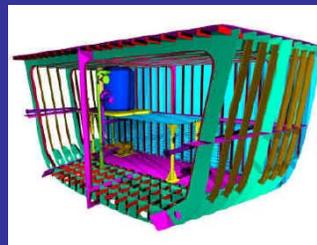
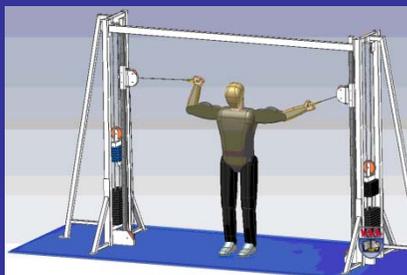
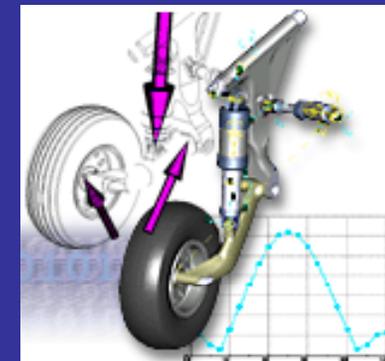
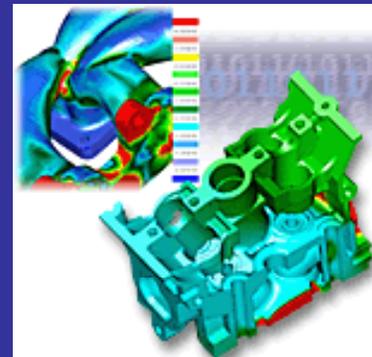
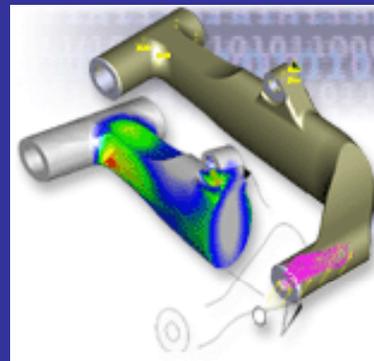
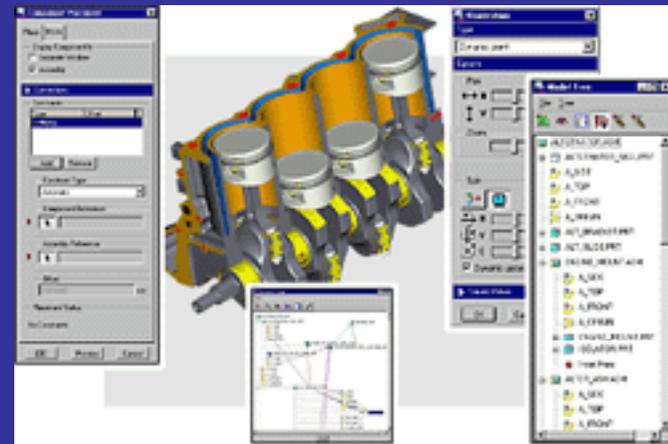
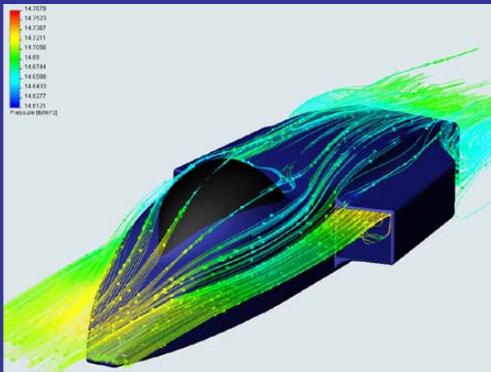


Final Project and Pro/E Applications



Final Project - Application of Integrated CAD/CAE/CAM System for Optimal Design, Design Improvement or Soft-prototyping

- Time: March 5 – 31
- Content: Your Choice
- MECH410: Group of 2
- MECH520: Individual

- Project Presentation: March 31, Tue, (1:30 – 4:30 pm)
ELW238 Computational Design Lab
- Project Report Due: April 3

Three Project Options

- An Application of Integrated CAD/CAE/CAM System
(Software: Pro/Engineer, UG NX 6, or SW)
 - creating the **optimal** (or at least **functional**) **design** of a **new** product with
 - performance analysis (structure, thermo, flow, dynamics, etc.), or
 - animation/simulation (motion, dynamics, manufacturing, etc.), or
 - improving a **complex, existing design** through analysis and/or simulation, or
 - creating demanding and **complex design models**.
- Interactive Graphics Programming in CAD
- An Application of Integrated CAD/CAE/CAM System Using Other Packages

A 3-5 minute slide presentation (4-6 slides) and program demonstration.

Format of the Project Report

Format

Title of the Project

Names and Student Numbers

Abstract (50 – 100 words)

Table of Contents

1. Introduction (Description of the Project, Problem Definition, Theory or Algorithm)
2. Implementations
3. Technical Challenges
4. Special Features and Highlights
5. Summary (Experience and Suggestions)

References

Appendix

- A. Important figures, drawings, calculations, etc.
- B. Electronic copy of all related and necessary Pro/E files and other source codes.

Email the following documents to: mech410@me.uvic.ca

- A Microsoft PowerPoint Presentation (4-6 slides): LastName1_LastName2 (.ppt)
- Project report in *MS Word* named as: LastName1_LastName2 (.doc)
- The Pro/E model files with the same name as above (different extension name).

Laboratory Consultants:

- Mr. Minh Ly (Sen. Sci) Office: ELW B264, Local: 8893, and Email: mly@me.uvic.ca
- Leon Zhou (TA) Office: Email: ylzhou@me.uvic.ca

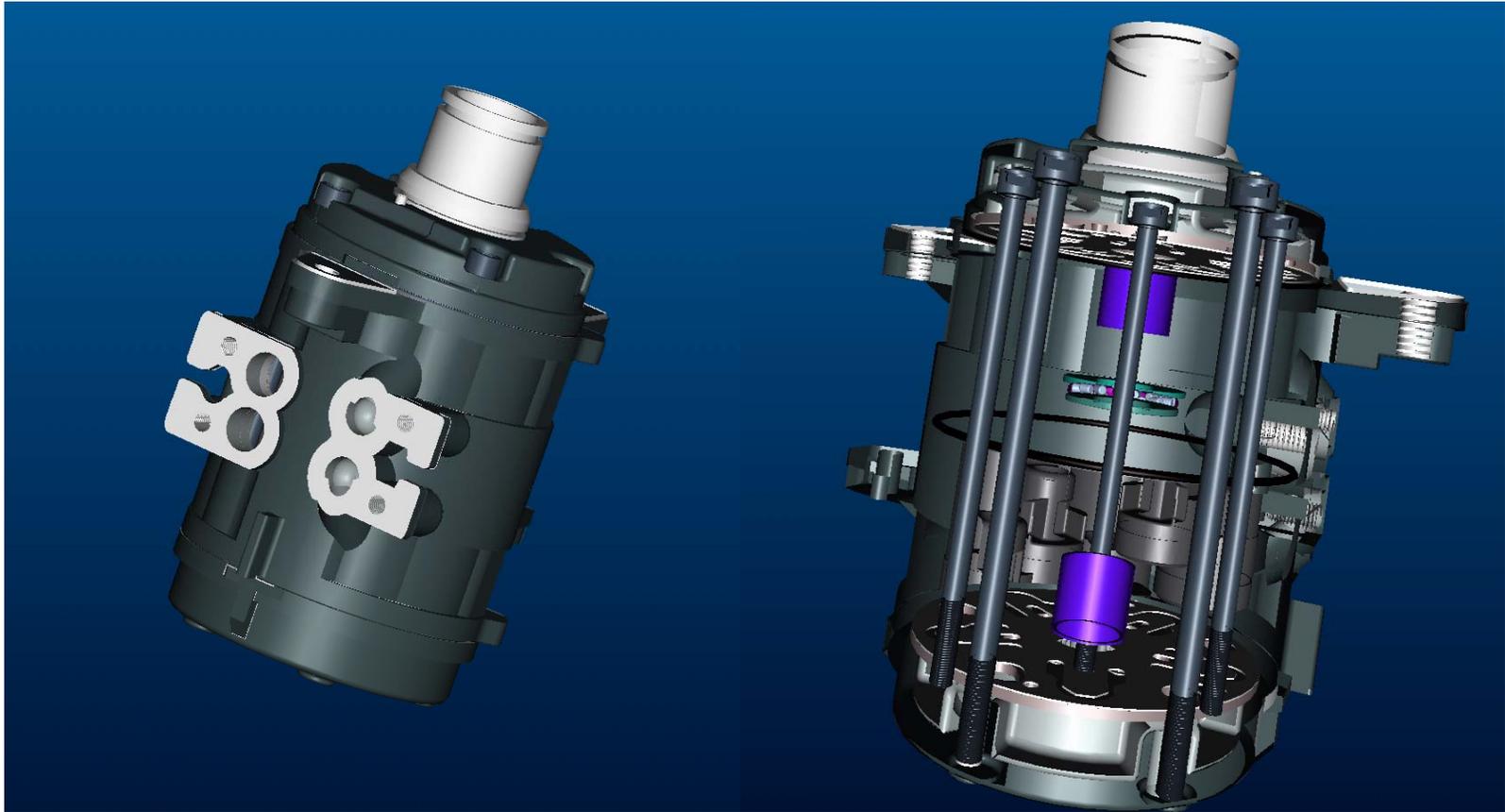
Scope of the Project

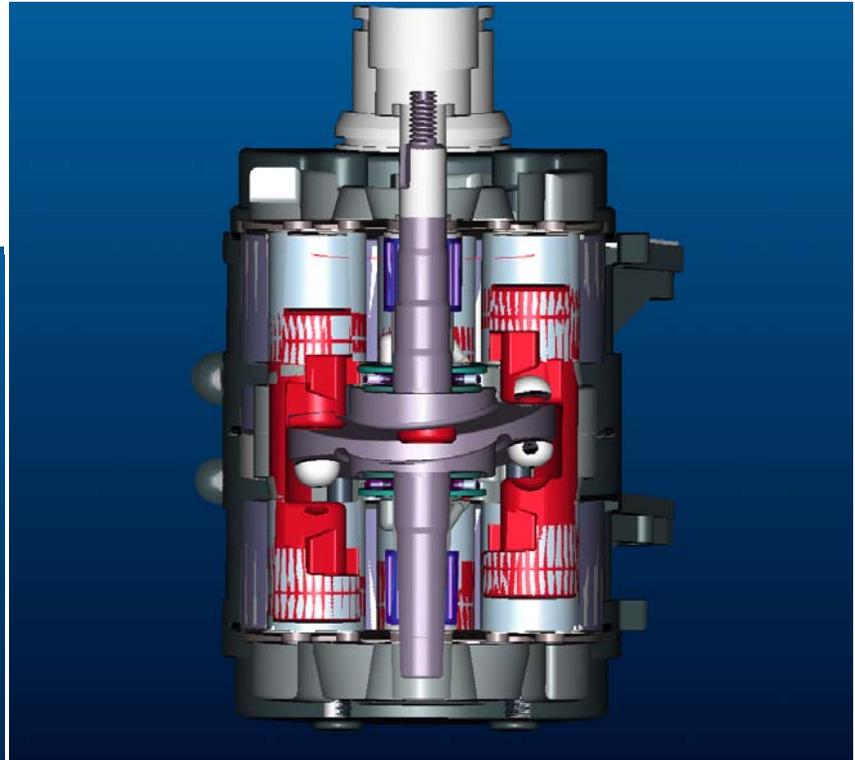
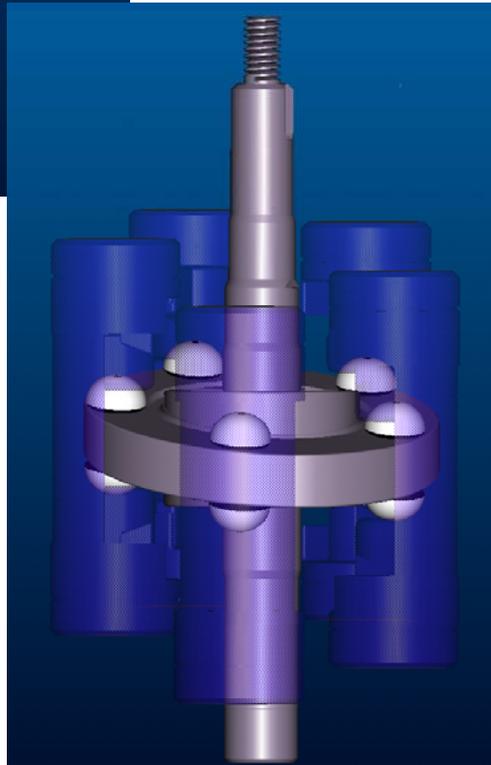
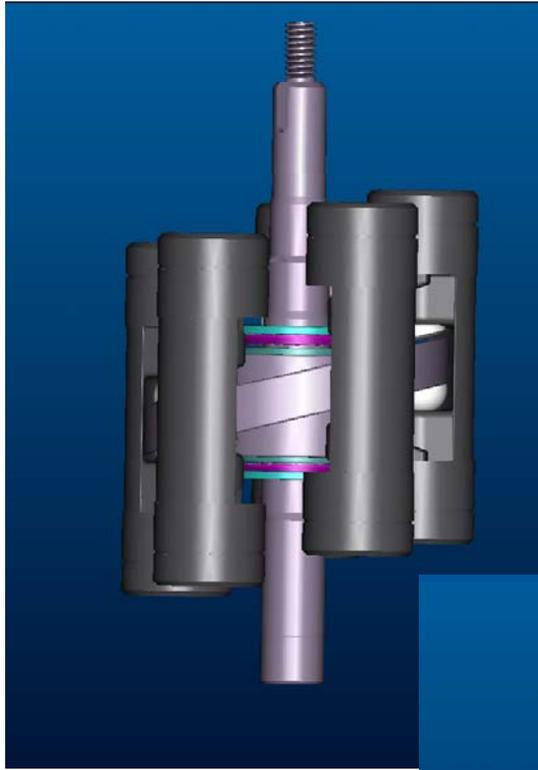
- Design, Analysis, Animation, Planning, Manufacturing and Optimization
- Mechanical Device, Assembly, Product and System
- Being able to show how CAD/CAE/CAM tools are used to obtain better design(s) by introducing:
 - design feedback and improvements
 - design optimization
- Any CAD/CAE/CAM Tool
- Interactive Graphical Programming
- ...

