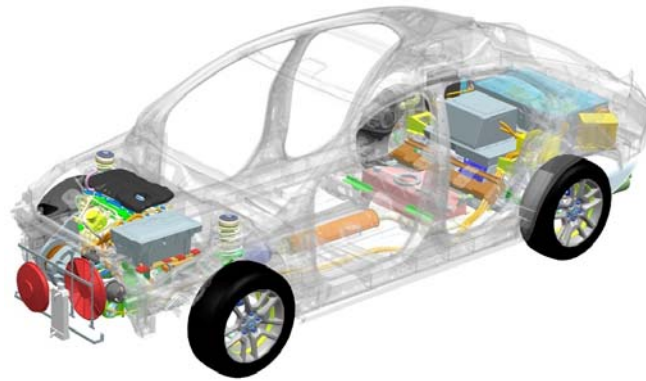




VEHICLE TECHNICAL SPECIFICATIONS

| Specification | Production 2013 Malibu | UVic Series-Parallel Malibu |
|-------------------------------------|-----------------------------|-----------------------------|
| Acceleration 0-60mph | 8.2 sec | 8.5 sec |
| Acceleration 50-70mph | 8.0 sec | 3.8 sec |
| Braking 60-0mph | 143.4 ft. (43.7 m) | 142.7 ft. (43.5 m) |
| Highway Grade-ability (20 minutes) | 10% @ 60mph | 4.2% @ 60mph |
| Cargo Capacity | 16.4 ft ³ | 7 ft ³ |
| Passenger Capacity | 5 | 5 |
| Mass | 1589.6 kg | 2078 kg |
| Ground Clearance | 155 mm | 156 mm |
| Charge Depleting Range | N/A | 83.8 km |
| UF-Weighted Fuel Energy Consumption | 8.83 lge/100 km [787 Wh/km] | 3.37 lge/100 km |
| Criteria Emissions | Tier 2 Bin 5 | Tier 2 Bin 5 |

Overall Development Plan



UVic EcoCAR2 through Optimization

Goals - Minimize emissions and energy consumption (Y3 points; E&EC performance)

Powertrain design and prototyping - advanced powertrain architecture, sizing and control System

- Support flexible multiple mode vehicle operations
- Enable optimal vehicle operation for different demands

Leading-edge powertrain control technology

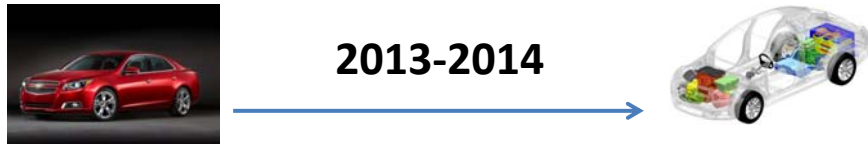
- Real-time optimal control to maximize efficiency/performance
- Optimal/intelligent energy management (fuel economy and life)
- Integrated Infotainment system (improved utility and efficiency)

Design for low mass, manufacturing, maintenance and reliability

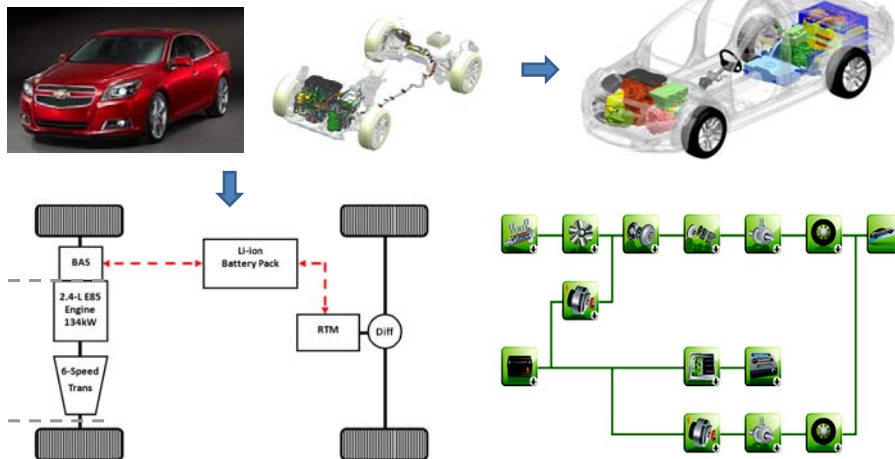
- Essential to have a fully functional vehicle
- Lesson from EC1