Example Projects

Air Conditioner Pump for a 1987 Merkur XR-4Ti

Chris Heynen & Brian Connors

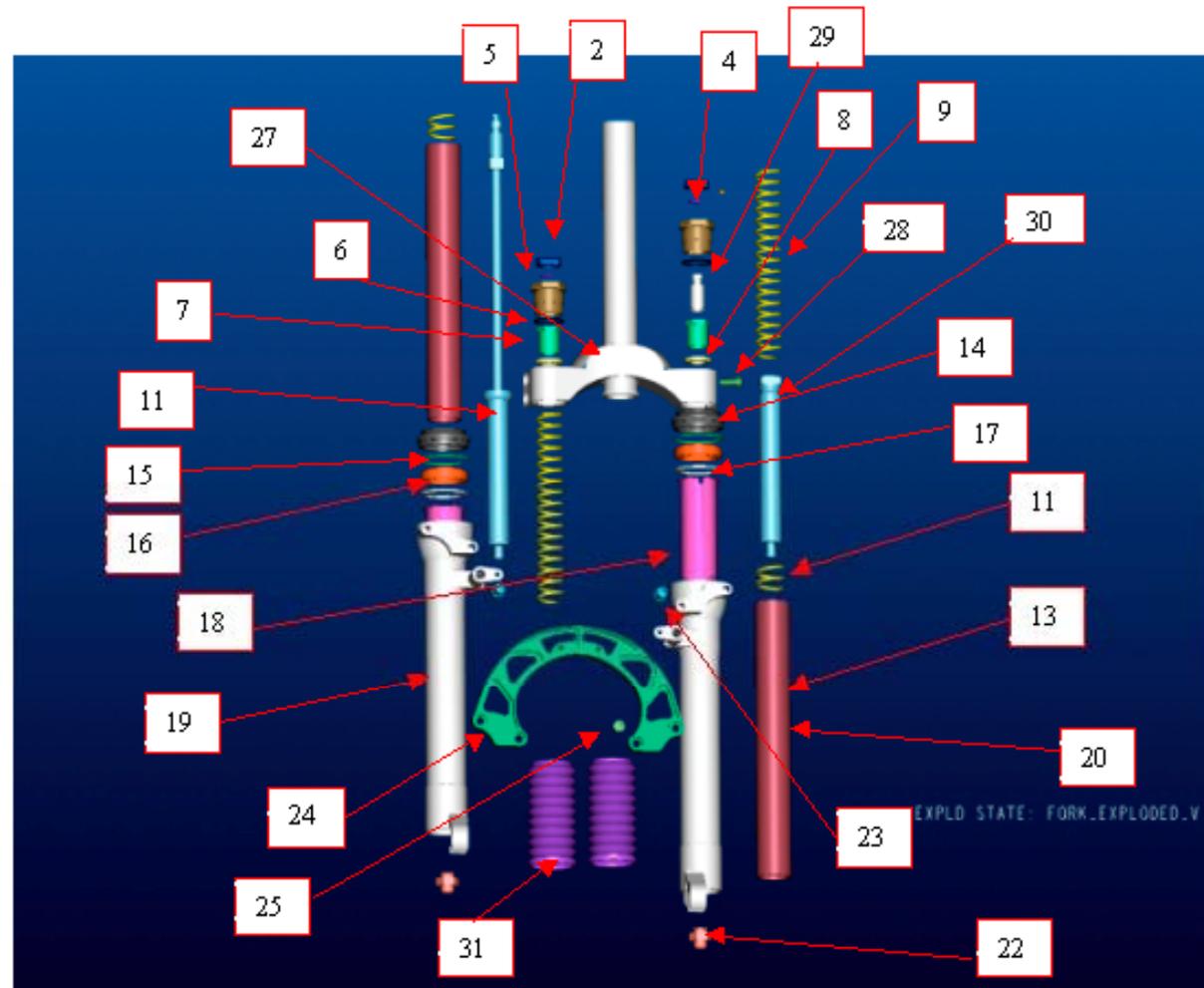




Modeling the Marzocchi Z.2 Atom Bomb Mountain Bike Shock

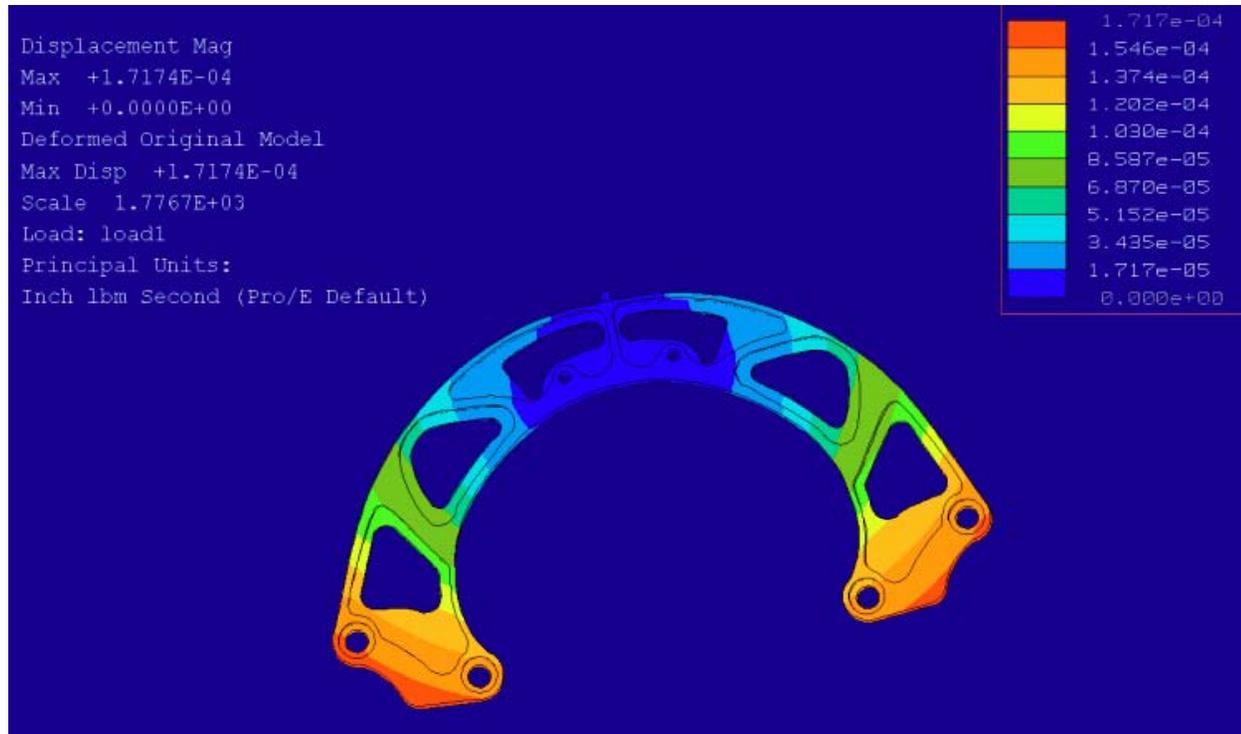
Aaron Lamb & Jon Baggett

- Assembly Modeling
- Stress Analysis on a Key Component



Modeling the Marzocchi Z.2 Atom Bomb Mountain Bike Shock

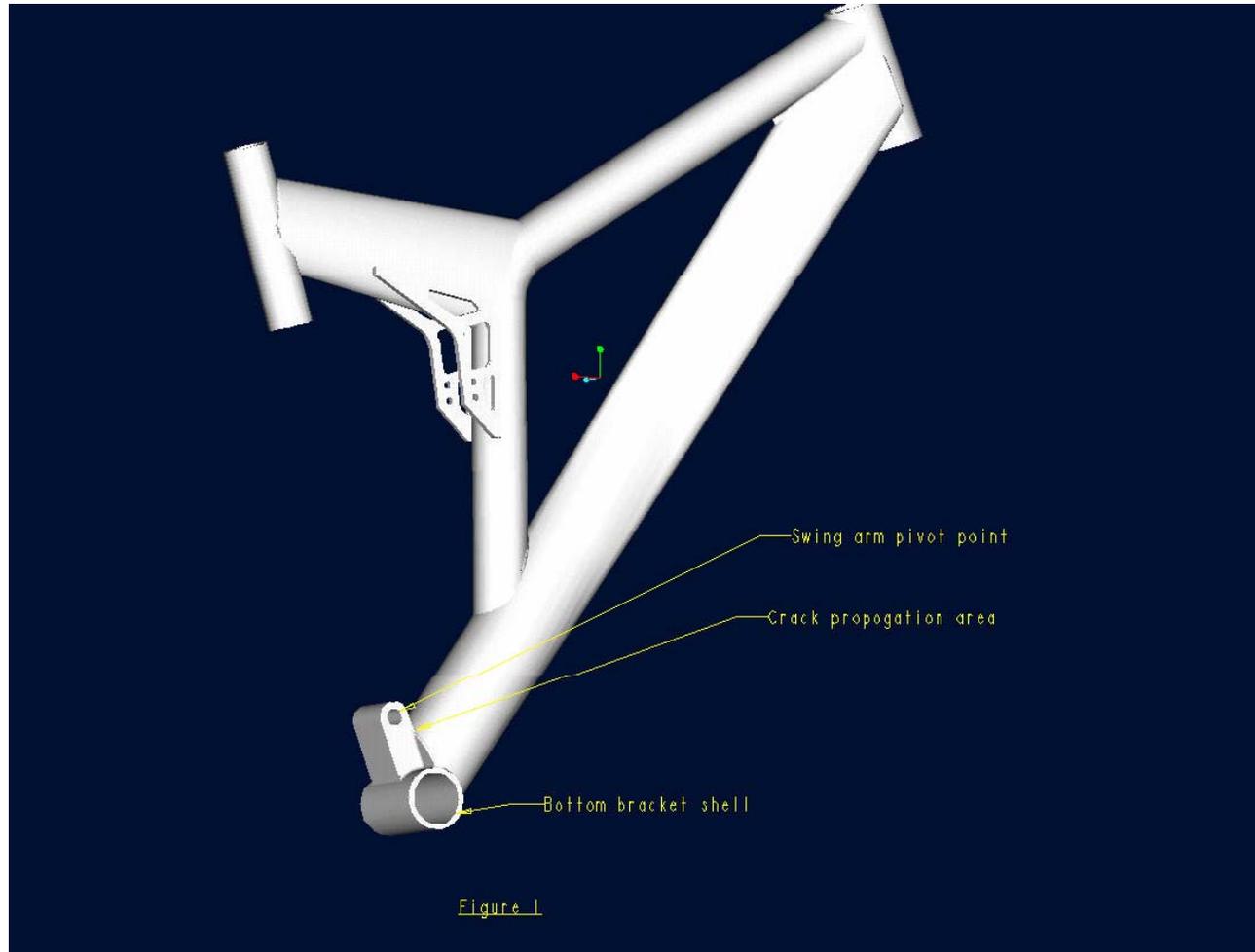
Aaron Lamb & Jon Baggett



Modeling and Analysis of Brodie Diablo Bike Frame

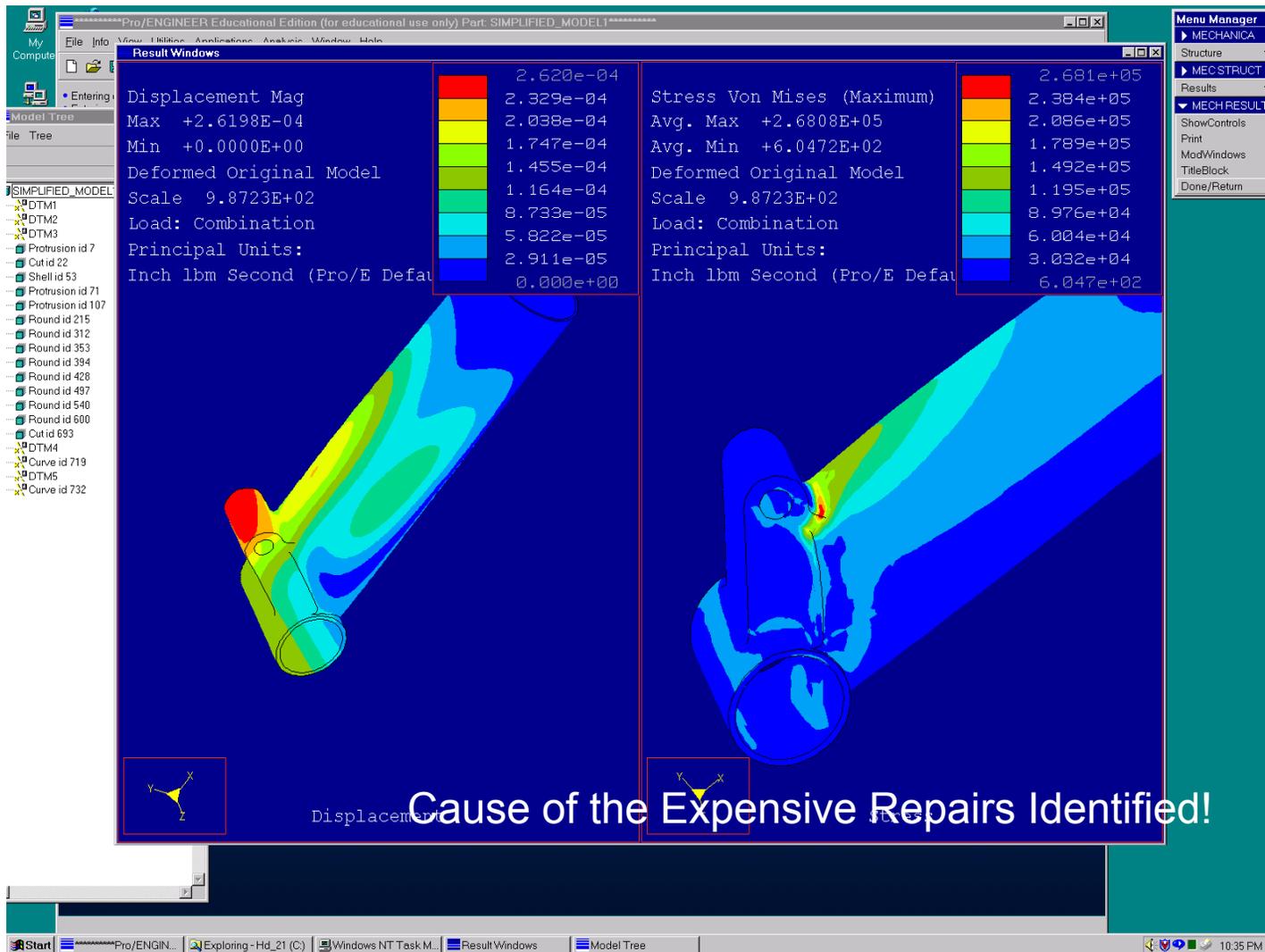
Walter Langer

- Frame Modeling
- Stress Analysis to Identify the Cause of the Failure



Modeling and Analysis of Brodie Diablo Bike Frame

Walter Langer



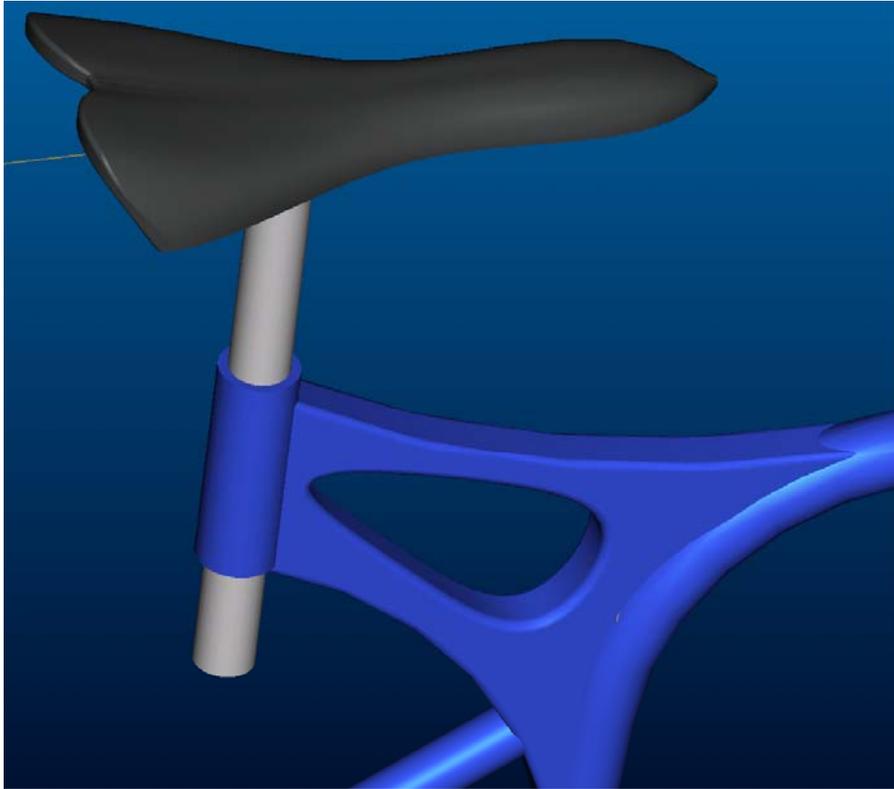
3D Mountain Bicycle Model

Lindsey Leu and Jenny Hoang



3D Mountain Bicycle Model

Lindsey Leu and Jenny Hoang



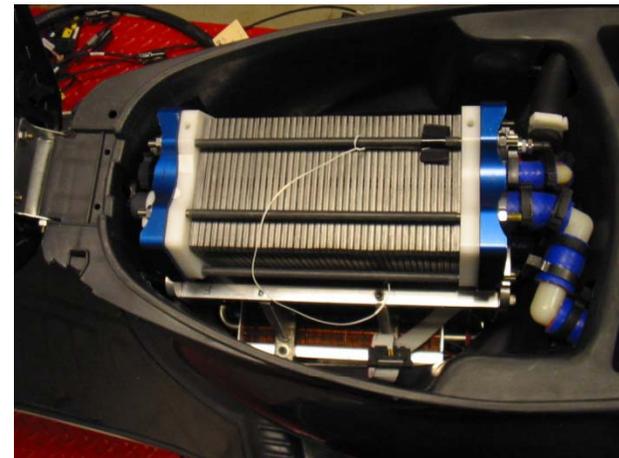
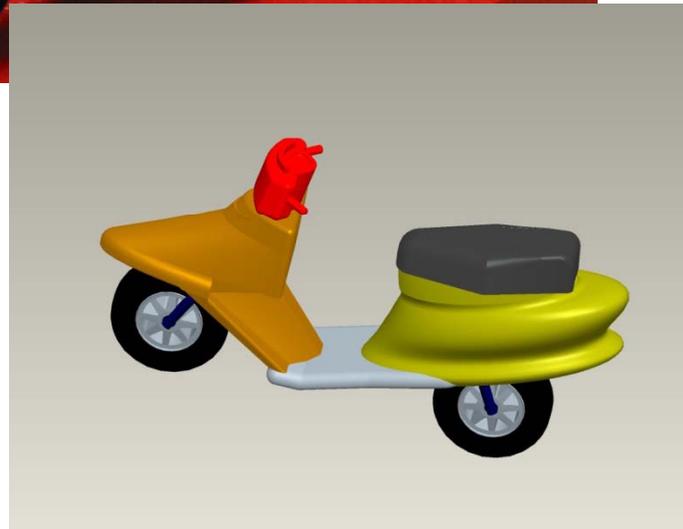
Fuel Cell E-Bicycle and Scooter Space Analysis

Onur Keskin

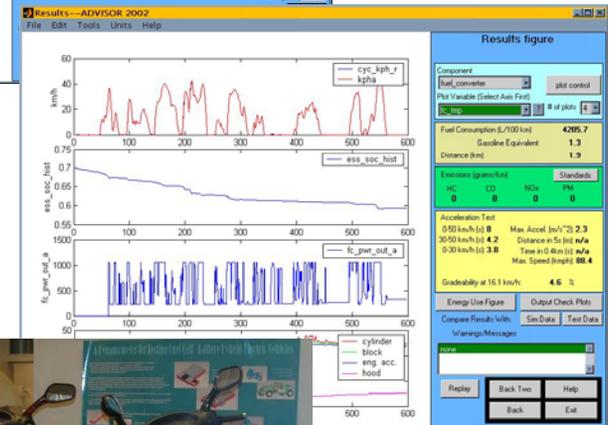
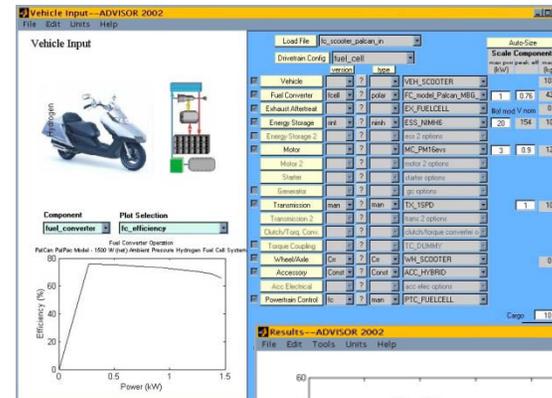
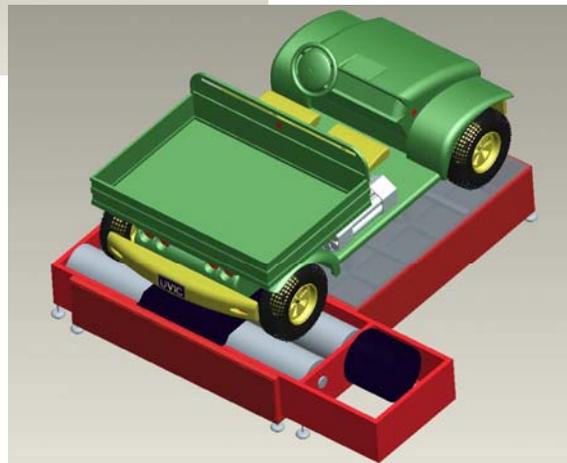
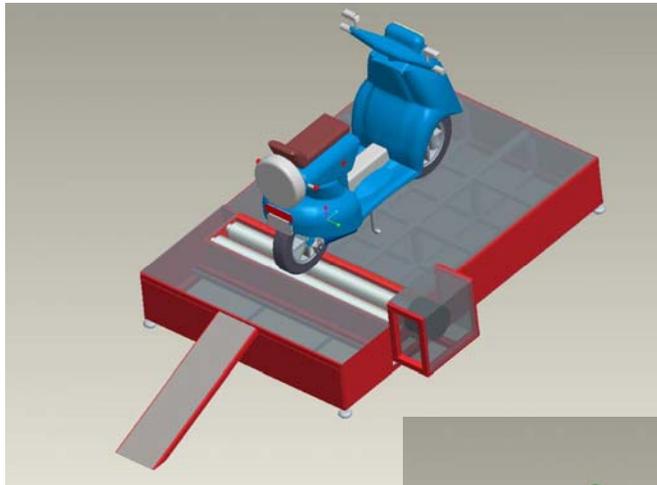


Fuel Cell E-Bicycle and Scooter Space Analysis

E. Lau & L. Horricks



Computer Modeling and Design of Fuel Cell Powered Low-Speed Electrical Vehicle Testing Stations



UVic Fuel Cell Bicycle Configuration

Richard V. Stackhouse



- This concept fuel cell powered bicycle shows the fuel cell system attached to a Rocky Mountain Bicycles RM6 full suspension bicycle.
- Due to the front motorized drive, the power system can be quickly and easily fitted to most bicycles, including full suspension.
- Two Wheel Drive Capability

Adaptable Electric Bicycle Power System



- Proof of power system configuration.
- Large mass better suited at back than front for adequate steering.

AEBPS Final Specs

Prototype Cost	~\$900 CDN (\$560 USD)
Electrical System	24 Volt EV Warrior System
Motor Controller	Curtis 1505 (20A Continuous, 80A (1 Minute Rating))
Battery Pack	Currie Cycles 24V Sealed Lead Acid 12Ah
Motor Power Output	400 Watts (Max.) 200 Watts (Continuous)
Maximum Motor Torque	37 Nm
Maximum Bicycle Speed	18.5 km/h (Mounted on RM6 with 167 lbm rider)
Throttle	Fully Variable Speed (Thumb Operated)
Total AEBPS Mass	14.9 kg (32.9 lbm)
Hub Motor Mass	3.6 kg (8 lbm)
Battery Pack Mass	9.8 kg (21.5 lbm)
Electrical System Mass	0.9 kg (2 lbm)
Topeak Beam Rack Mass	0.6 kg (1.4 lbm)





Formula SAE Competition Car Related



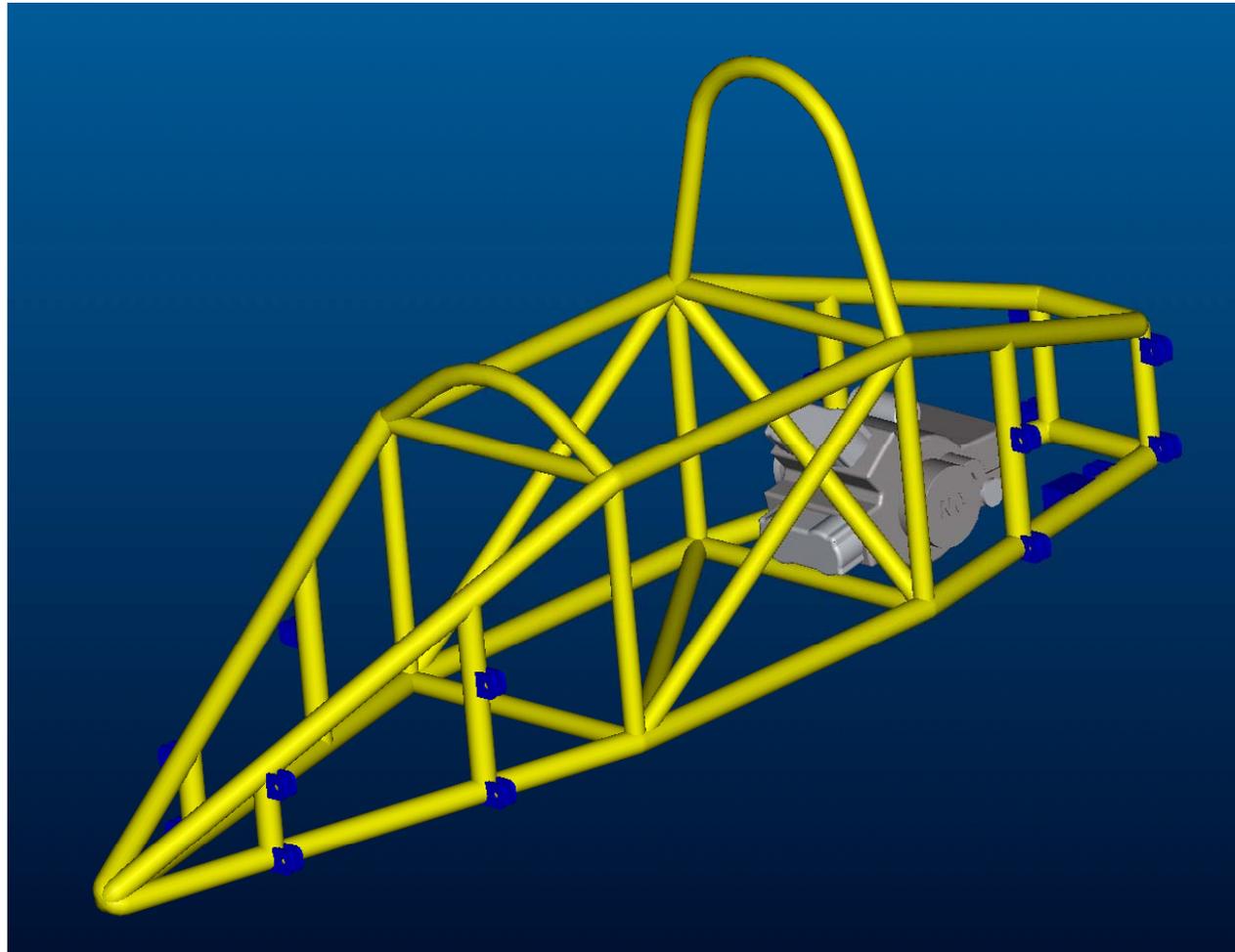
Figure 1: Team UVic race car

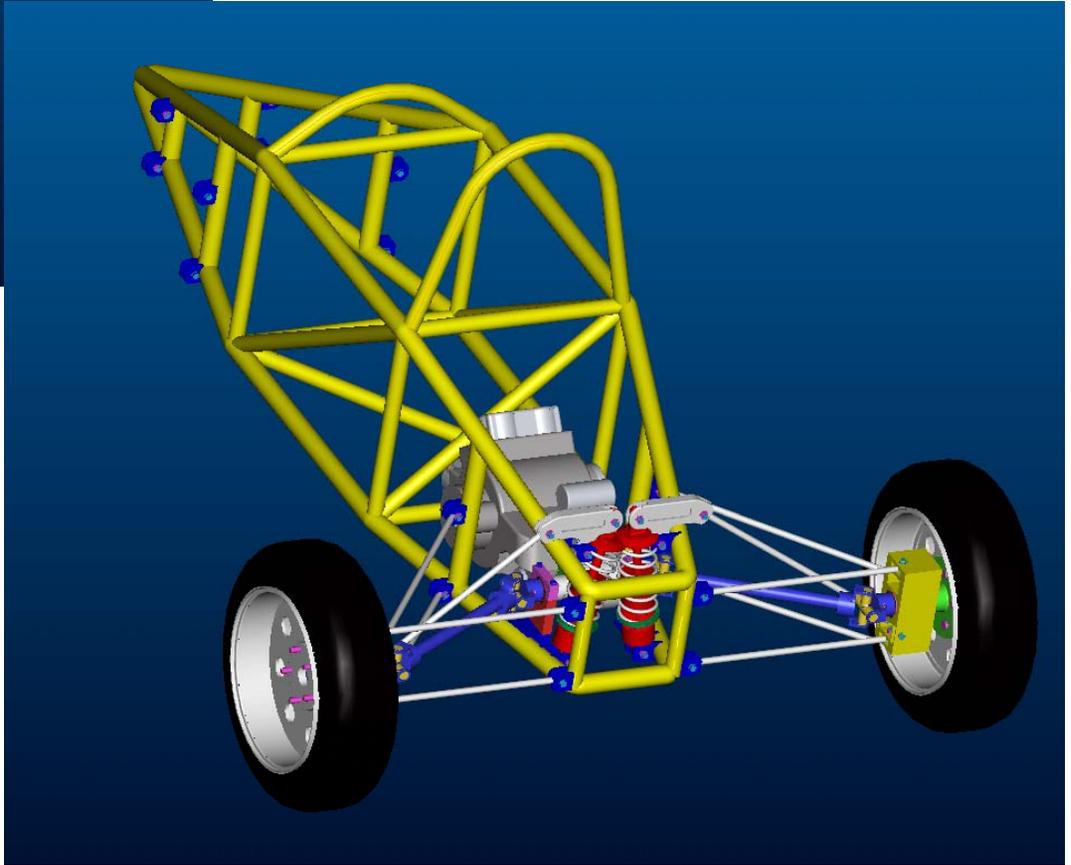
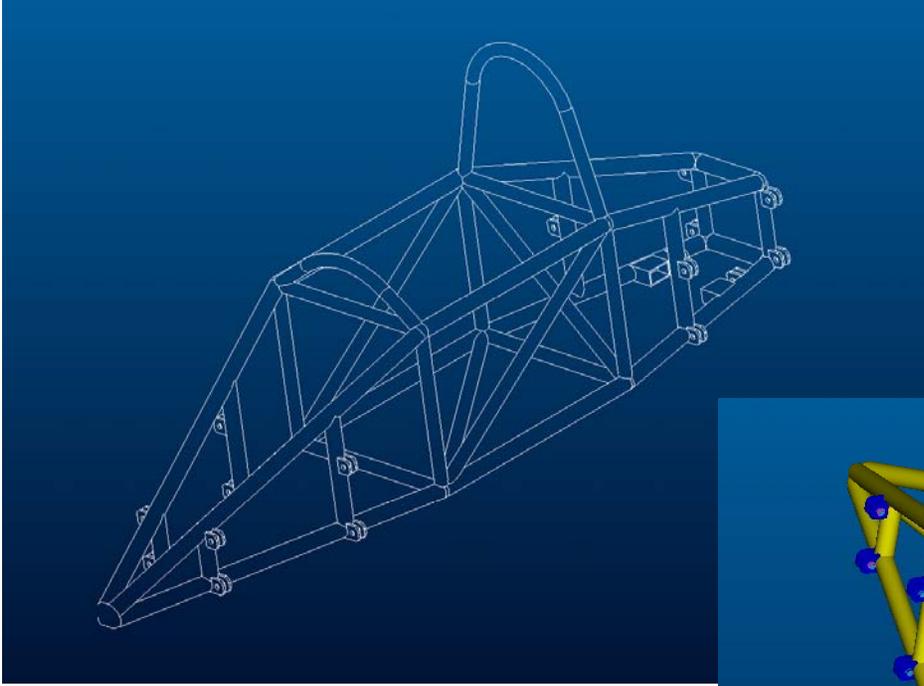


Figure 5: Current 3D model

SAE Formula Racecar Chassis and Modeling in Pro/ENGINEER

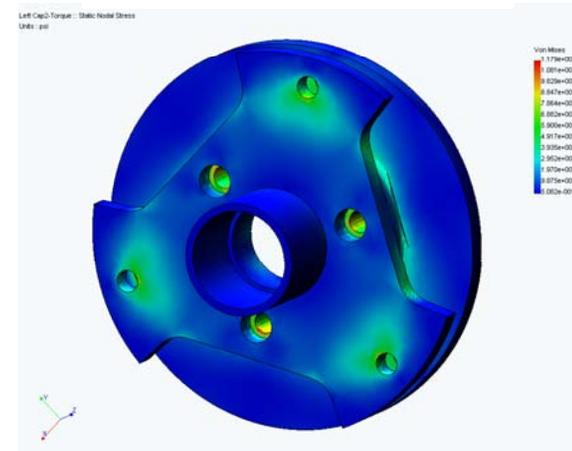
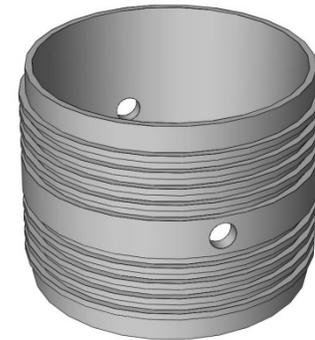
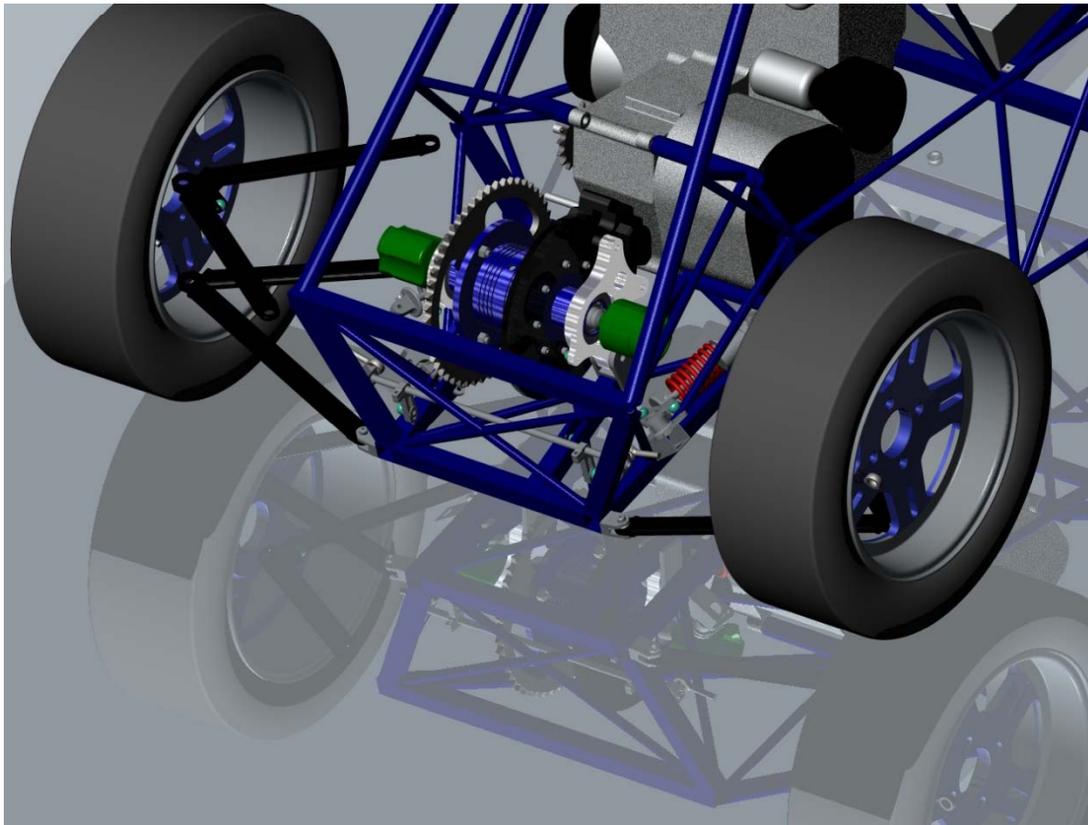
Jarvis Degroot & Greg Montie



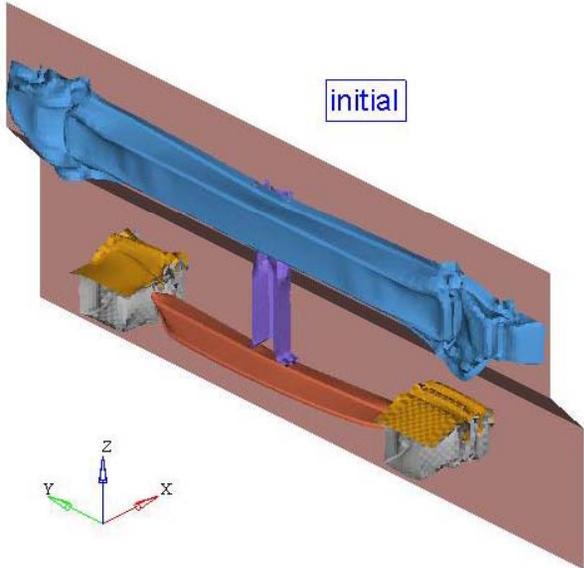
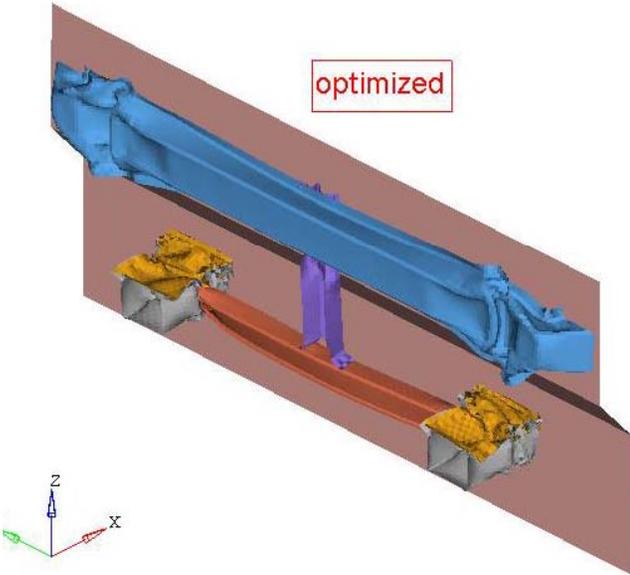
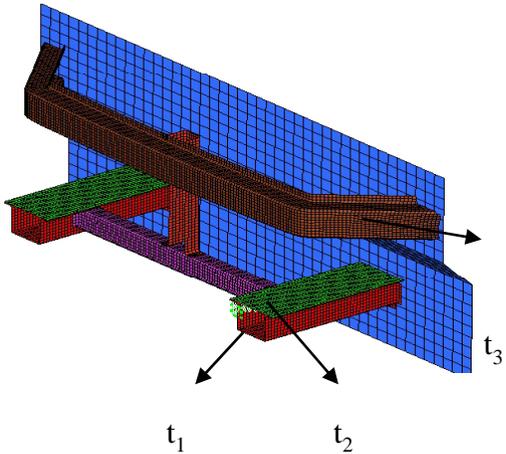


Formula UVic Drivetrain Design

Richard Lewis and Justin Alexander



Vehicle Bumper Crash FEA Simulation and Design Optimization to Control Peak Deceleration and Increase Energy Absorption (J. Gu)

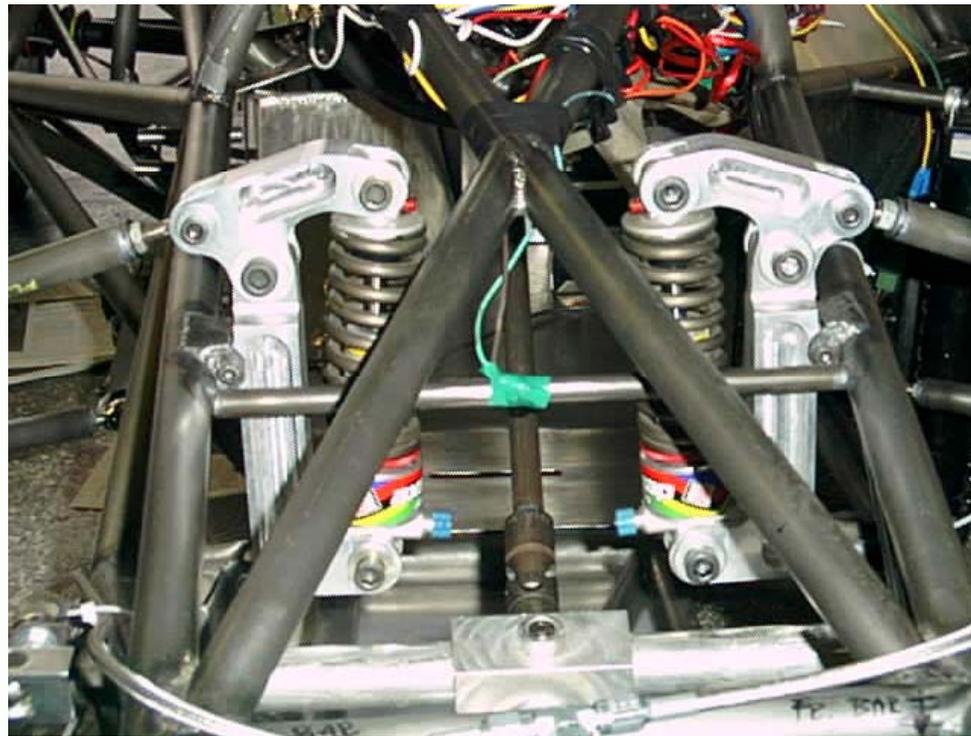
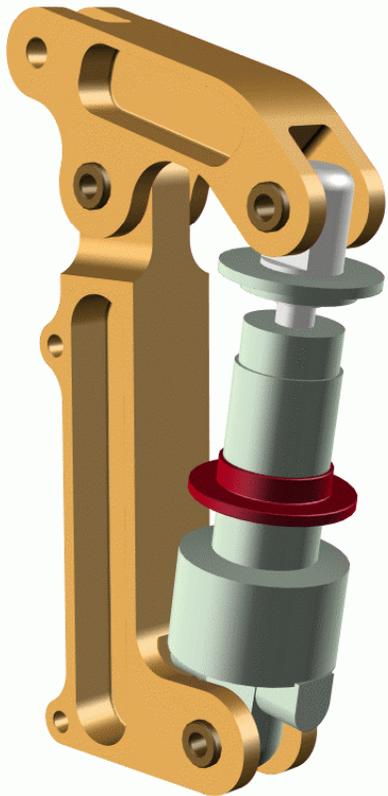


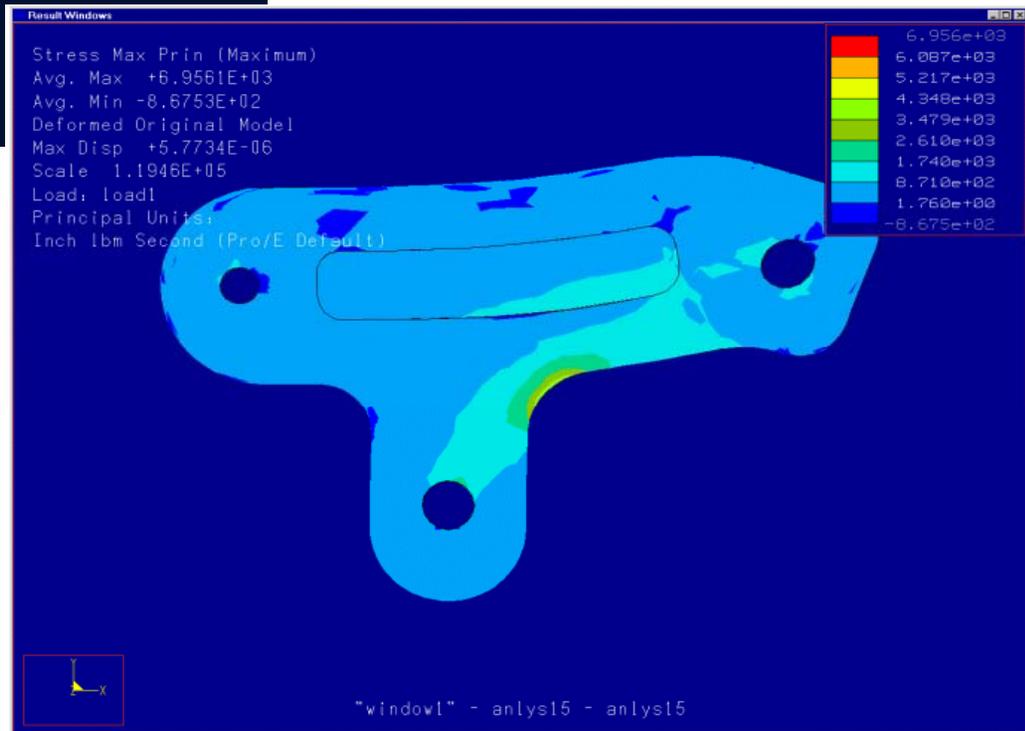
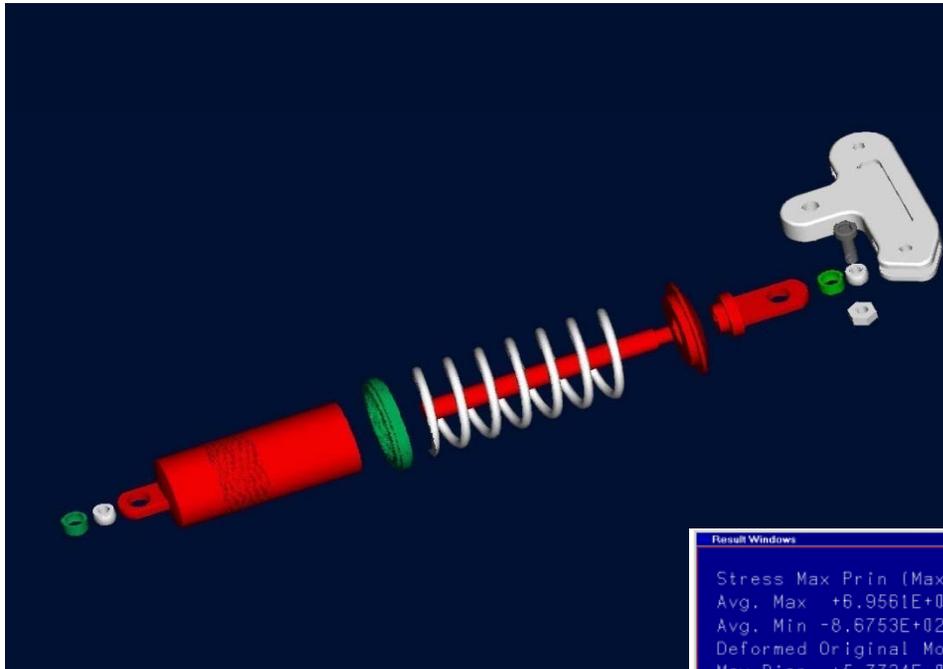
Modeling the Suspension of a Formula SAE Car



Eldon Cottingham, Carl
Thomas and James Cox

Modeling the Suspension of a Formula SAE Car

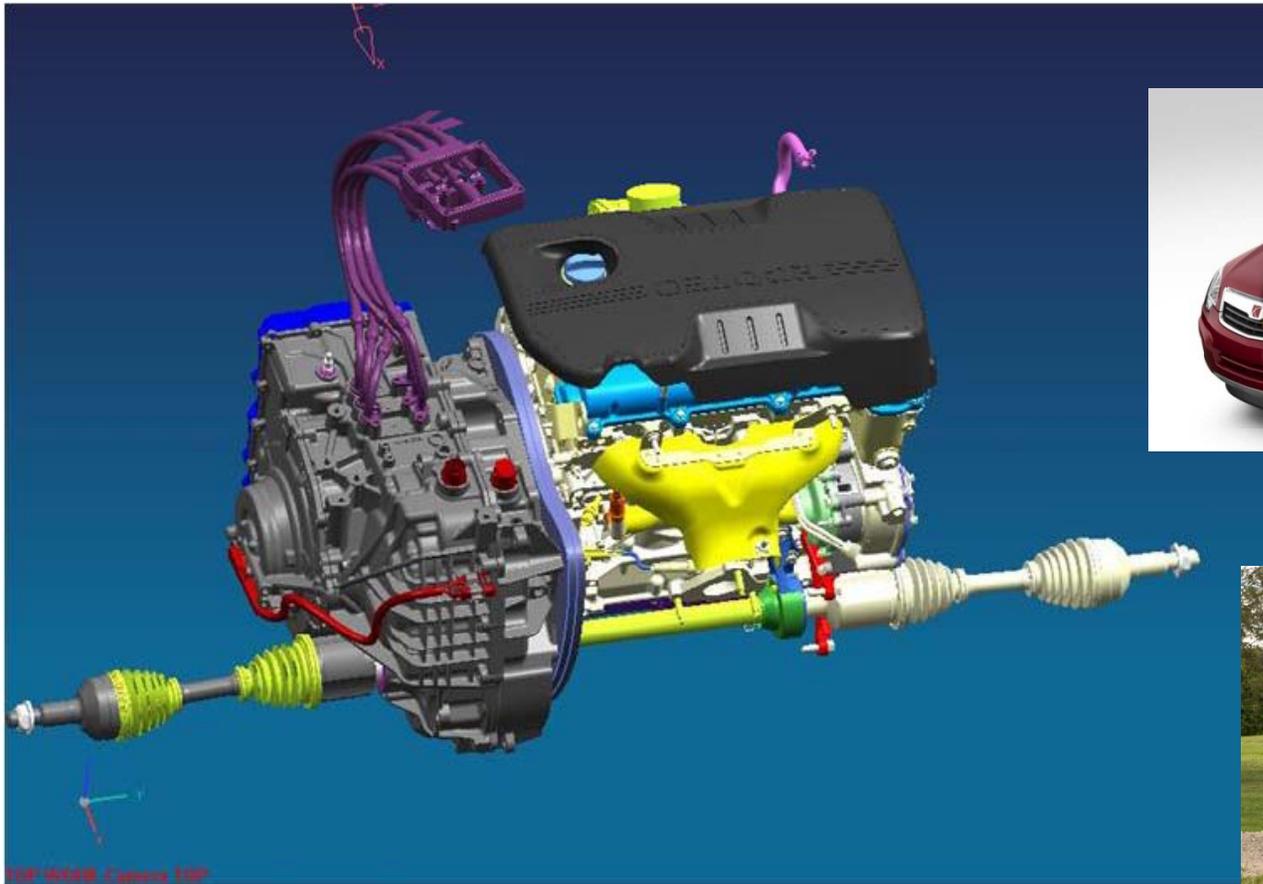


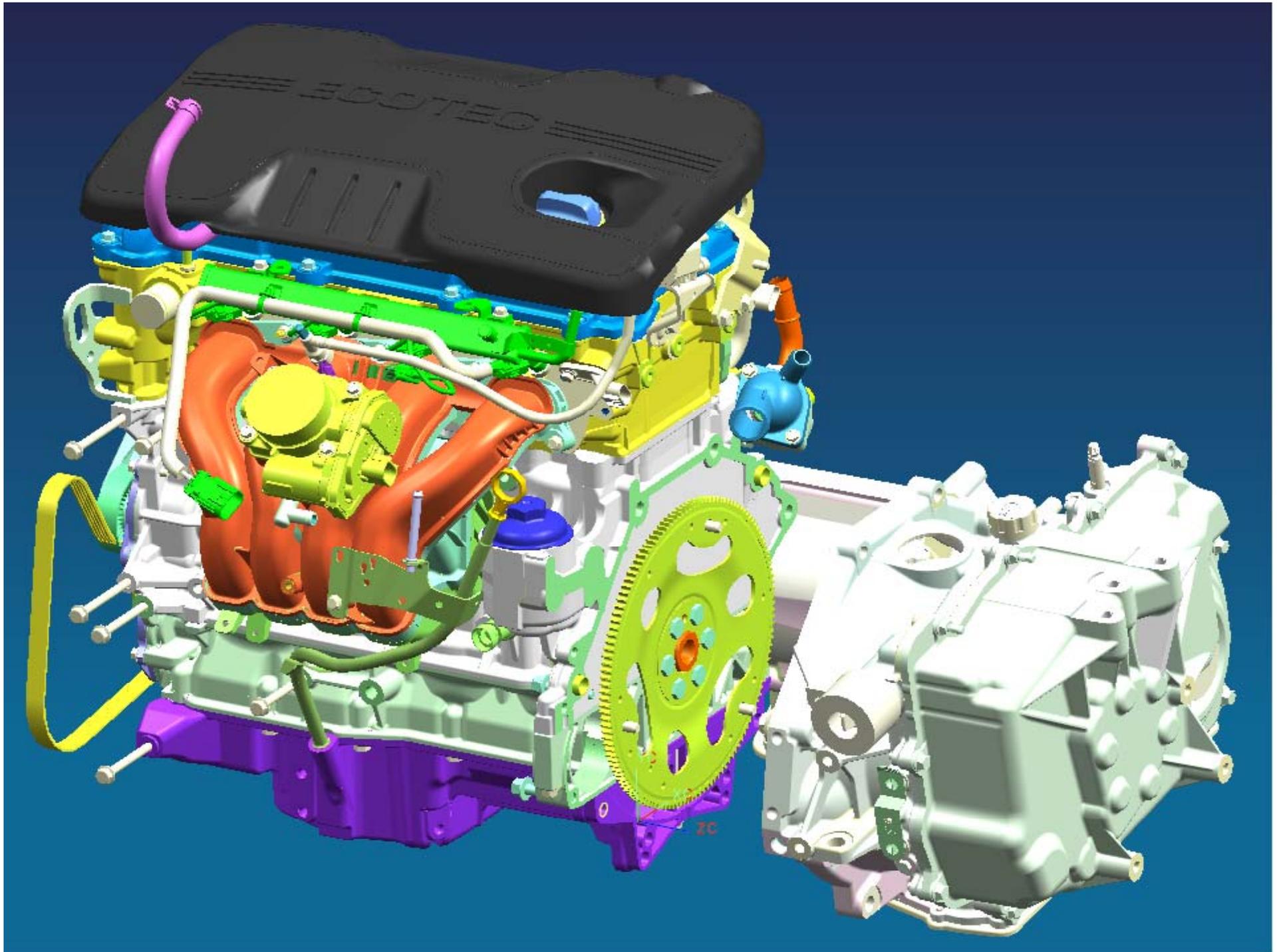


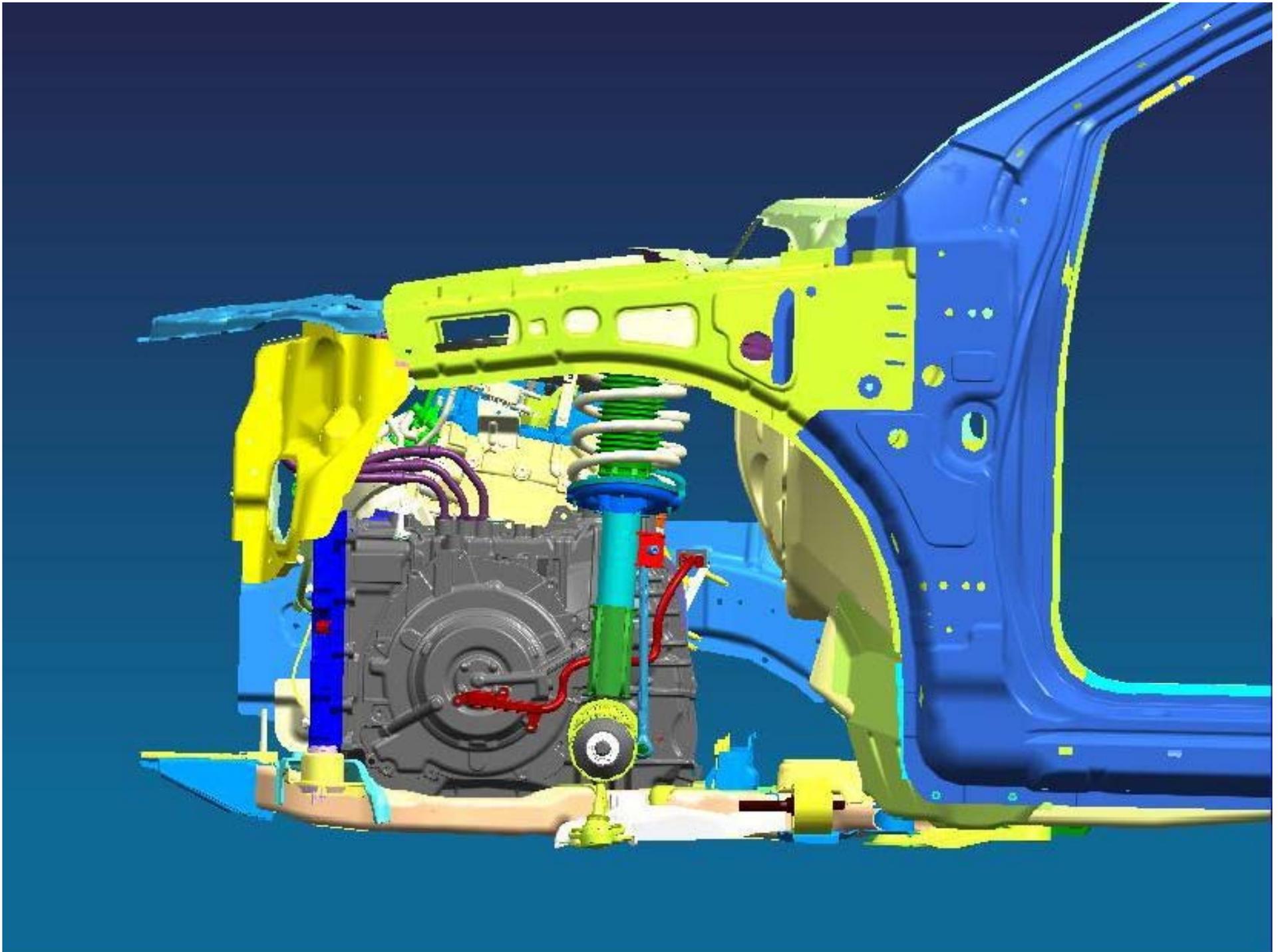
EcoCAR HEV Design and Analysis Using Unigraphics NX