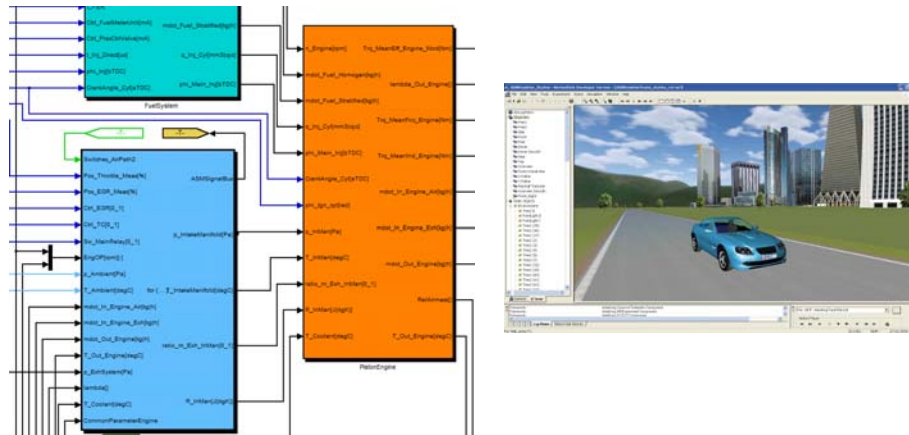
An Example: What we have done in EcoCAR2 Y3



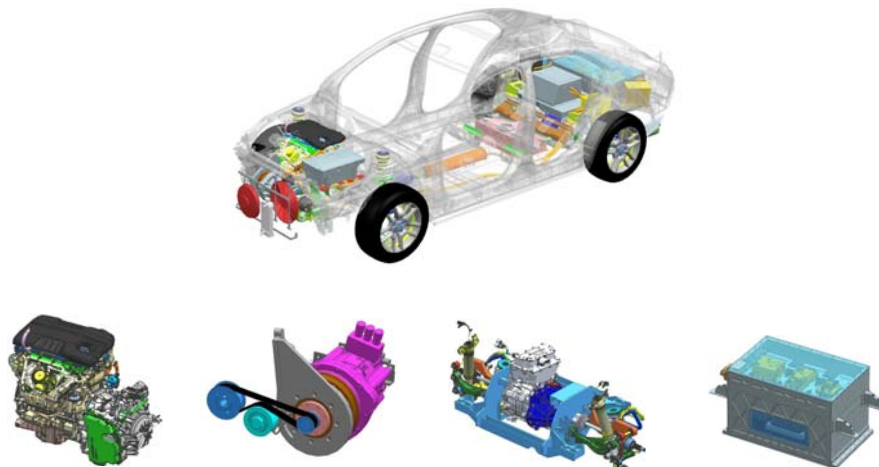
Hybrid Electric Powertrain Design, Modeling, and Optimization