Integrating the GM 2-Mode Transmission into the EcoCAR

Design Team: David Robinson, Degnan Hembroff and Michael Versteeg



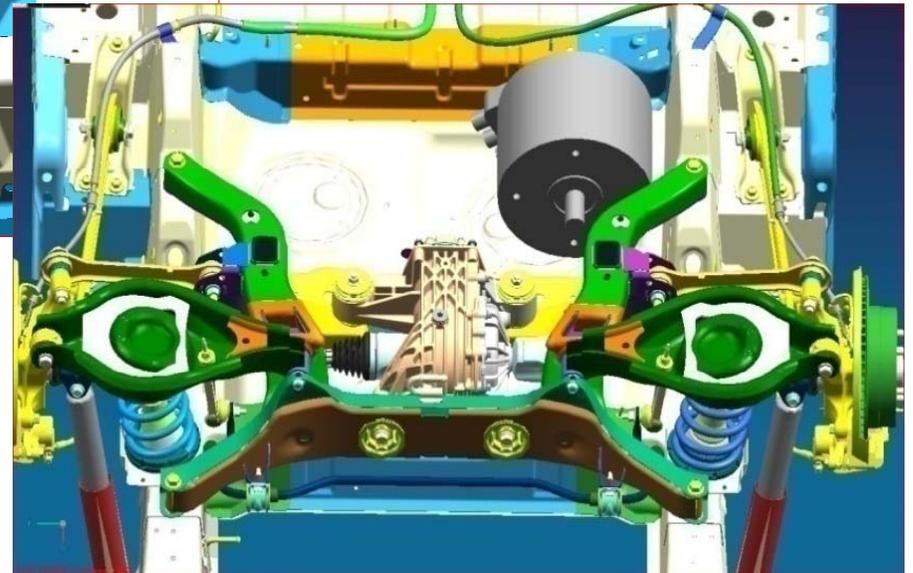
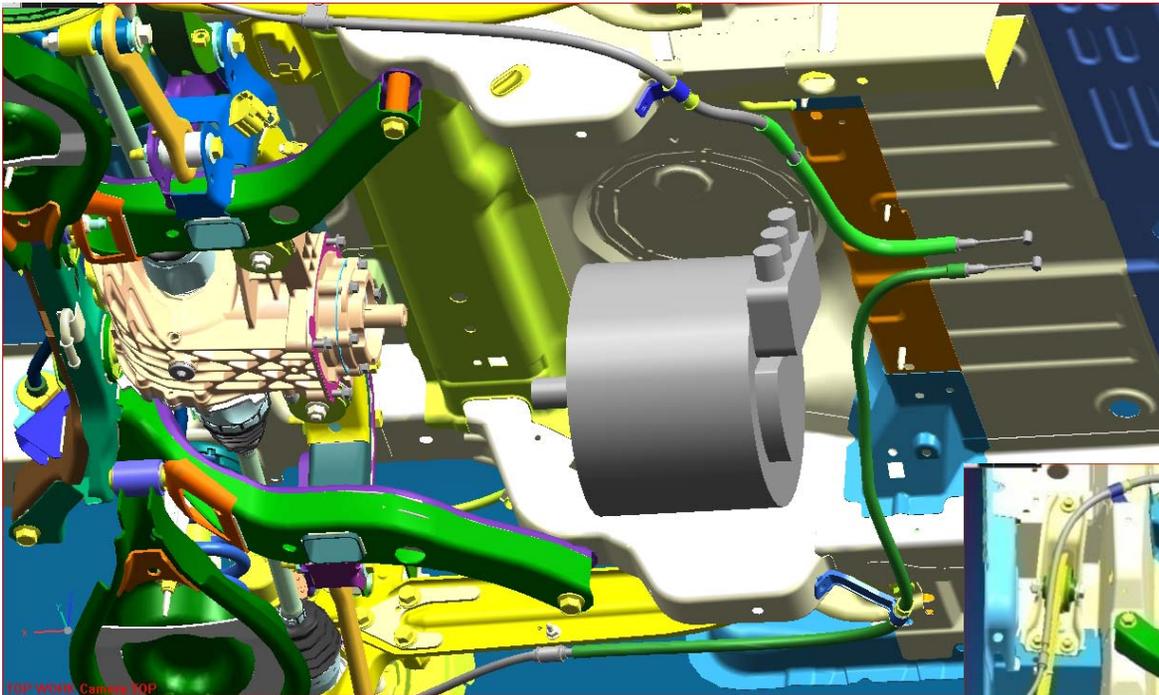




EcoCAR HEV Design and Analysis

Electric Rear Wheel Drive Gearbox

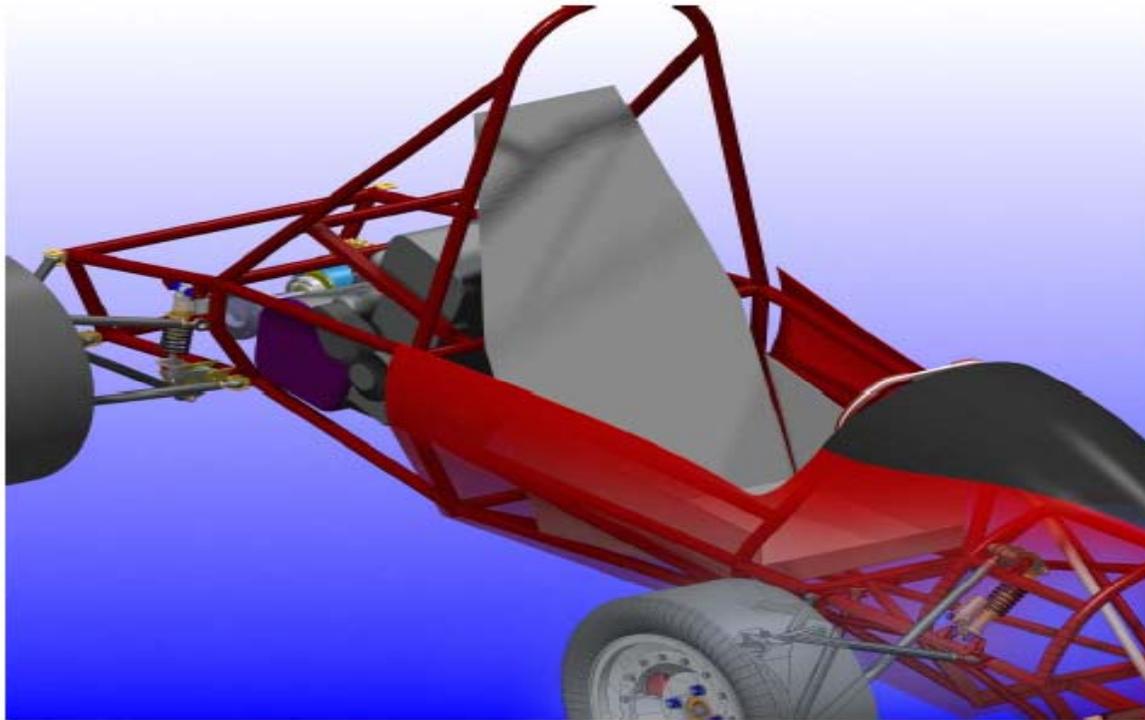
Adam Binley, Jake Soepber, Kyle McWilliam, Bryce Donnelly, Yoshua Ichihashi & Sean Walsh



UVic SAE Team



Engine Intake Design for the Uvic Formula SAE Race Car



Mech 410

Prepared by:
Aaron Sandstorm
Armando Tura

SAE Race Car Modeling and Analysis Using SolidWorks, FloWorks and Pro/E

This project was an opportunity to model and analyze the intake system for the Formula SAE race car, and to get familiar with the FloWorks. The analysis confirmed that, on first approximation, the design selected, even if not optimal, should be able to feed the engine in a satisfactory fashion. High performance output is expected from the fuel injected system planned for the next year car.

SolidWorks in conjunction with FloWorks, demonstrated to achieve results intuitively and quickly. A real test of the system will give a response on the reliability of the predictions. SolidWorks models proved to be easily exported into IGES and imported into Pro/E, expanding the possibility of this package.

Modification
of Intake
Design with
Added
Venturi
Restrictor

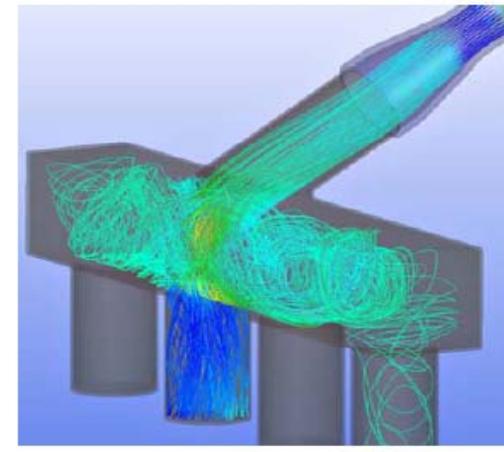
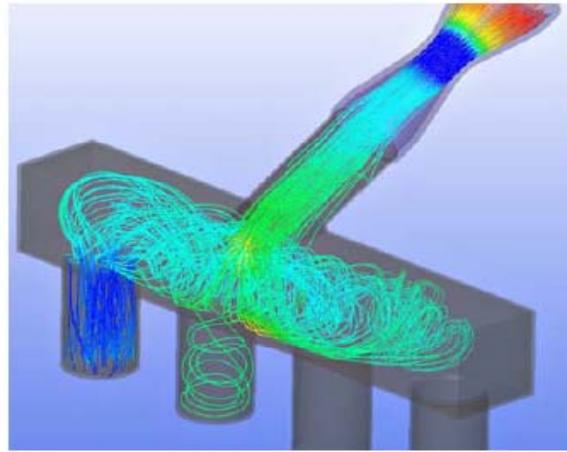


Figure 14: intake current configuration

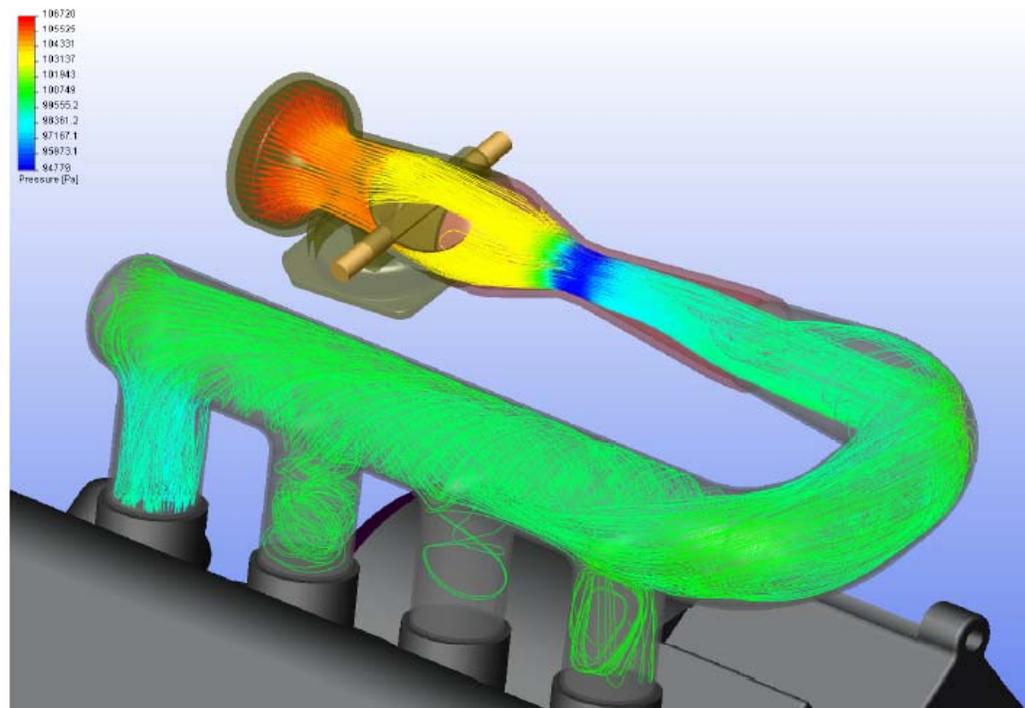
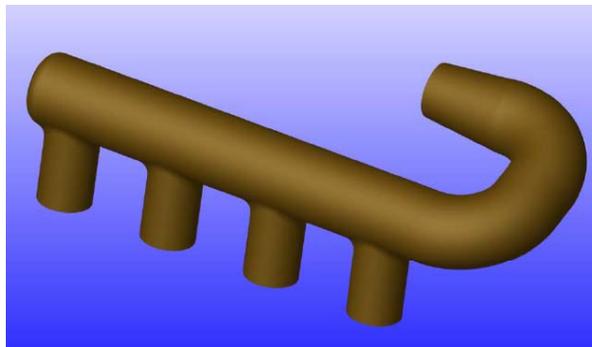
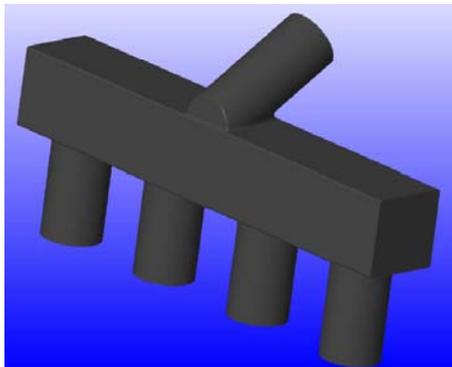
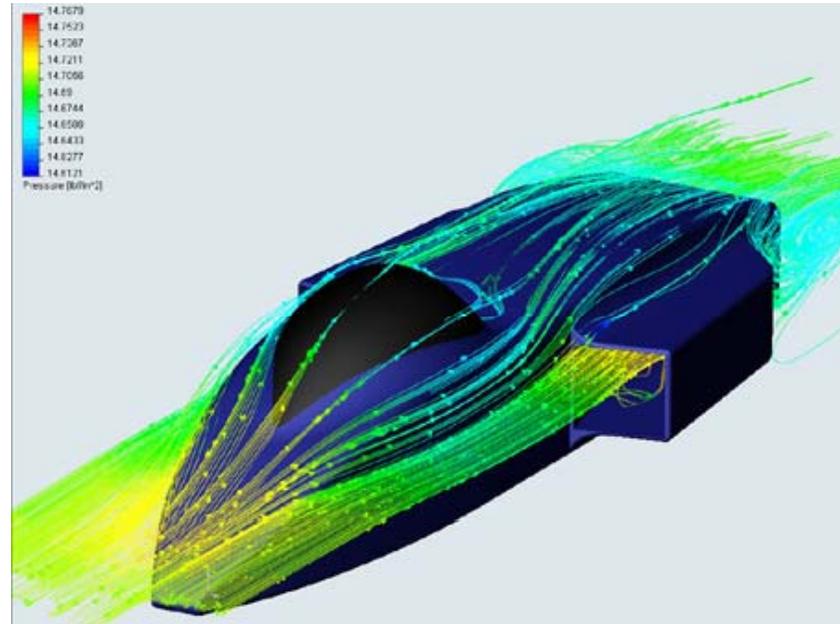


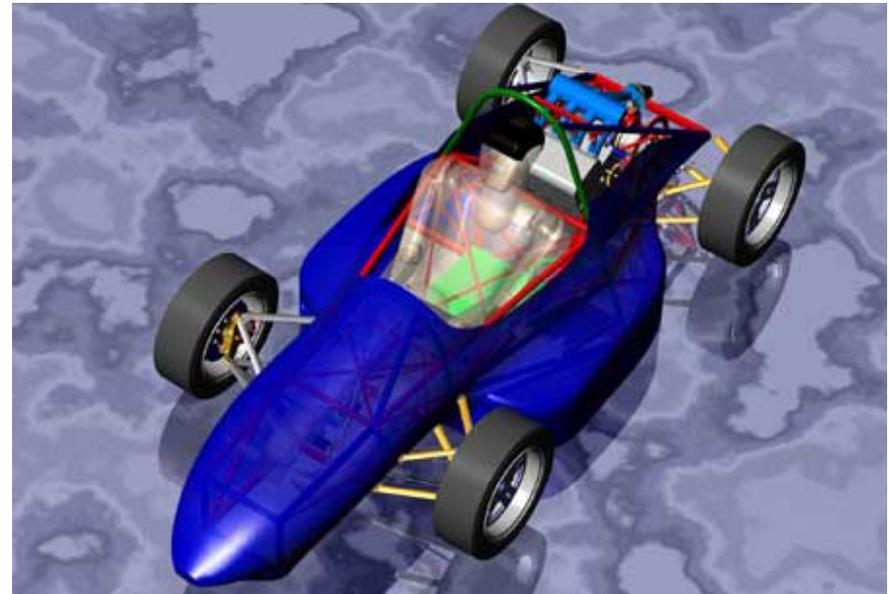
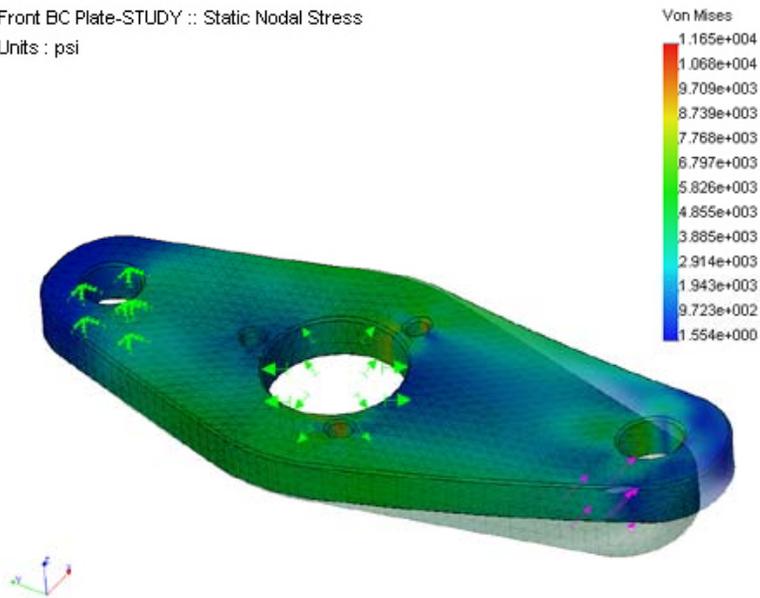
Figure 16: alternative manifold



Figure 17: Pro/Engineer model



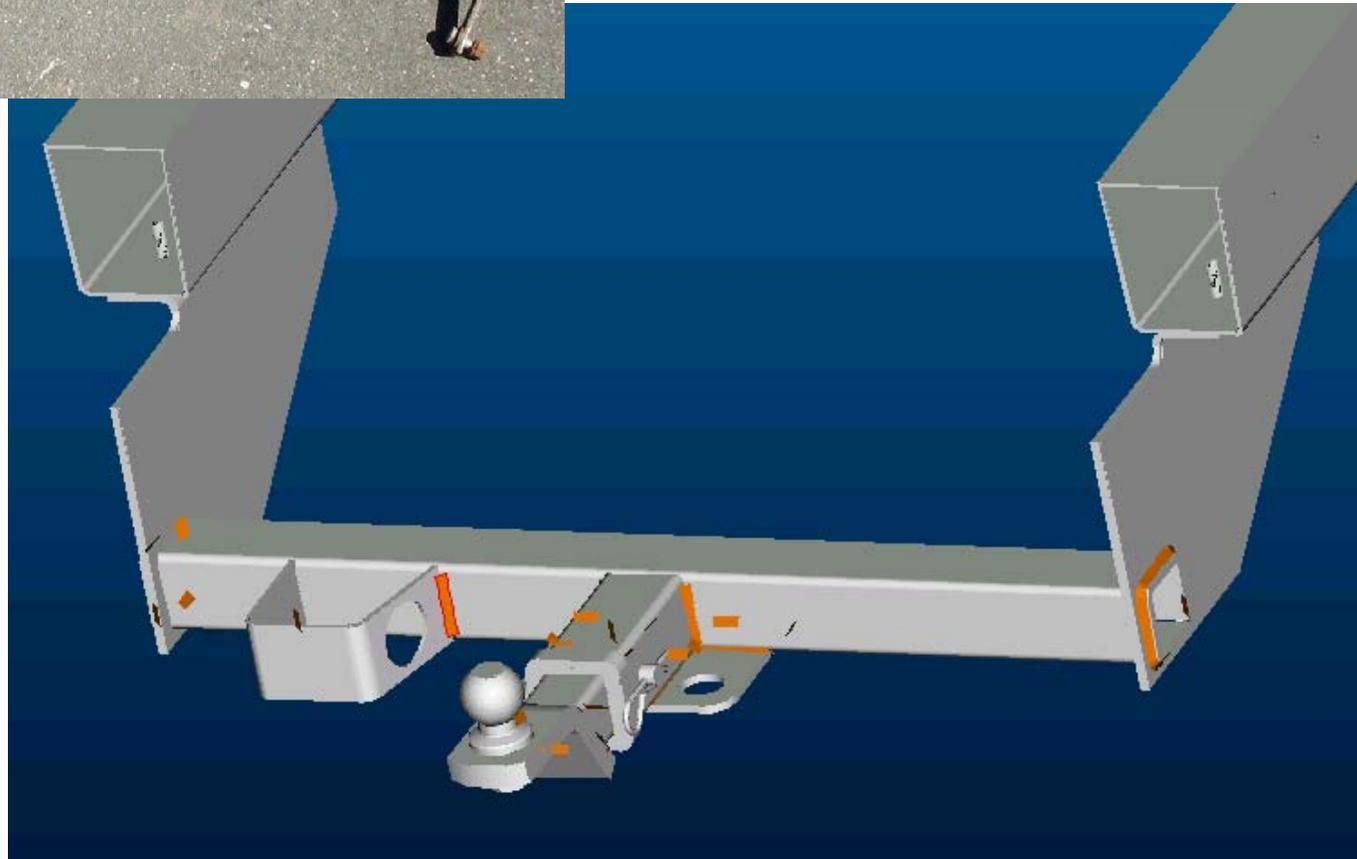
Front BC Plate-STUDY :: Static Nodal Stress
Units : psi





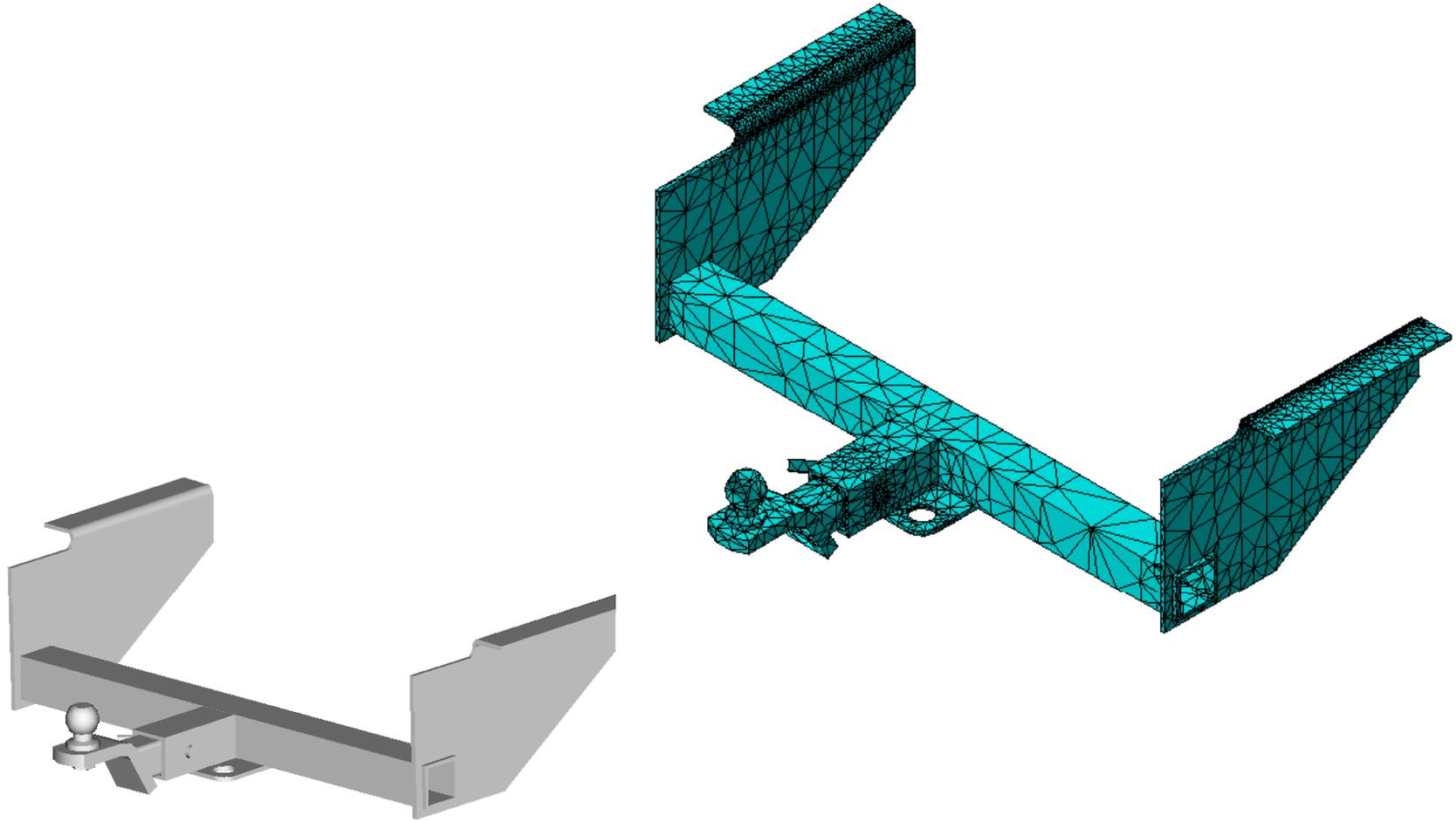
Modelling and Structural Analysis of a Frame Hitch Using Pro/ENGINEER, Pro/MESH and **ANSYS**

Daryl Brodie and Curran Crawford

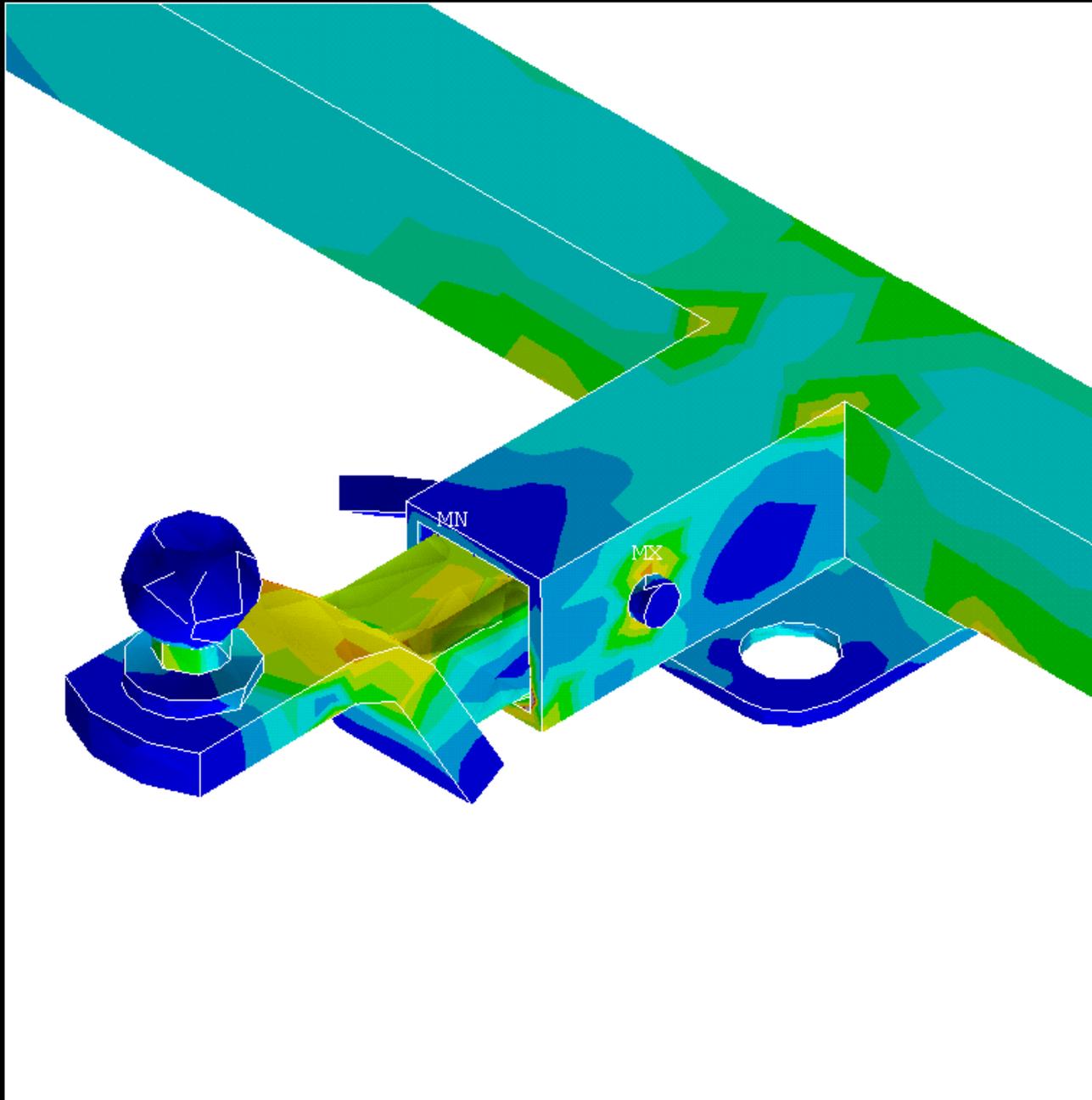
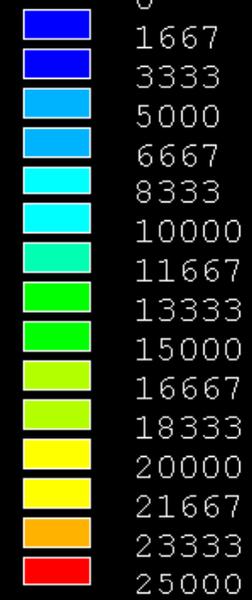


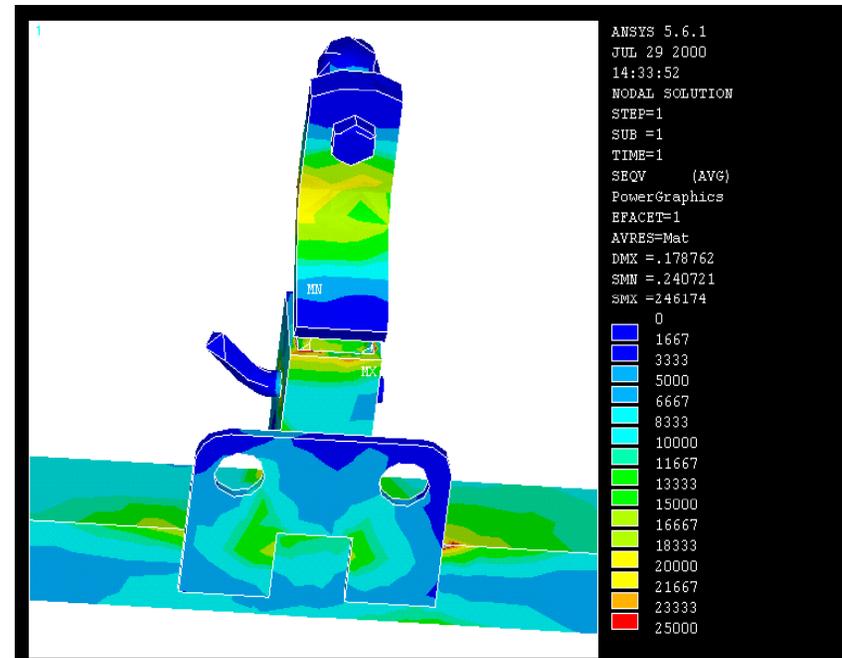
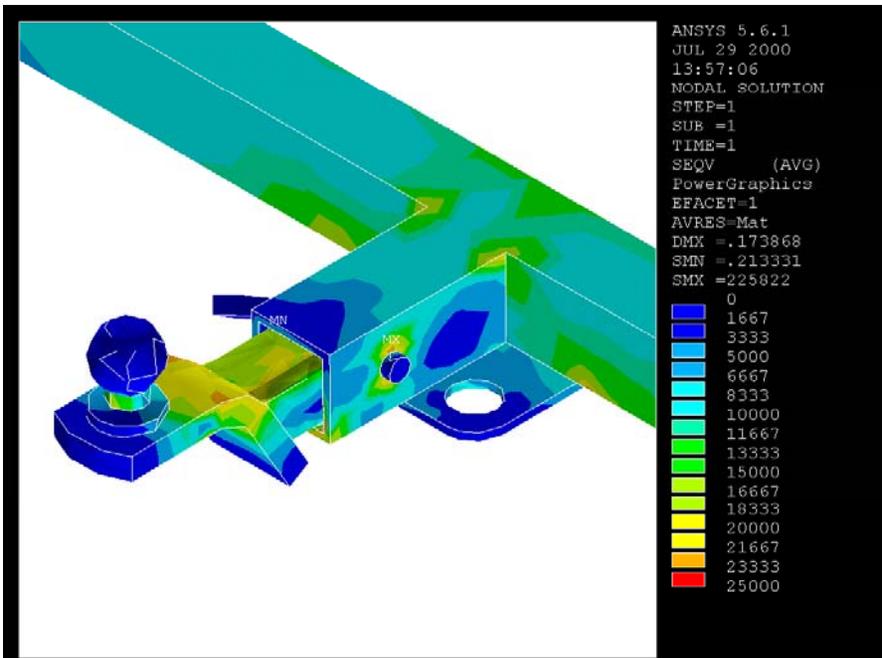
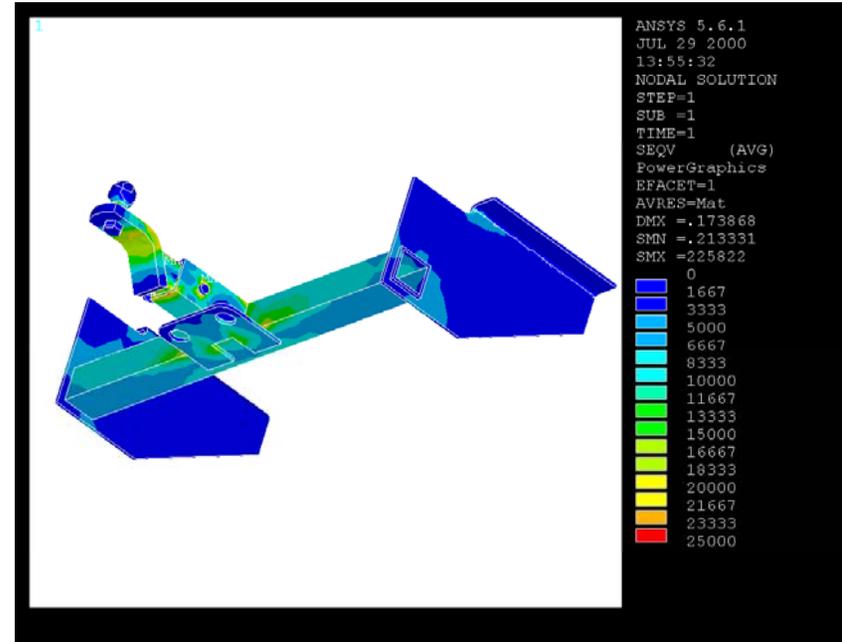
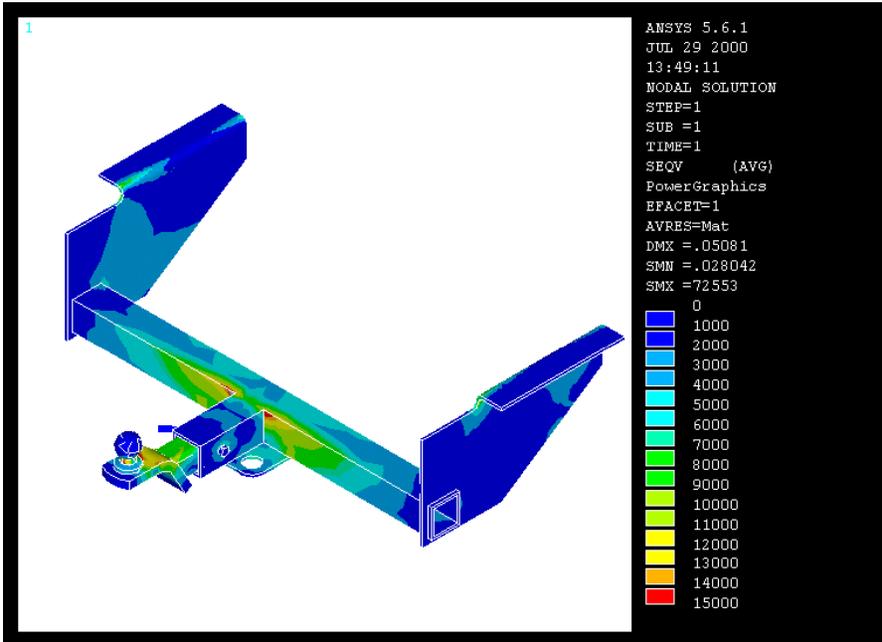
Modelling and Structural Analysis of a Frame Hitch Using Pro/ENGINEER, Pro/MESH and ANSYS

Daryl Brodie and Curran Crawford



ANSYS 5.6.1
JUL 29 2000
13:57:06
NODAL SOLUTION
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SUB =1
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AVRES=Mat
DMX =.173868
SMN =.213331
SMX =225822

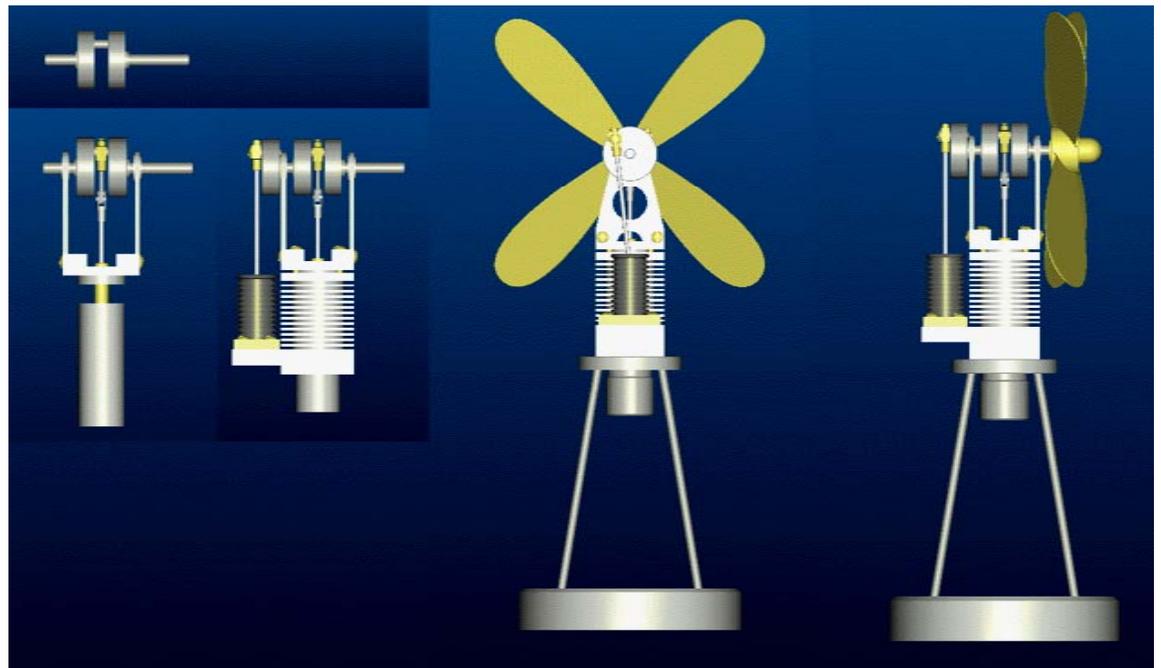
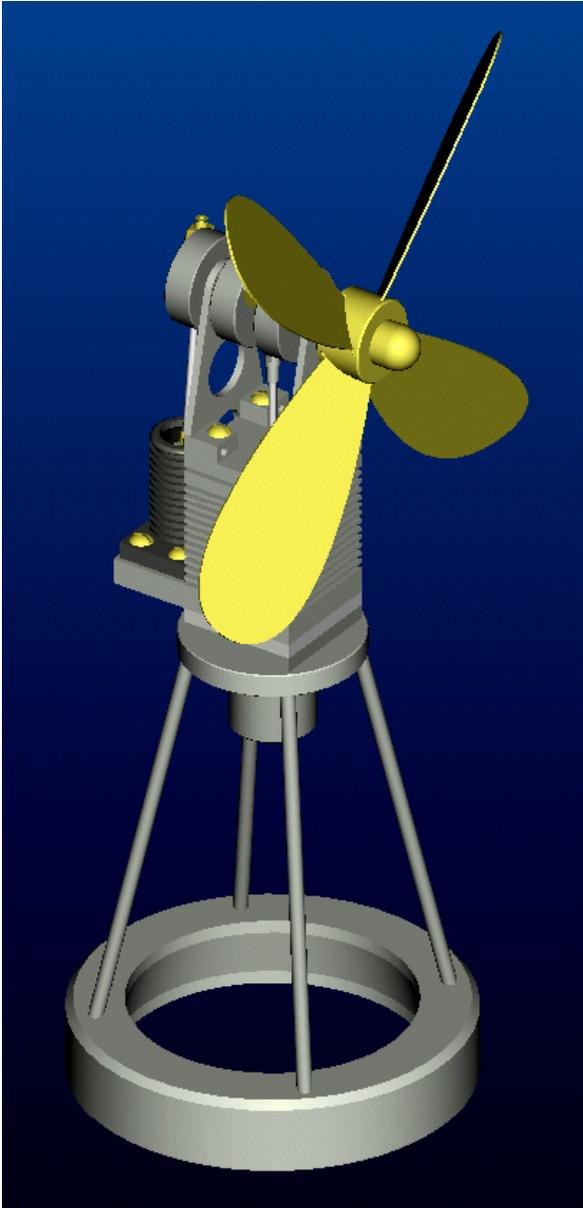