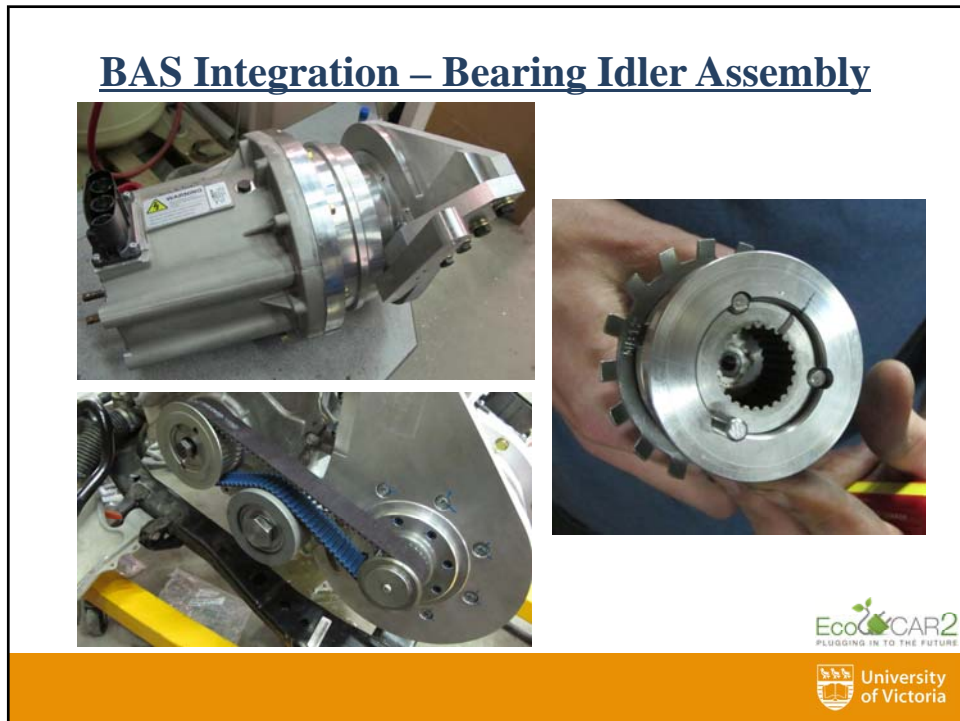
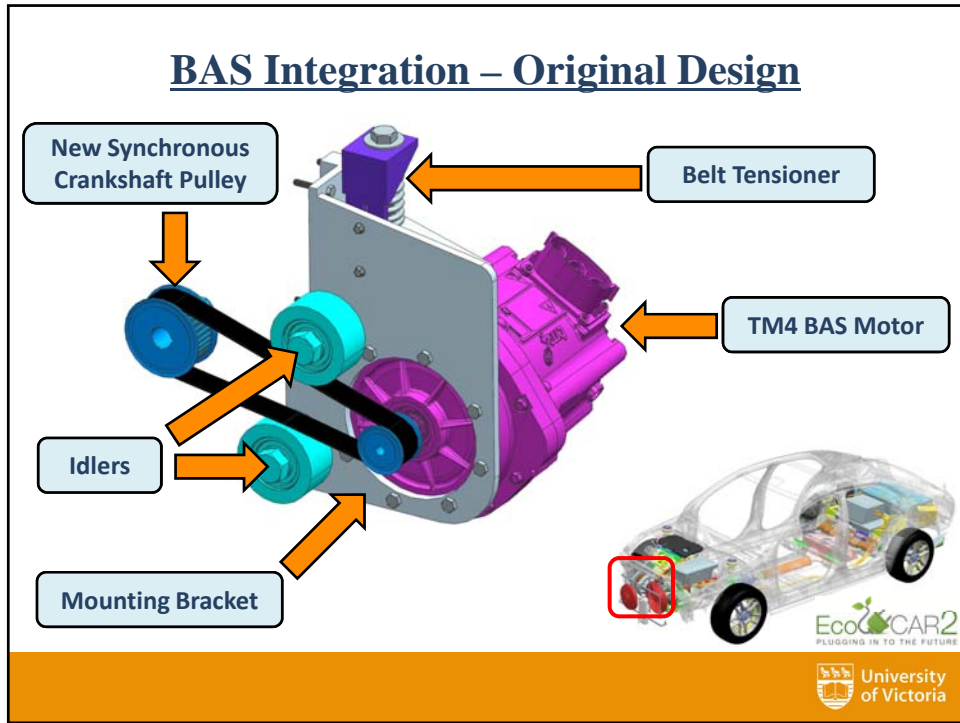