Mini-Stirling Engine Fan

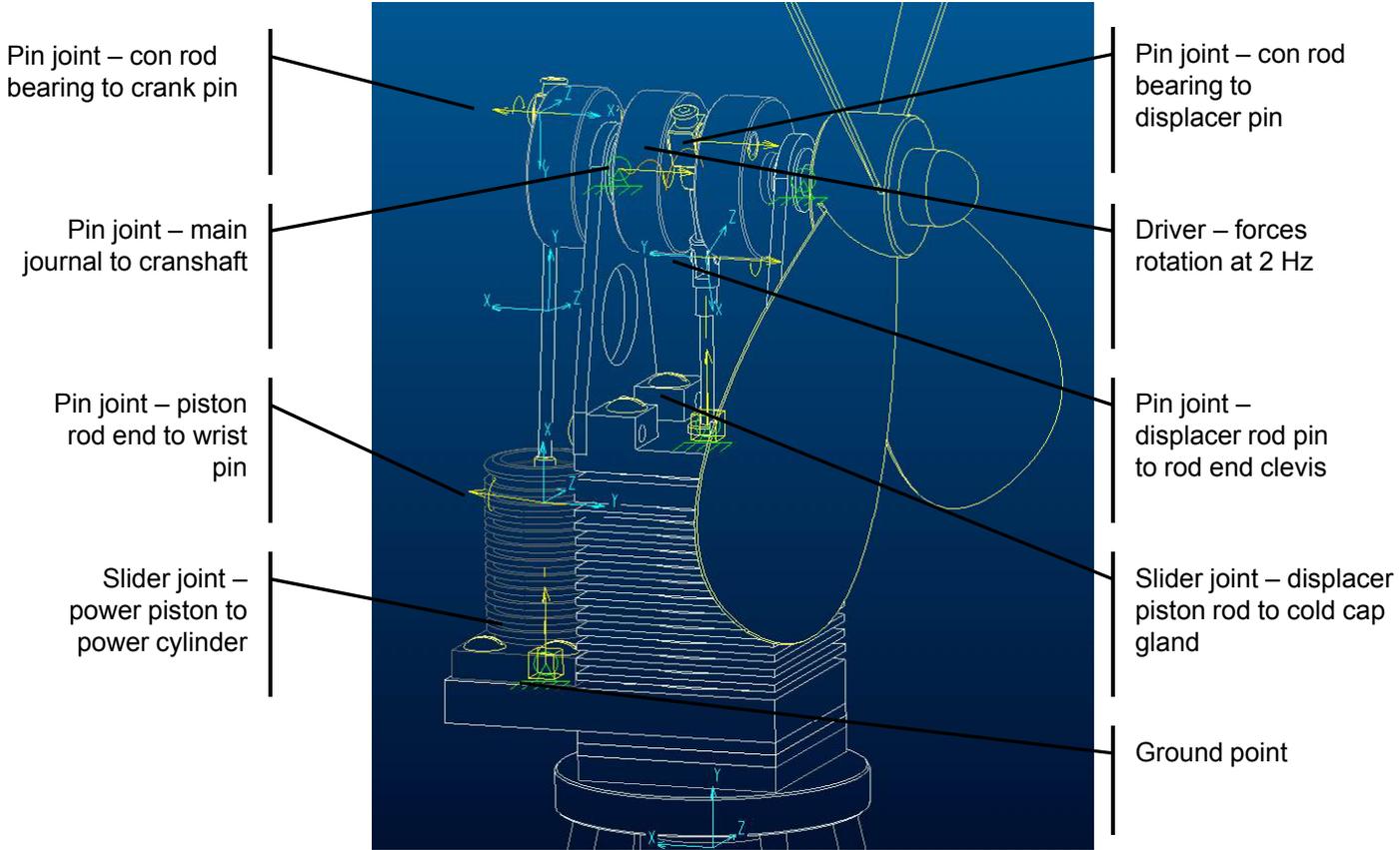
Dean Lowe

- Design Modeling
- Production Drawings
- Motion Animation



Mini-Stirling Engine Fan

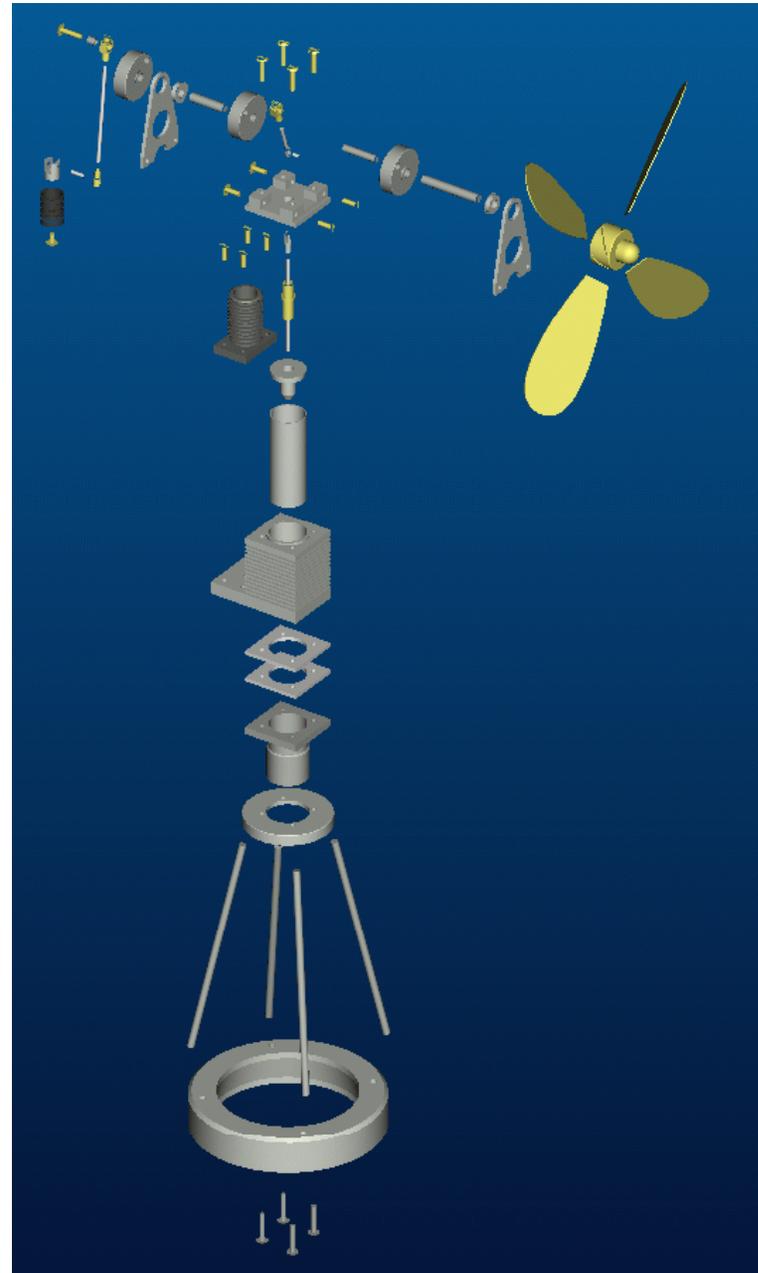
Dean Lowe



Joints and drivers on the Stirling engine fan

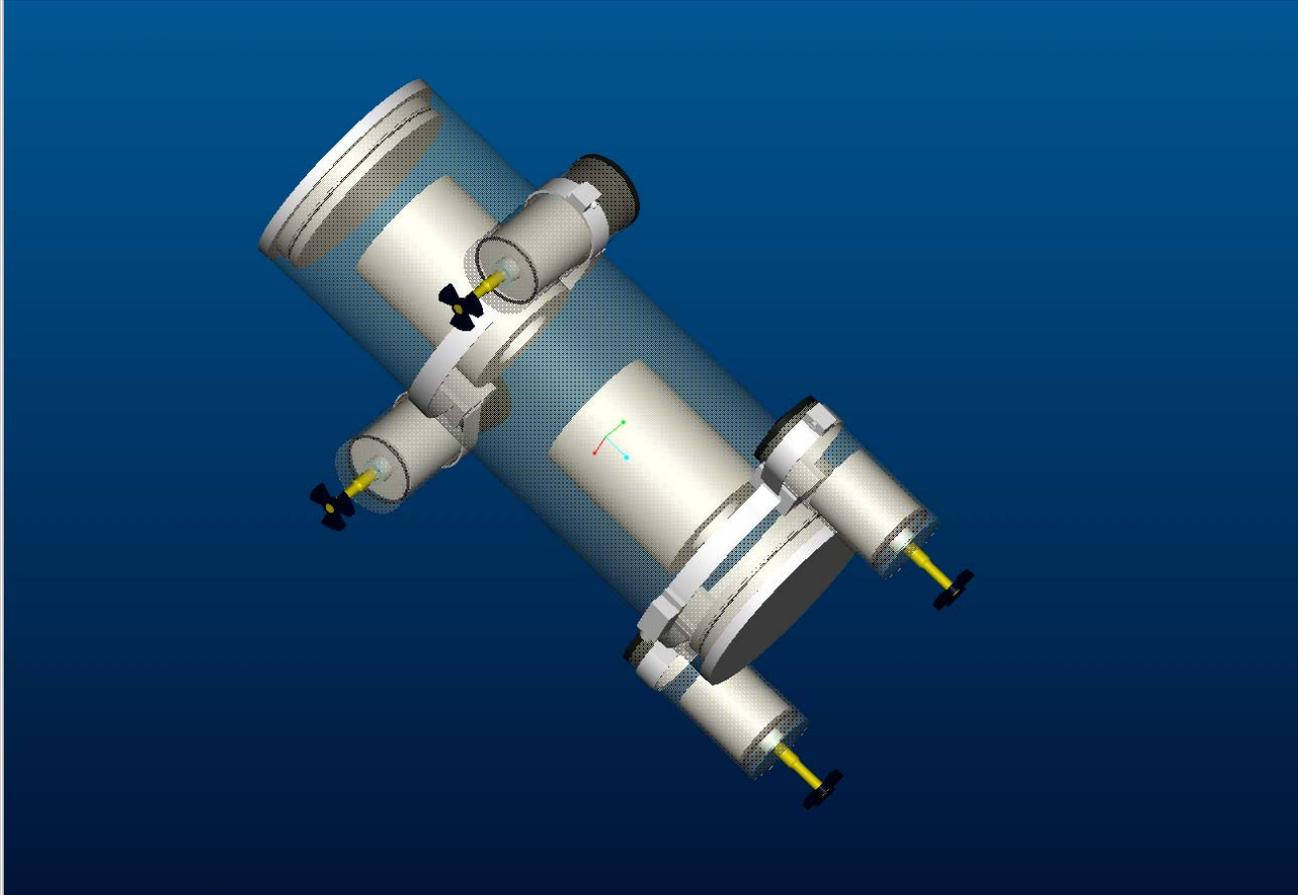
Mini-Stirling Engine Fan

Dean Lowe



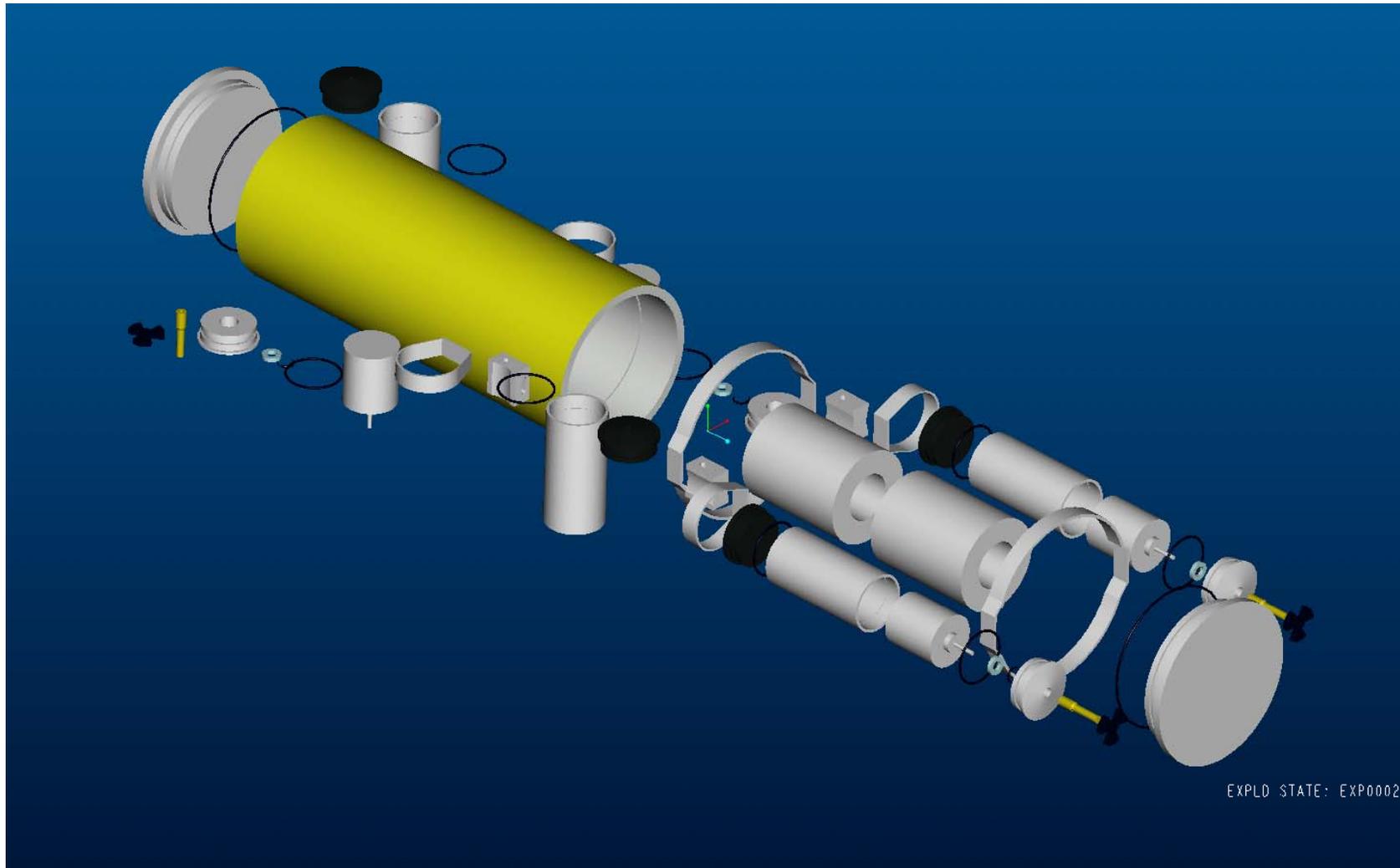
Parametric Modeling of an ROV

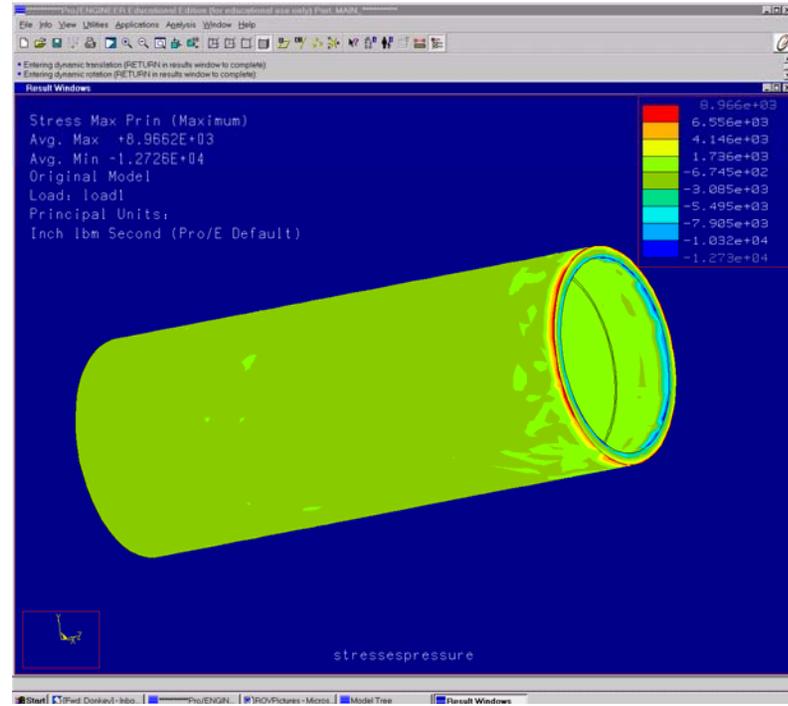
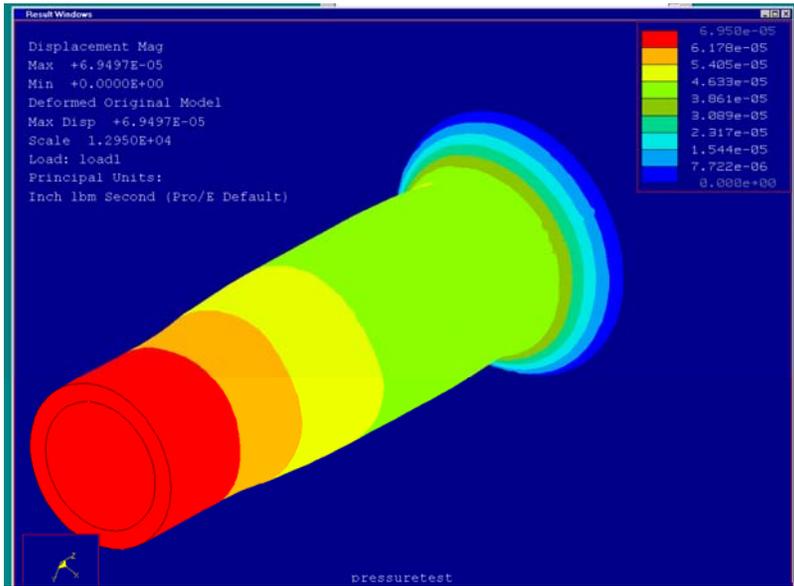
Chris Lyons, and Alex Wigzell

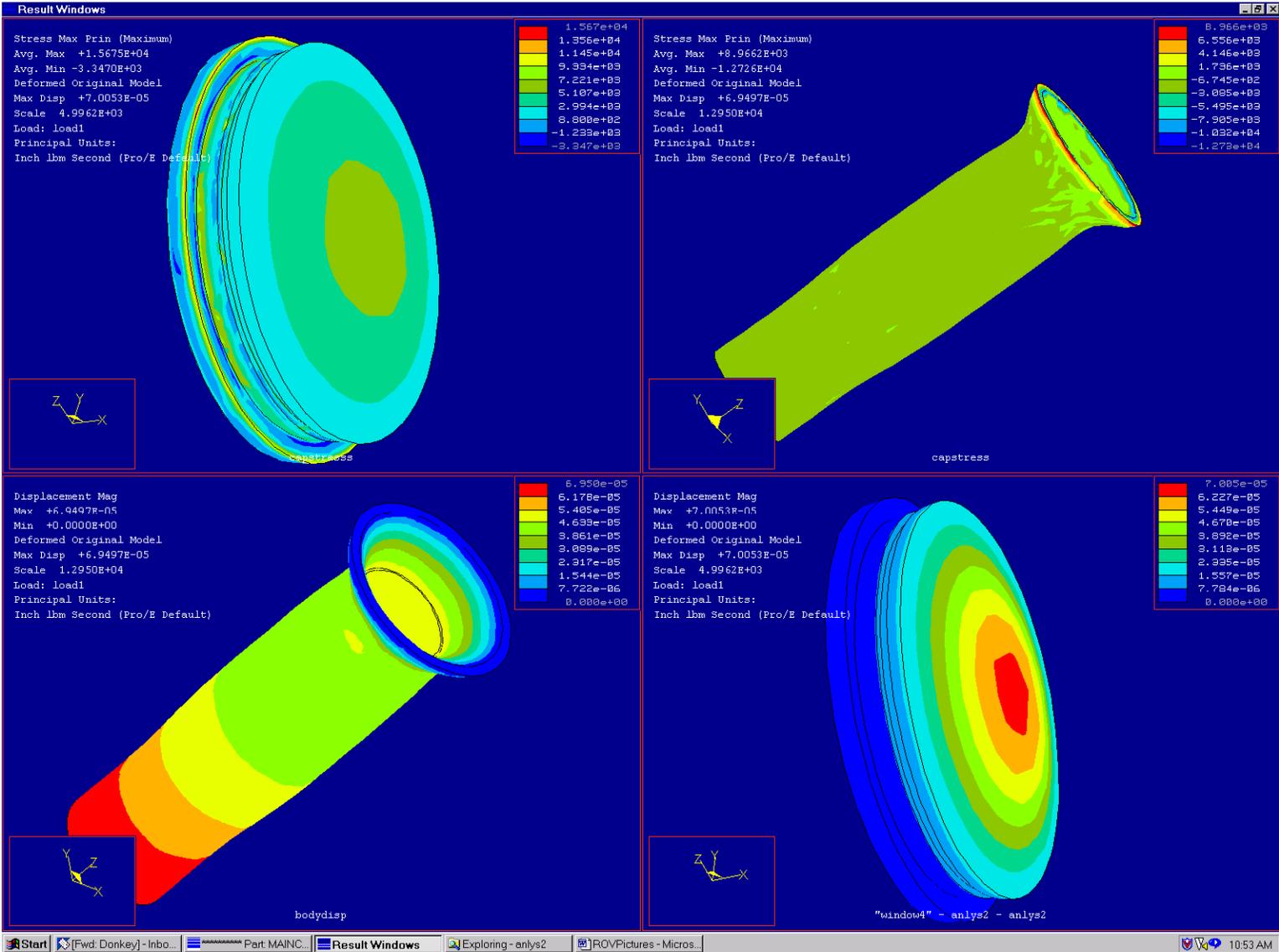


Parametric Modeling of an ROV

Chris Lyons, and Alex Wigzell

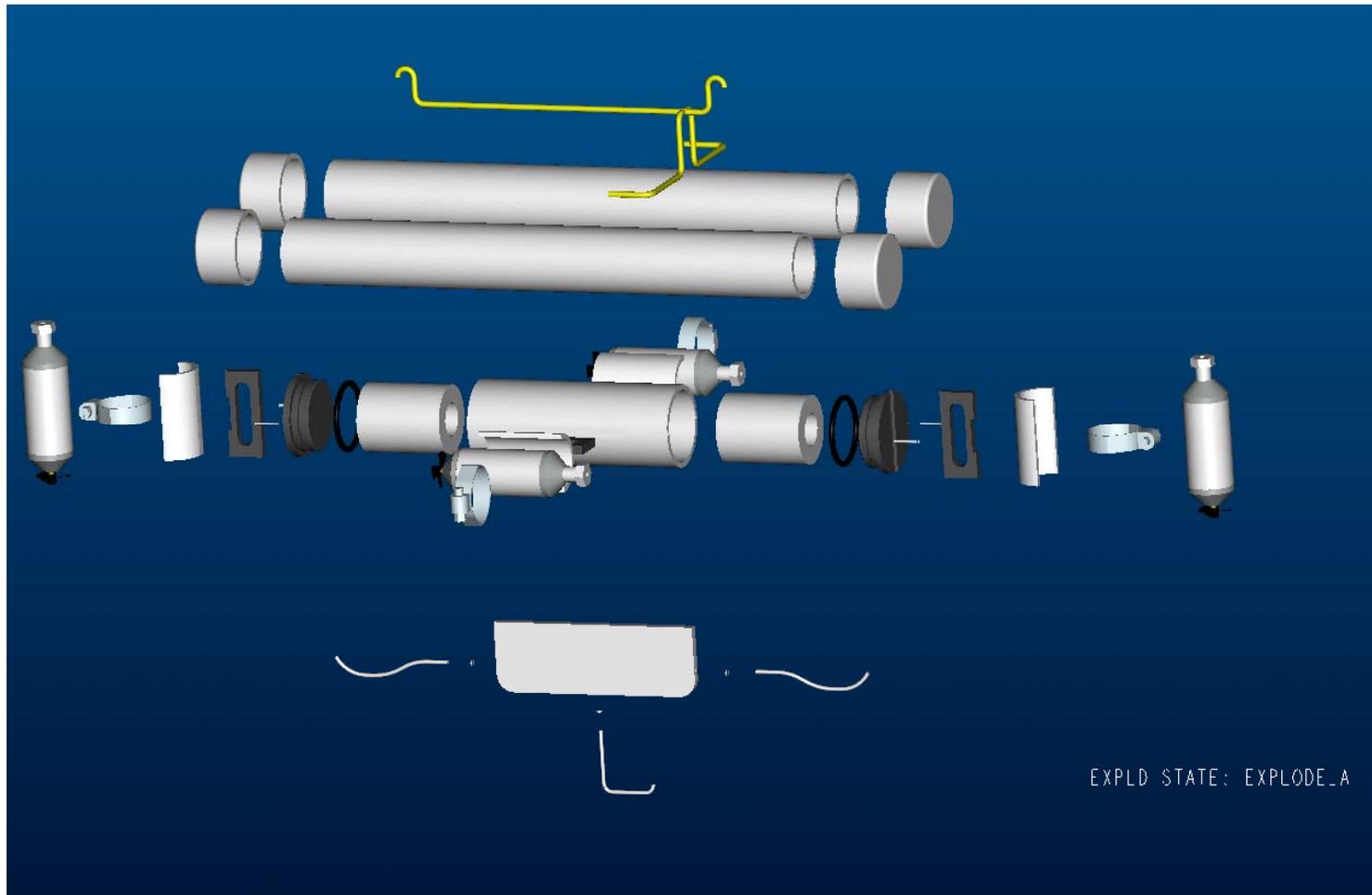






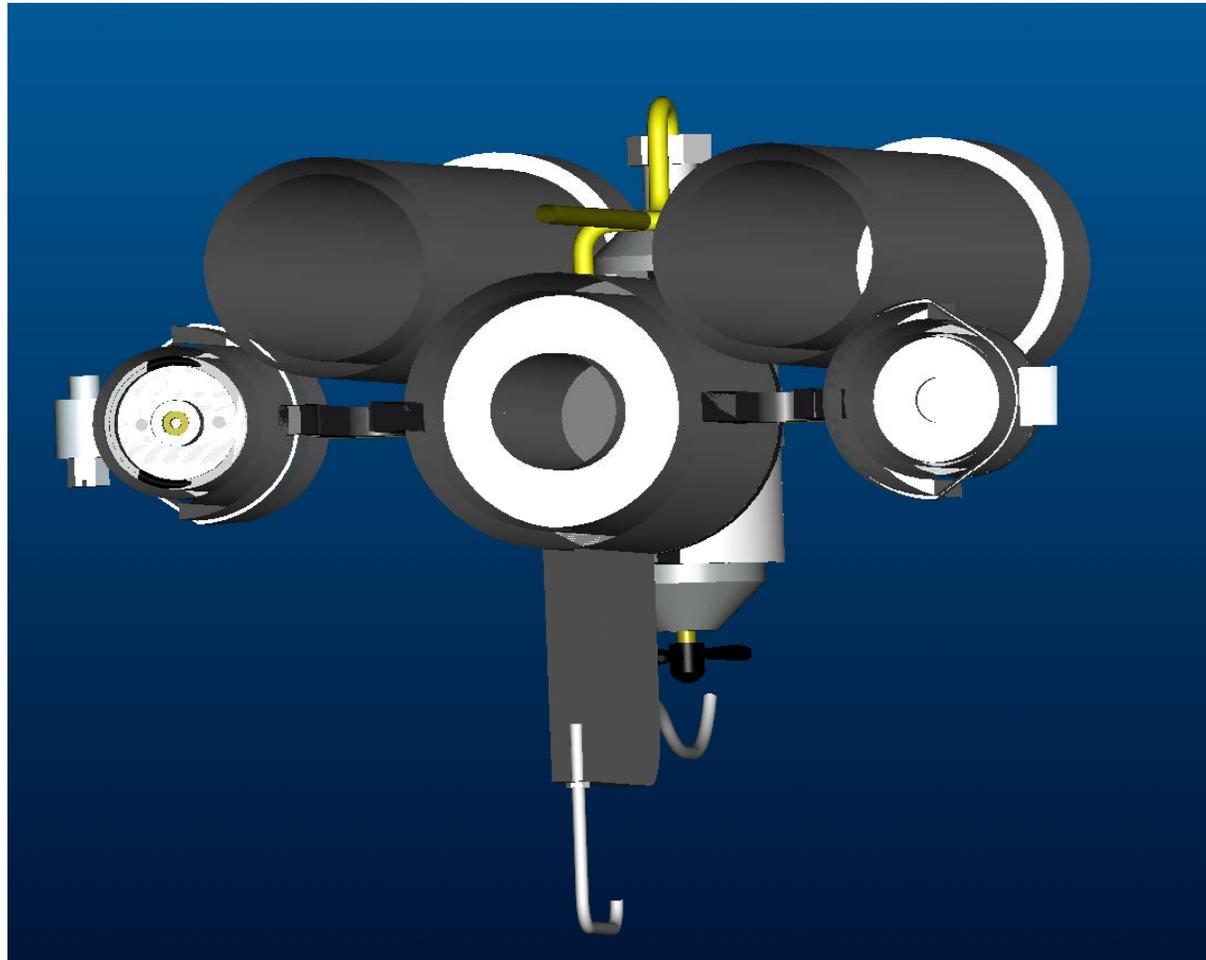
Computer Modeling of a Remotely Operated Underwater Vehicle