Modelling and Simulation Using dSPACE ASM

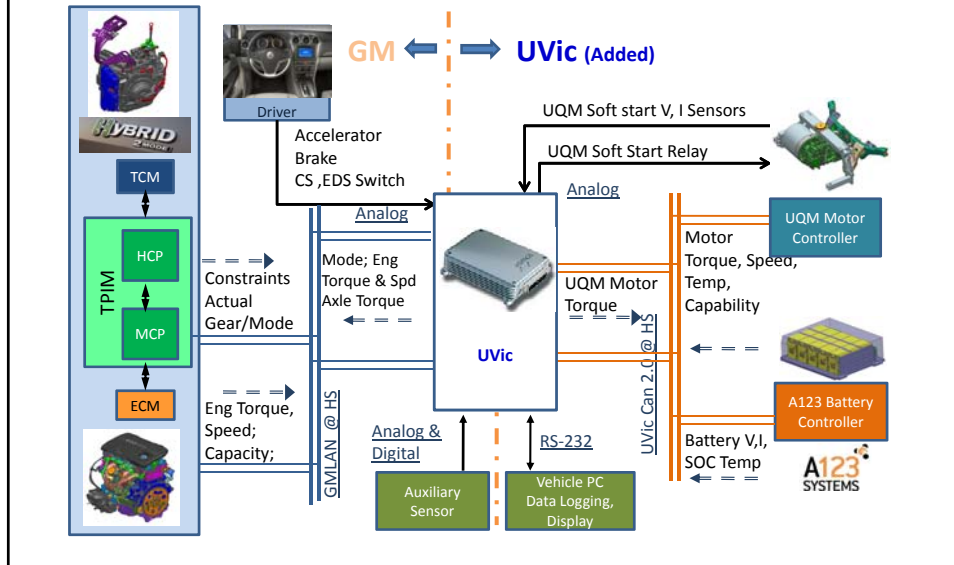


Mechanical Design, Optimization, Prototyping/Refrification/Manufacturing

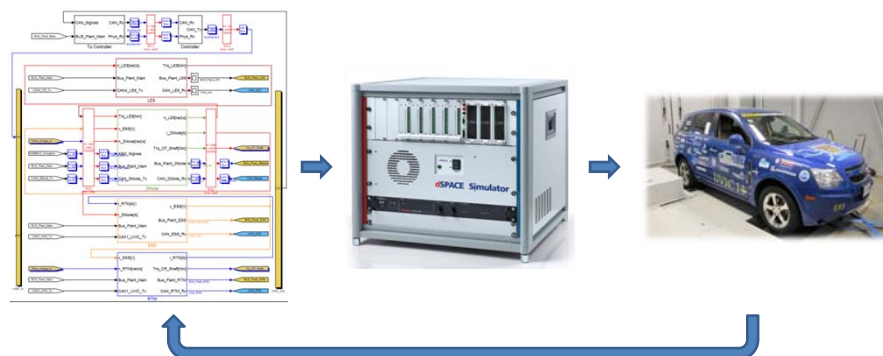




UVic 4WD 2-Mode Plus EcoCAR Control System



Electrical/Controls/Software/Testing



Hardware in Loop (HIL) and In-Vehicle Testing under UDDS and HWFET cycles to validate of design and control system

New to EcoCAR 2: Infotainment System

- Android and Ca-Fi: 6.2 inch touch screen LCD, powered by The Freescale™ Cartex™ A8 i.MX5x processors running at 1.2 GHz; music and other audio with output connections for camera, USB and antennas, designed to be compatible with all sorts of car.
- Mercedes-Benz A-Class concept
- Toyota Entune in-car infotainment system
- Other electronics and embedded systems: solar roof Prius, etc.



Dyno Testing



UVic EcoCAR 2009 Competition Awards

- 2nd Place Overall
- 1st Place First Year Technical Reports
- 1st Place, MathWorks Modeling Award
- Best Electrical Systems Presentation
- 2nd Place, Hardware-in-Loop Evaluation
- 3rd Place, dSPACE Embedded Success Award
- Best Media Relations Program



Faculty Advisors: Zuomin Dong and Curran Crawford



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UVic EcoCAR 2010 Competition Awards

- 4th Place Overall Award
- Best Technical Reports Award
- US National Science Foundation Outstanding Incoming Advisor Award (Drs. Dong and Crawford)
- Ron Stence Spirit of Challenge Award
- Dr. Don Streit Sportsmanship Award
- Modeling and Simulation (dSPACE) - 3rd Place Award
- Energy Storage System Design (A 123Systems) - 3rd Place Award
- Sprit of Outreach Award



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UVic EcoCAR 2011 Competition Awards

- 1st Place MathWorks Award - Optimal Powertrain Design and Control
- 1st Place dSPACE Award - Hardwire in Loop Testing and Vehicle Dynamics Modeling
- Fastest 0-60 miles/h Acceleration (6.3 seconds)
- Fastest 50-70 miles/h Acceleration (3.5 seconds)
- Best Engineering Workmanship Award (Overall Appearance and Design for Service)
- 3rd Place A123 Workmanship Award - 21 kWh Li-ion Battery Pack Design and Prototyping
- Best EcoCAR Website Award (<http://www.ecocar.uvic.ca>)



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UVic EcoCAR2 2012 Competition Awards

- First Place - Mechanical Design Award
- First Place MathWorks (Modeling, Simulation and Optimization) Award
- Third Place A123 Battery System Award
- Third Place Infotainment System Award

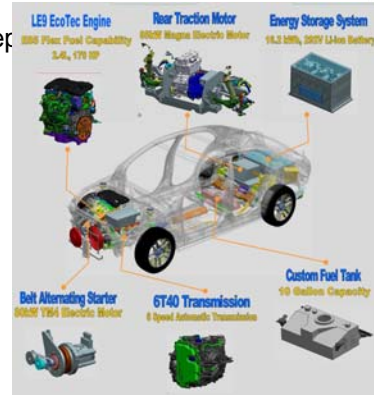


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UVic EcoCAR2 2013 Competition Awards

- First Place Award in [Mechanical Design](#) and Presentation
- First Place Award in MATLAB Modeling and Application
- First Place Award in Infotainment System
- Highest Scores of all Year 2 Technical Reports
- Third Place in Electrical System
- Third Place in Control System
- First Place of Team Skit Video



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UVic EcoCAR2 2014 Competition Awards

- 1st Place – MathWorks – Modeling Award
- 2nd Place – *dSPACE* Embedded Success Award
- Dr. Donald Streit Sportsmanship Award
- 2nd Place - Controls Presentation
- 2nd Place – Business Final Presentation
- 3rd Place – Mechanical Presentation
- 2nd Place (with 5 others) – 0-60 Mile Acceleration of the Vehicle



Enhanced Curriculum at UVic

NEW COURSES INTRODUCED

- MECH459/558 - Fundamental of Hybrid Electric Vehicles (Offered in 3B) (Open to All Grad. Students)
Instructor: Dr. Z. Dong (Open to Team Members)
- MECH497 Green Vehicle Technology Project (3 Units, Crawford & Dong)

EXTENSION OF EXISTING COURSES

- MECH499 Design Project (ME Faculty Members)
- ECE499 Design Project (Dr. K. Li)
- MECH464 Mechatronics System Design (Dr. D. Constantinescu)
- MECH498 Honour Thesis (3 Units, ME Fac.)

ECOCAR 2 CO-OP TERMS

- EcoCAR 2 Trainings (at Sponsors' sites) and EcoCAR 2 Developments

GRADUATE STUDIES AT M.A.SC. AND PH.D. LEVELS

Advanced Industrial Training



TRAINING AT MAJOR SPONSORS' FACILITIES (5-12 team members)

- **Computer Modeling**
 - MathWorks MATLAB/Simulink Multi-physics Modeling Tool (\$1.5M)
Headquarter (Boston) & Workshop/Seminars at UVic (Fall and Spring)
 - Siemens NX Computer Aided Design and Engineering Software Tools (\$50M)
 - US Argonne National Lab (ANL)'s Advanced Vehicle Powertrain Modeling Tools (\$50K)
- **Automotive**
 - GM Research Center (MI) and Vehicle Proofing Grounds (MI & AZ)
 - US EPA Vehicle Testing Facilities (MI)
- **Electronics**
 - dSPACE (ANL) Hardware in Loop Tech/Equipment & Vehicle Dynamics Modeling (\$400K)
 - Freescale Microcontrollers
- **Energy Storage and Battery System**
 - A123 High Power Battery Modules and Technical Supports (MA, \$70K)

FULL TECHNICAL SUPPORTS AND TUTORING (Mentors / Team Technical Support Staffs)

- GM, Siemens, dSPACE, A123, Freescale, etc.

CO-OP TERMS

- EcoCAR 2 Related Trainings (at Sponsors' sites) and UVic EcoCAR Co-op Terms



Formula Hybrid

<http://students.sae.org/competitions/formulaseries/hybrid/>

- 2014 Competition:
 - April 28 - May 1, 2014
New Hampshire International Speedway, Loudon, NH
 - Registration Fee: \$1,750.00
Registration Limit: 35 teams
Registration Opens:
 - For Hybrid category on Monday, October 7, 2013 10:00 AM EDT
 - For Electric category on Wednesday, October 9, 2013 10:00 AM EDT
 - For entry of a 2nd team vehicle on Monday, November 4, 2013 10:00 AM EST



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Formula Hybrid Contact

- **Doug Fraser**
Director, Formula Hybrid
603.646.3522
- **Amy Keeler**
Coordinating Manager
603.646.6580
- **Formula Hybrid**
Thayer School of Engineering at Dartmouth
14 Engineering Drive
Hanover, NH 03755
- Email: info@formula-hybrid.org
- For rules questions, visit the [Formula Hybrid Support Center](#).
- To submit required documents, visit the [Formula Hybrid Document Upload Page](#).



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What is Formula Hybrid?