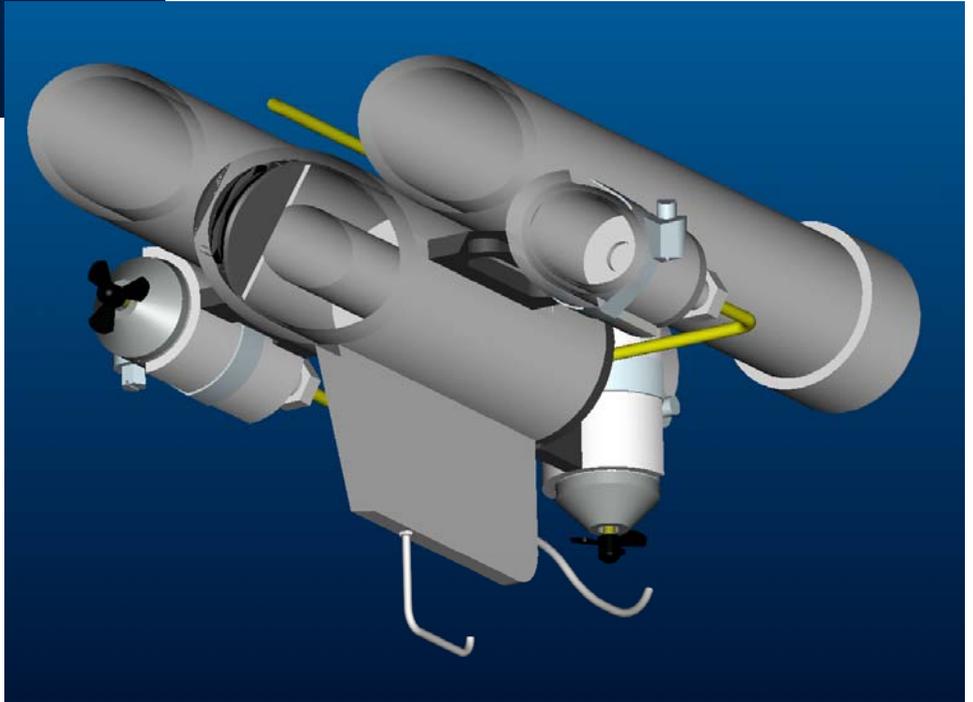
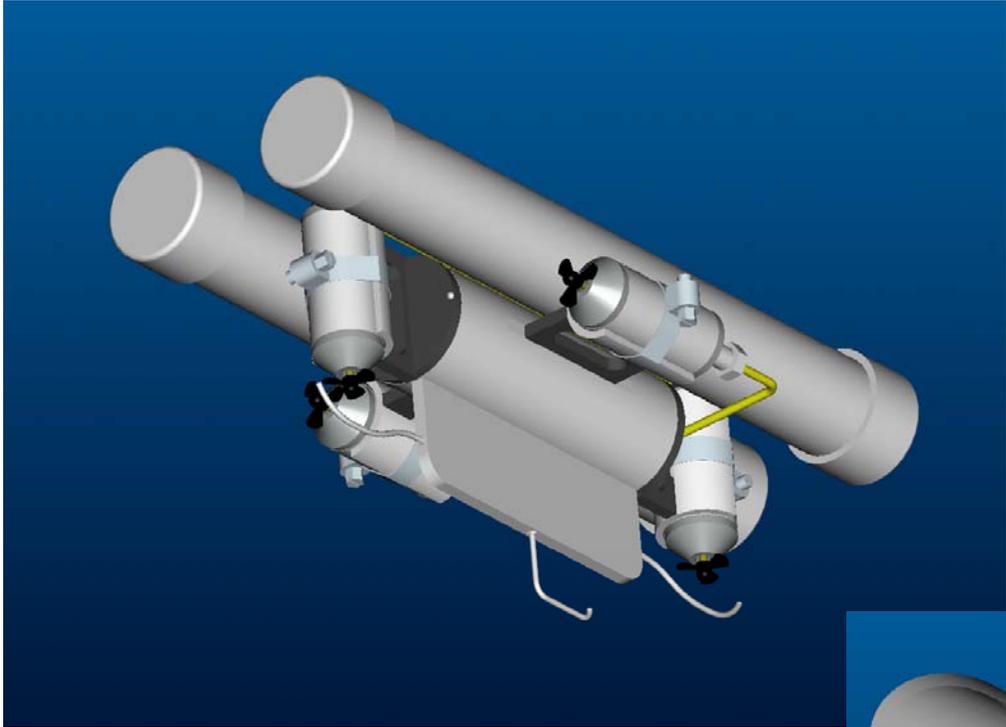
Chris Dicken and Mark Tsui



Computer Modeling of a Remotely Operated Underwater Vehicle

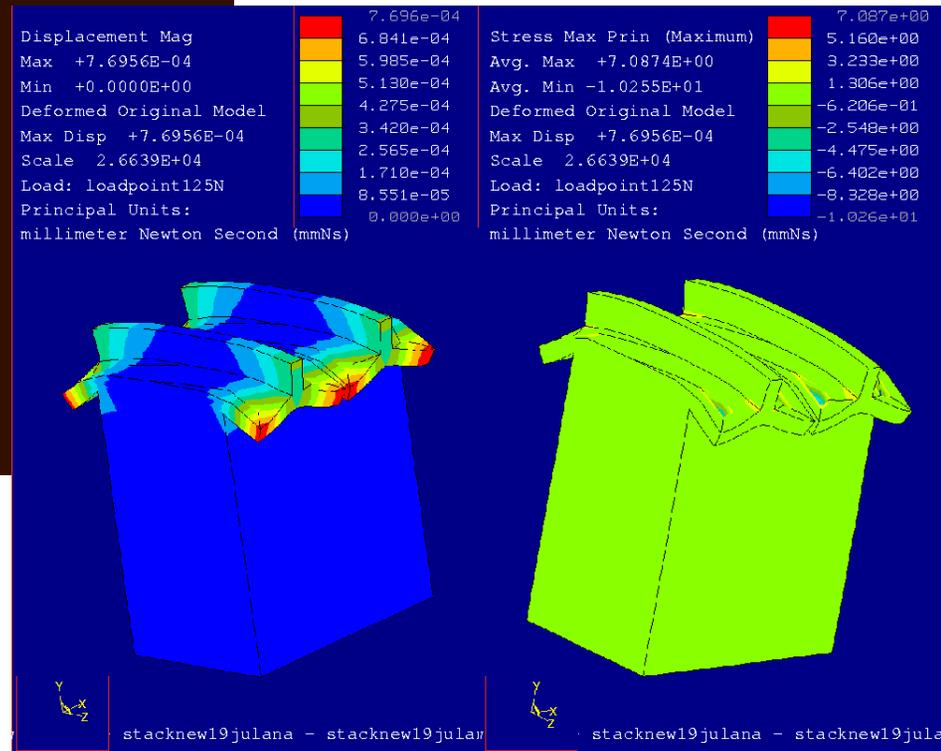
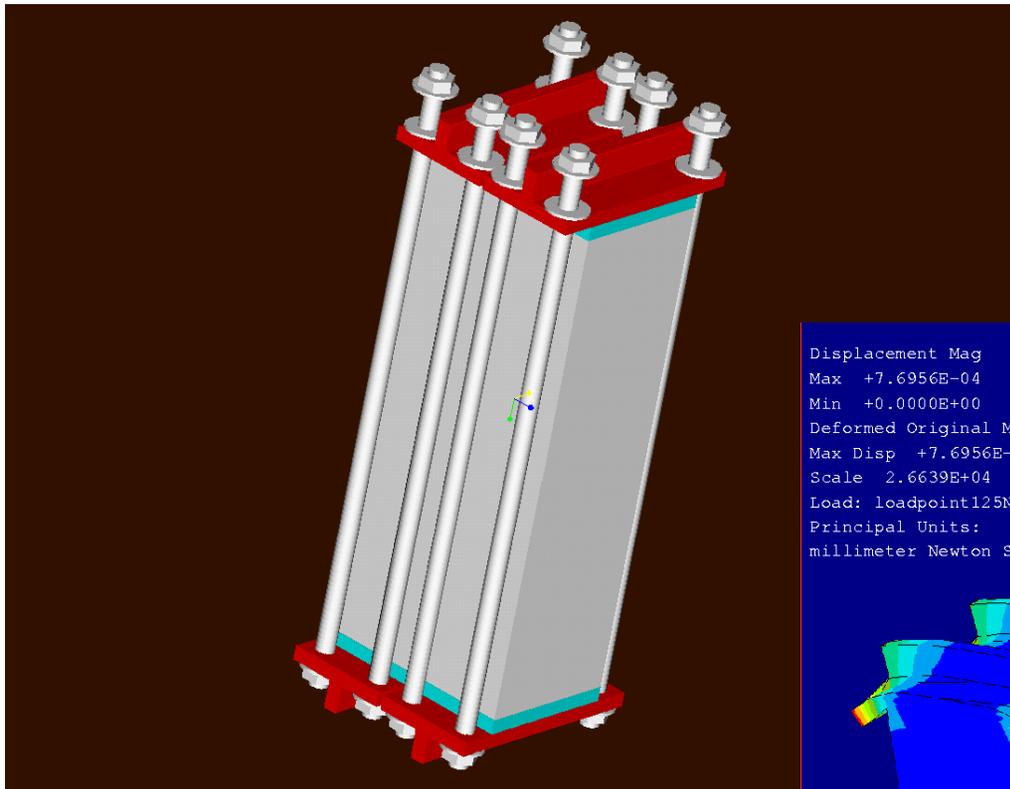
Chris Dicken and Mark Tsui



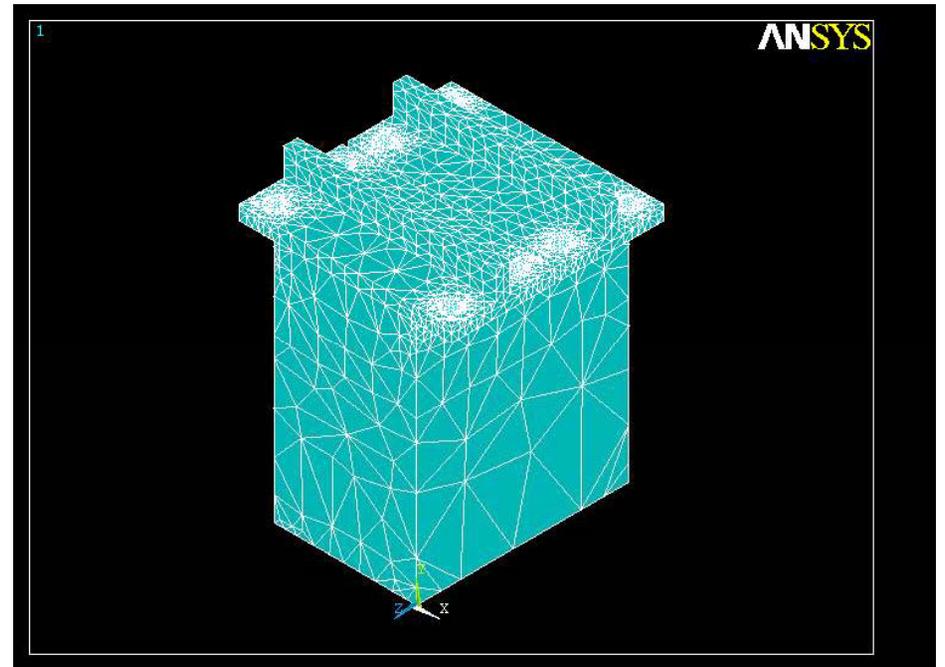
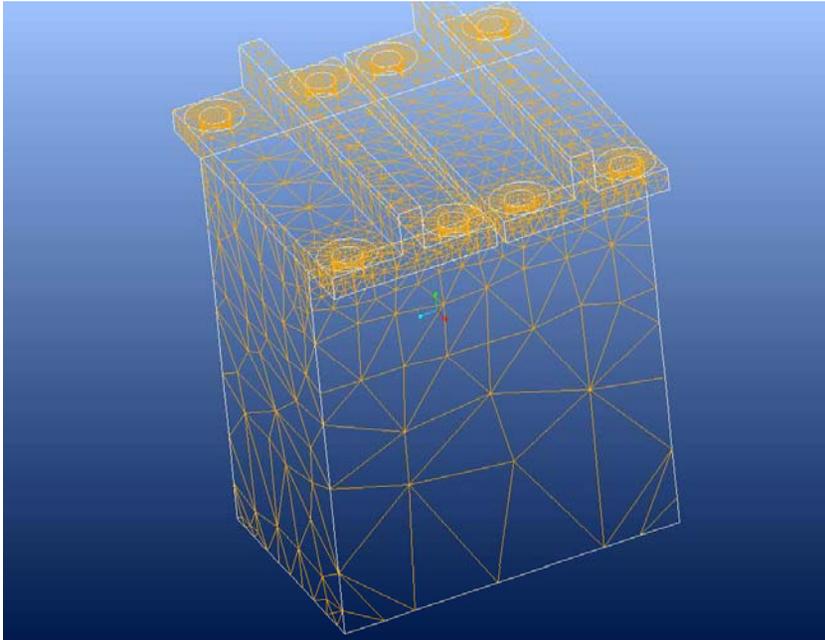


Fuel Cell Stack Modeling and Analysis

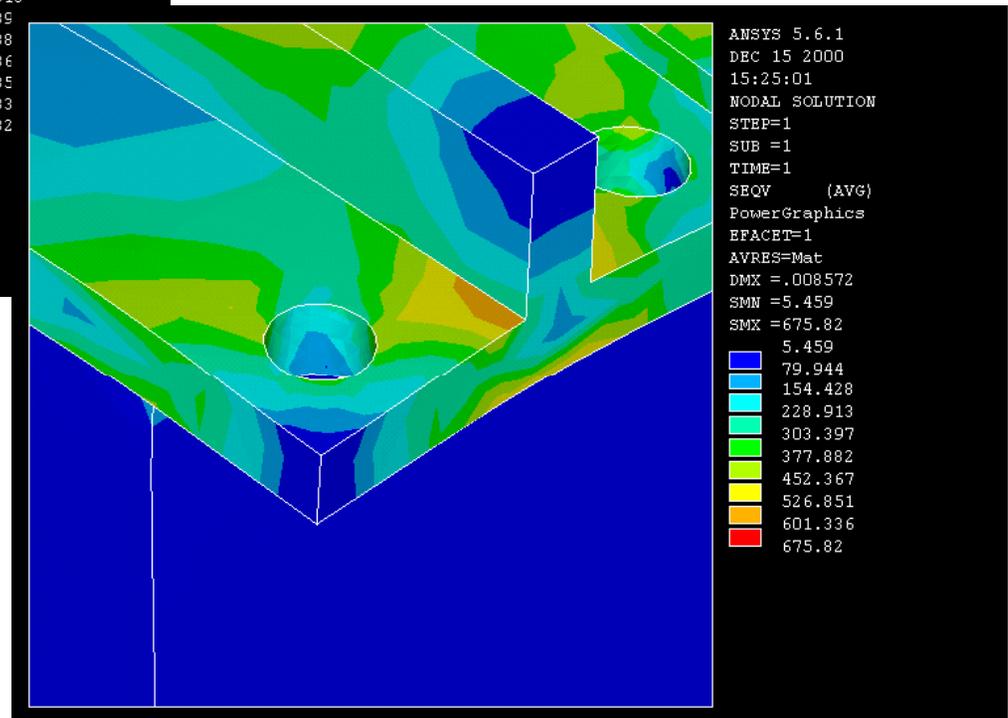
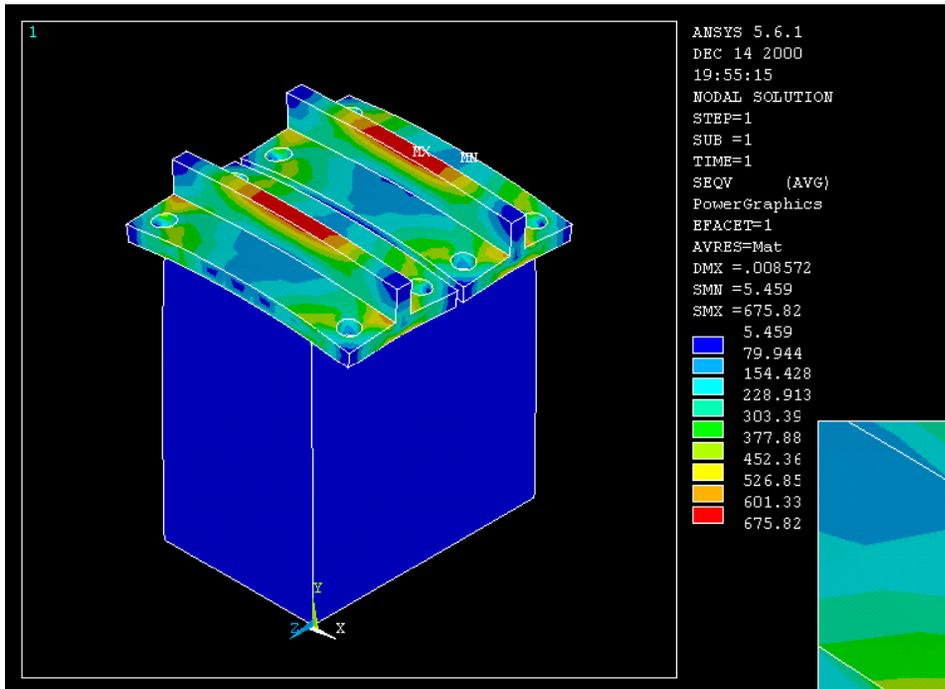
M.M. Rao



FEA Mesh Generation of Fuel Cell Stack

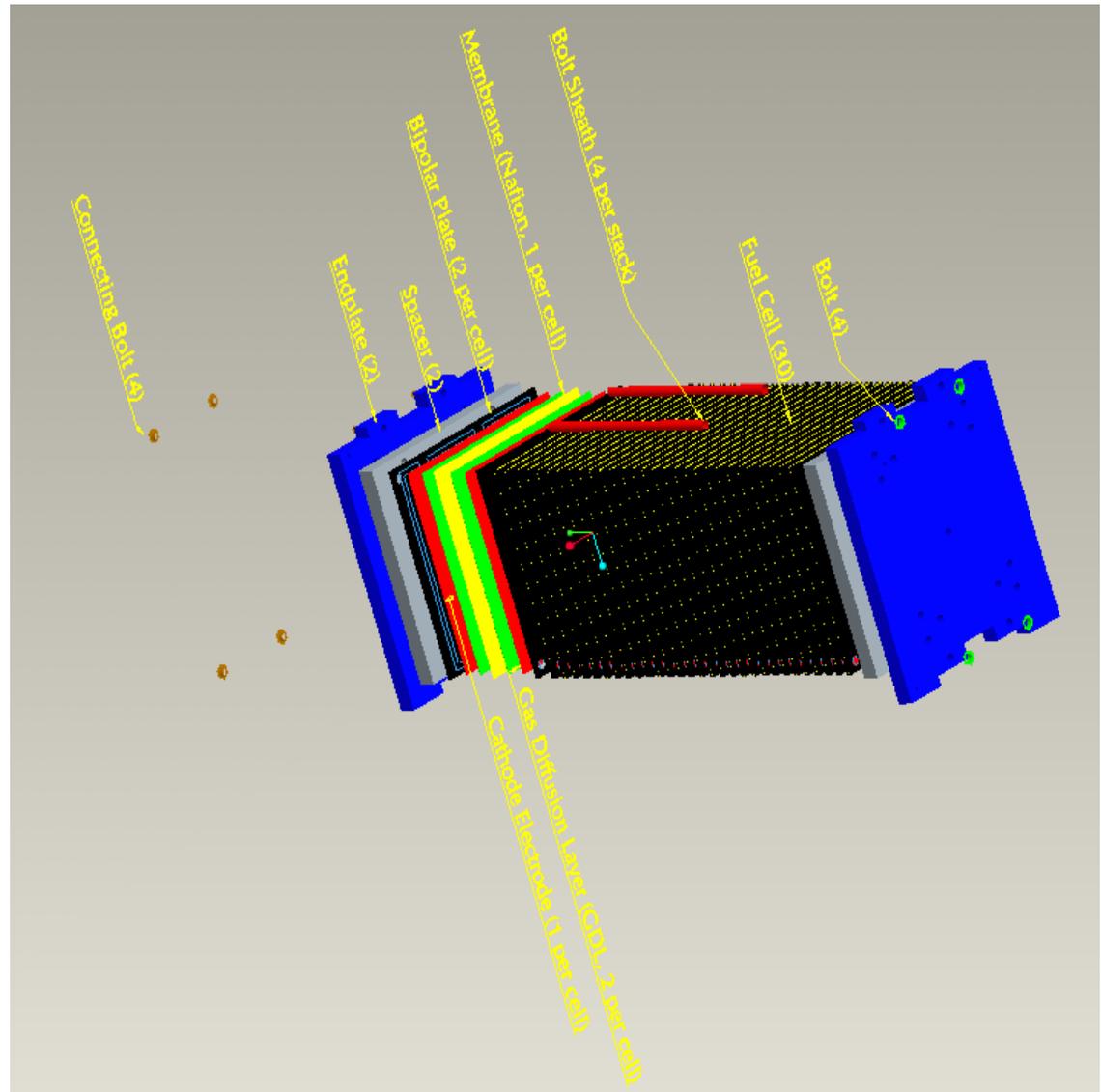
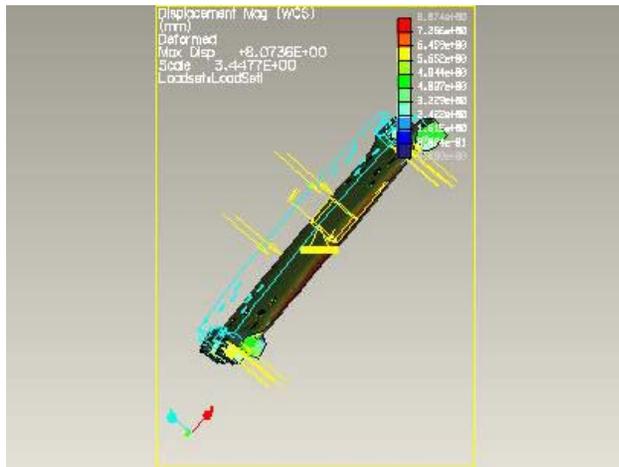
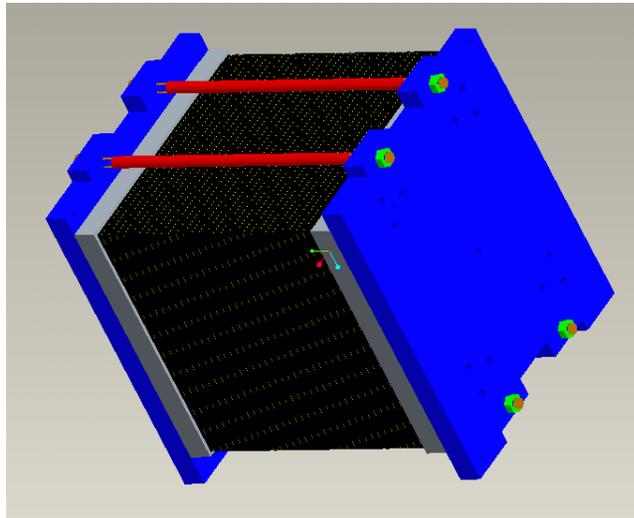