- Formula Hybrid™ is a design and engineering challenge for undergraduate and graduate college and university students. They must design, build, and compete an open-wheel, single-seat racecar. This car must conform to a formula which emphasizes drive train innovation and fuel efficiency in a high-performance application.
- Formula Hybrid builds on the Formula SAE program and takes it to the next level. It adds a new layer of complexity and provides an additional technical challenge to student teams. We expect that one path of entry to the Formula Hybrid competition will be to construct the vehicle and develop the chassis and related systems in the Formula SAE program and then replace the IC engine with a hybrid drive train the following year for the Formula Hybrid competition, resulting in a two-year design cycle.



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Competition Information

- [Rules and Important Documents](#)
- [Register](#)
- [Online Registration Guide](#)*
- [Registered Teams](#)
- [Event Website](#)
- International students will need to download and complete the [International Student Registration form](#) and submit to CDS staff for use during onsite registration at event.



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2014 Formula Hybrid Teams

| | | | |
|-----|---------------------------------|-----|------------------------------|
| 029 | Atilim University | 027 | Nitte Meenakshi Inst of Tech |
| 016 | Carnegie Mellon Univ | 017 | Princeton Univ |
| 021 | Dartmouth College | 024 | Rensselaer Polytechnic Inst |
| 023 | Delhi Technological University | 013 | RV College of Engineering |
| 005 | Embry-Riddle Aero Univ | 018 | Tufts Univ |
| 028 | Ferris State University | 015 | Univ of Akron |
| 025 | Georgia Institute of Technology | 026 | Univ of Houston - Houston |
| 020 | Illinois Inst of Tech | 014 | Univ of Idaho |
| 002 | Lawrence Technological Univ | 004 | Univ of Michigan - Ann Arbor |
| 003 | McMaster Univ | 012 | Univ of Waterloo |
| 011 | Middle Tennessee State Univ | 019 | University of Vermont |
| 022 | Milwaukee School of Engrg | 001 | Yale Univ |

Major Sponsors

- **Platinum Sponsors** 
- **Gold Sponsors** 
- **Silver Sponsors** 
- **Friends of Formula Hybrid** 
- **Team Sponsors** 
- **Additional Sponsors** 
- **UVic Sponsors** 

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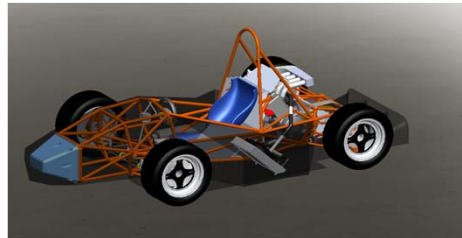
Event points breakdown for 2014 Formula Hybrid event

| Static Events | | Hybrid |
|---------------------|-----------------------------|-------------|
| | Presentation | 100 |
| | Engineering Design | 200 |
| Dynamic Events | | |
| | Acceleration - Electric | 75 |
| | Acceleration - Unrestricted | 75 |
| | Autocross | 150 |
| | Endurance | 400 |
| Total Points | | 1000 |

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| 2014 Formula Hybrid™ Summary Score Sheet | | | | | | | | | | | |
|------------------------------------------|---------|----------------------------------------|--------------|--------|-------------------------|-----------------------------|-----------|-----------|--------------------------|-----------------------------|-------------------|
| Line No. | Car No. | Team Name | Presentation | Design | Acceleration - Electric | Acceleration - Unrestricted | Autocross | Endurance | Total Penalties Assessed | Total Score 1000H / 925E | Position in Class |
| | | | 100 | 200 | 75 | 75 (1) | 150 | 400 | | | |
| HYBRID DRIVE CLASS | | | | | | | | | | | |
| 1 | 1 | Yale University | 85.40 | 142.94 | | | 0.00 | 0.81 | | 229.15 | 4 |
| 2 | 2 | Lawrence Technological University | 56.19 | 148.95 | | | 0.00 | 48.48 | | 253.63 | 2 |
| 3 | 3 | McMaster University | 96.61 | 200.00 | | | 0.00 | 0.00 | -100.00 | 196.61 | 7 |
| 4 | 4 | University of Michigan | 93.35 | 51.35 | | | 0.00 | 75.33 | | 220.03 | 5 |
| 5 | 5 | Embry-Riddle Aeronautical University | 100.00 | 151.35 | | | 0.00 | 0.00 | | 251.35 | 3 |
| 6 | 12 | University of Waterloo | 76.27 | 0.00 | | | 0.00 | 0.24 | | 76.51 | 10 |
| 7 | 13 | RV College & Nitte Meenakshi Institute | 73.01 | 68.47 | | | 0.00 | 0.00 | | 141.48 | 9 |
| 8 | 14 | University of Idaho | 83.44 | 178.17 | | | 0.00 | 0.08 | | 261.70 | 1 |
| 9 | 22 | Milwaukee School of Engineering | 56.32 | 128.53 | | | 0.00 | 0.00 | | 184.85 | 8 |
| 10 | 24 | Rensselaer Polytechnic Institute | 90.48 | 109.31 | | | 0.00 | 0.00 | | 199.79 | 6 |
| 11 | 28 | Ferris State University | 0.00 | 0.00 | | | 0.00 | 0.00 | | 0.00 | 11 |
| 12 | 29 | Attilm University | 0.00 | 0.00 | | | 0.00 | 0.00 | | 0.00 | 11 |
| 13 | | | | | | | | | | | |

UVic "Traditional" Formula SAE Team



Competition information at [Formula Hybrid website](#) most commonly used student resources located under the 'Students' tab

- Anticipating a fantastic competition next year with between 25 and 35 international teams represented.
- [Start a Team](#) – outlines suggestions for getting started
- [Forum](#) – have team leaders sign on to keep up-to-date with rules updates, etc.
- [Rules and Deadlines](#) - Read the **2014 Rules** – the 2015 Rules are expected to release on September 1, major changes are currently posted under the Announcements page. **Action deadlines** for 2015 will be similar to those outlined for this year (some dates will be earlier)
- [Announcements](#) – outlines updates over the past year
- **Components** - [supplier sponsored](#) (free or heavily discounted parts) and [recommended components](#) (recommended by FH staff and alums)
- [Schedule and Program](#) (2014) – Read this to become familiar with the track layout, schedule of events, daily operations, etc.
- [Tech Support and References](#) – When your team runs into technical questions you can submit a ticket with the [FH Support Center](#). The [Document Upload Page](#) is where you'll submit action deadlines. 2014 Action Deadlines can be viewed for reference. Some of these will be updated in 2015.
- Follow the event on Facebook (Formula Hybrid) and Twitter (@Formula_Hybrid).
- Registration will open in early October. (anticipate the registration fee increasing to \$2,100 USD and the cap on registration is 35 teams, with hybrids receiving priority registration (a few days earlier than electrics).
- One of the most significant changes this year - updating the business presentation to a project management presentation.



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Formula Hybrid Management

- Amy Keeler
Coordinating Manager, Formula Hybrid
Thayer School of Engineering
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603.646.6580



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UVic Formula Hybrid Team

Team Leaders: Edward Ted Alley & Ryan Johnston

- Charles Jumbo <cjumbo@uvic.ca>;
- Leon Yan <leonyan29@gmail.com>;
- Joseph George <josephge@uvic.ca>;
- Eric Ashlee <ericash@uvic.ca>

Control and Modeling – Rough Model for Cost Estimation

- Daniel Prescott <d.e.prescott@gmail.com>;
- Edward Ted Alley <ehralley@gmail.com>;
- Rui Cheng <ruicheng@uvic.ca>;
- Jackie Dong <jdong@uvic.ca>;
- Herbert Zhu <hongboz@uvic.ca>;
- Aaron Kao <kaoaaron@uvic.ca>;
- Martin Guinto <martinguinto@gmail.com>;

Electrical

- Kevin Andersen <kevinandersen83@gmail.com>;
- Xing Zhang <jason.xing.zhang@gmail.com>;
- Humam Altayeb <hsa@uvic.ca>;
- Tal Melamed <tal.melamed.69@gmail.com>;

IT and Programming

- Morgan McKenzie <rmtm@uvic.ca>;

Formula SAE

- James Thomson <angus86@uvic.ca>;
- Scott Egan <thescottegan@gmail.com>;

Mechanical

- Ryan Johnston <ryan.r.johnst@gmail.com>;
- Brian Everts <BrianEverts@shaw.ca>;
- Kailey Allan <KaileyA@uvic.ca>;
- Victor Oliveira <victoroliveirab@hotmail.com>;
- Victor Souza <victorc@uvic.ca>;

Outreach and Project Management

- Valery Heckel <valeryheckel@gmail.com>;
- Martin Guinto <martinguinto@gmail.com>;

Weekly Team Meeting: Tue 5:00 pm Q-Hut



Reception and Open House at “Q-Hut”