FEA Fuel Cell Stack Stress and Compression Analysis



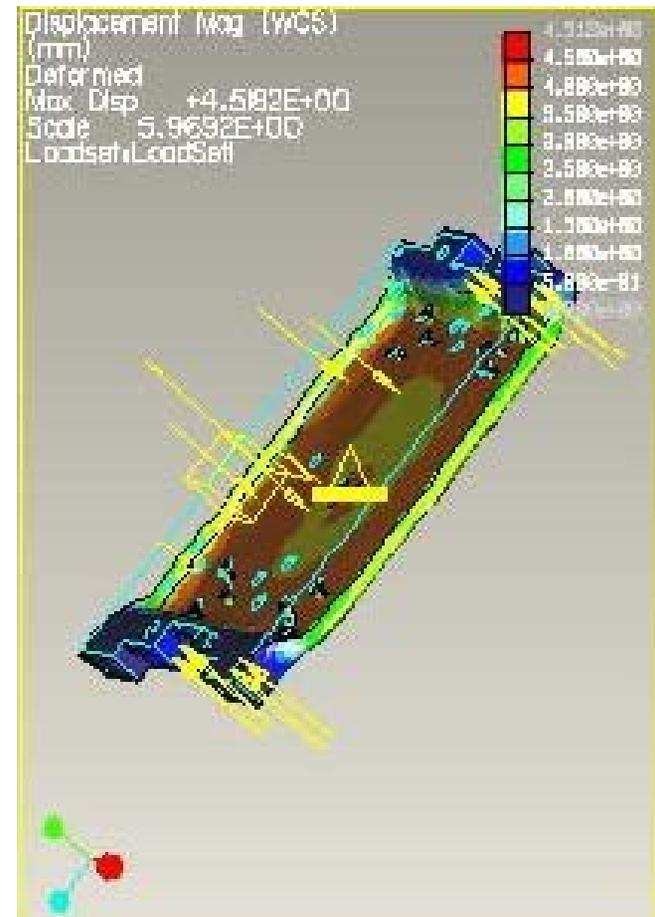
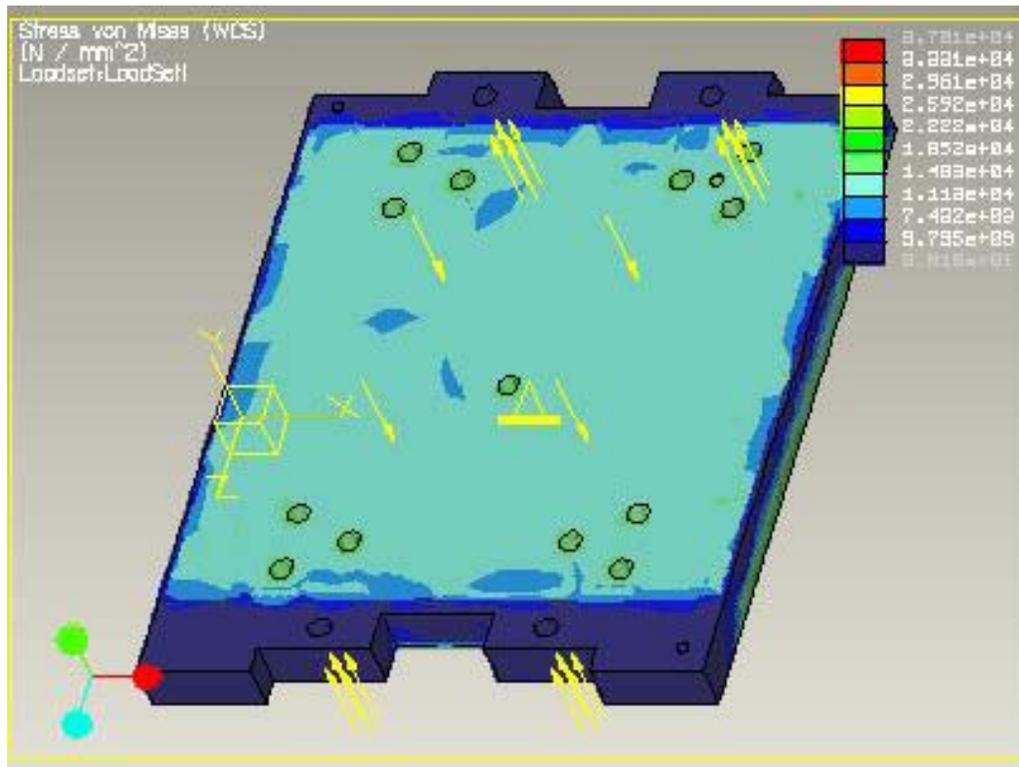
Modeling and Optimization of Fuel Cell Stack Endplate

Jeff Wishart



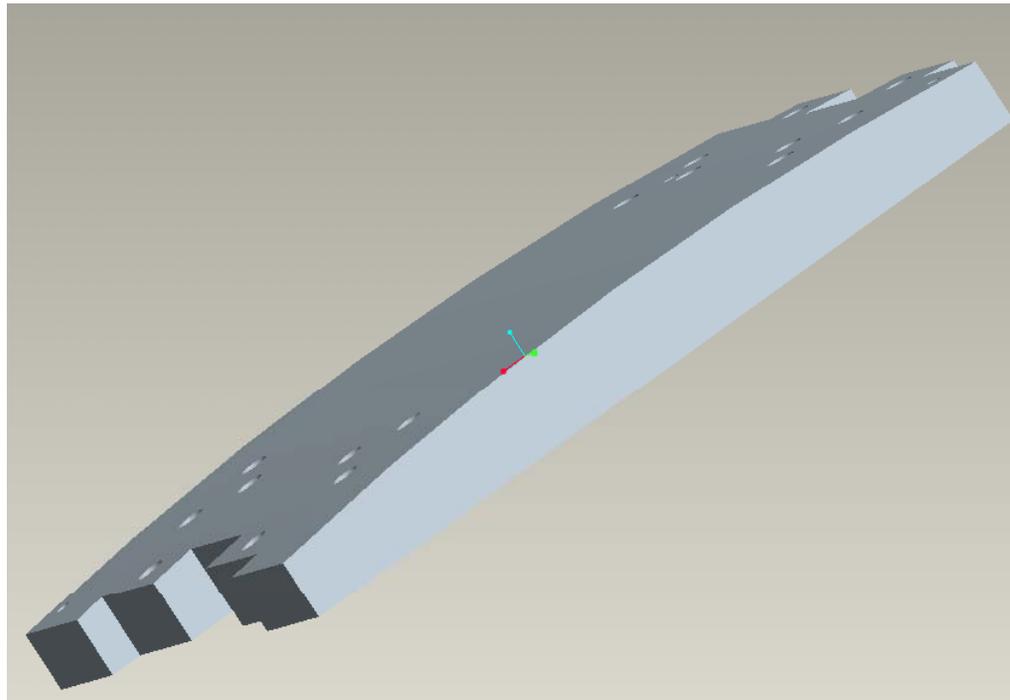
Structural Analysis

- Pressure load on place of Endplate from spacer and from four bolts/nuts: 0.5MPa and 0.125MPa, respectively
- Actual load causes 4 μ m of displacement: too small for Pro/E to handle
- Artificial Pressure loads of 20000 and 5000 MPa used
- Maximum Displacement: 4.518mm
- Maximum Von Mises Stress: 37GPa



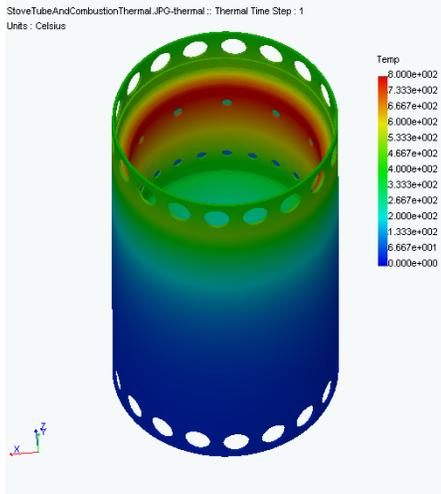
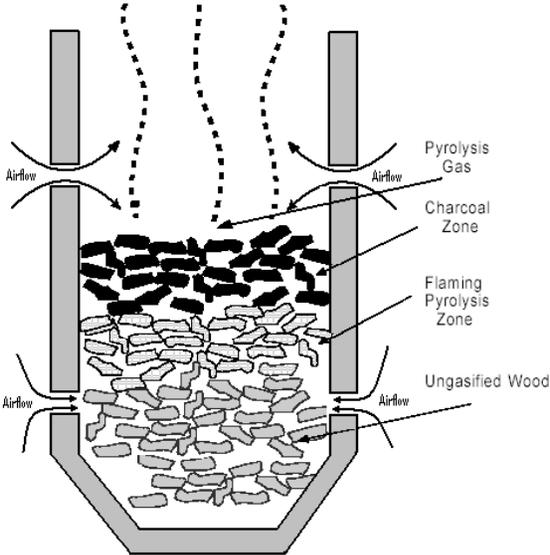
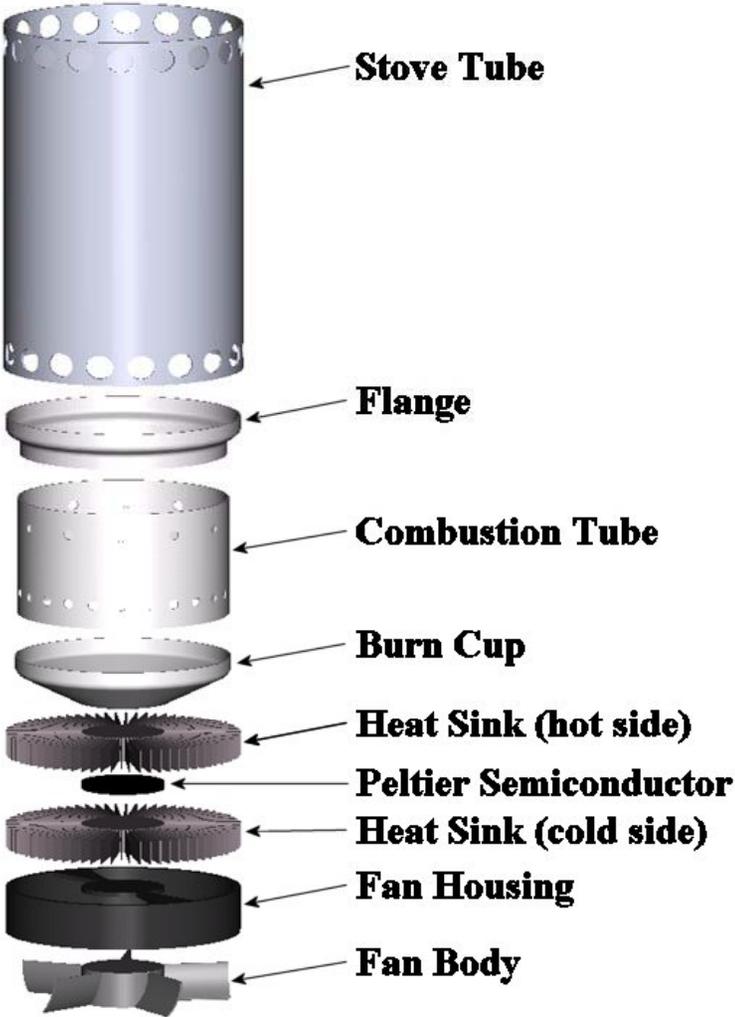
Bowed Endplate Design

- Radius of curve (bow) calculated such that the maximum distance from curved surface to original dimension equal to maximum displacement value (4.518mm), and then varied decreasingly to zero
- Maximum Displacement: 8.07mm
- Maximum Von Mises Stress: 90GPa



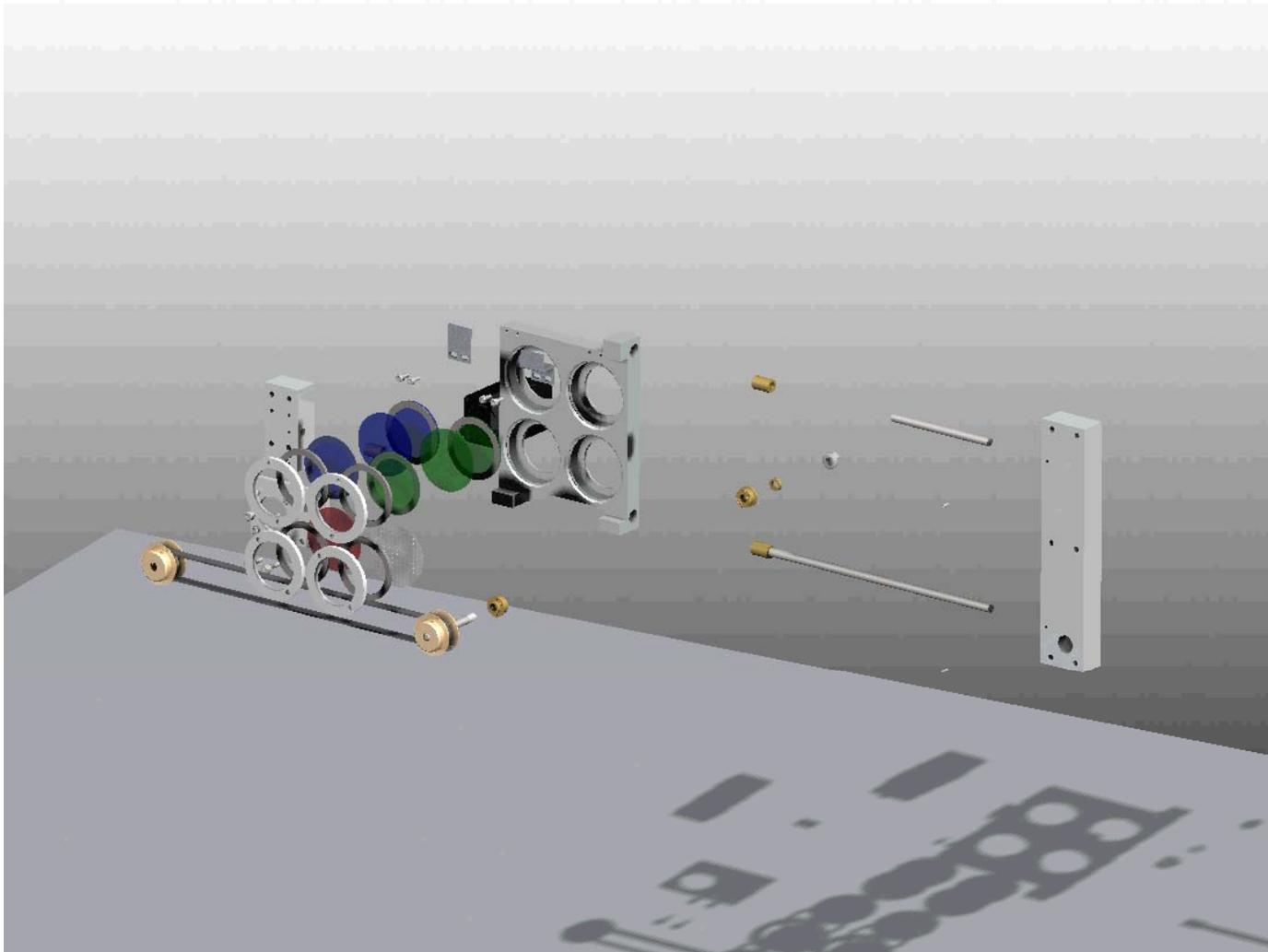
Modelling a Lightweight Solid Fuel Backpacking Stove

Scott Borstad



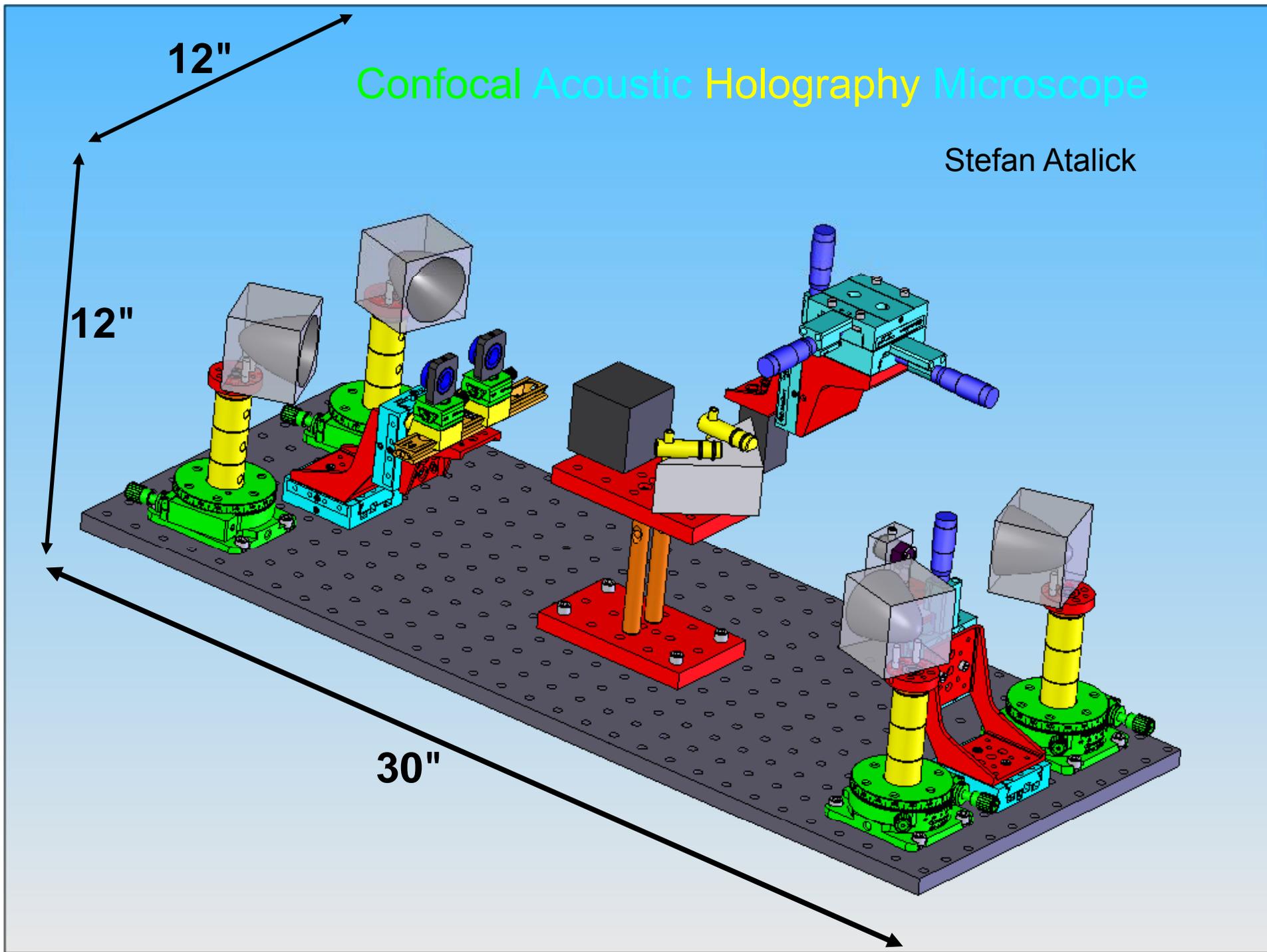
Color Filter Slide Assembly Animation

Alexis Hill and Ben Townsend (SolidWorks)

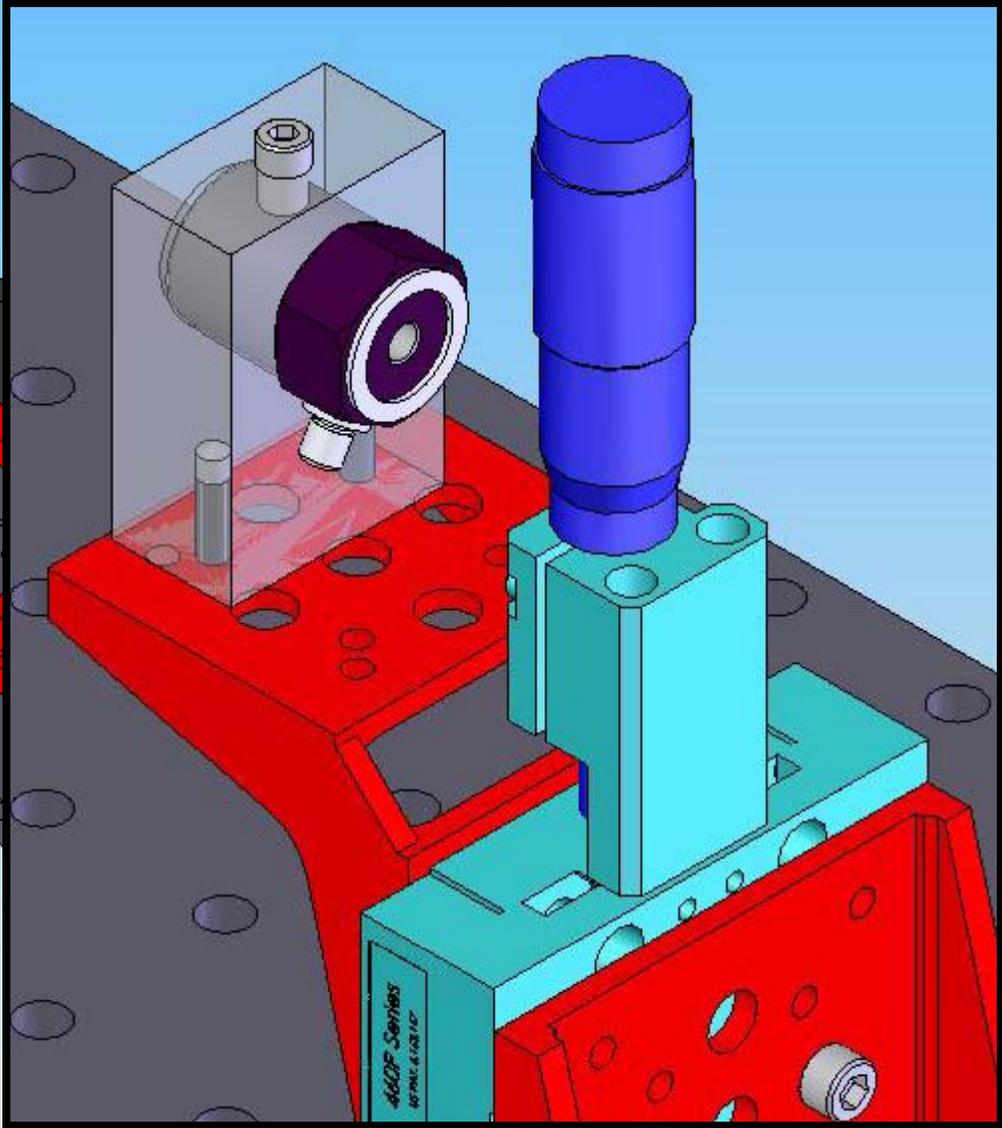
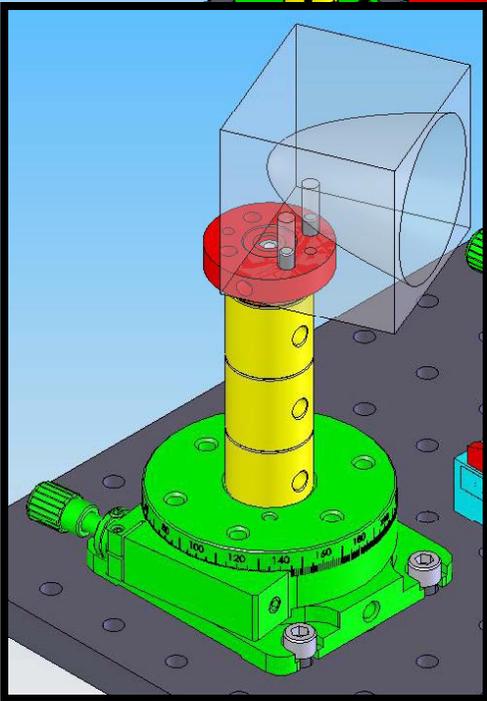
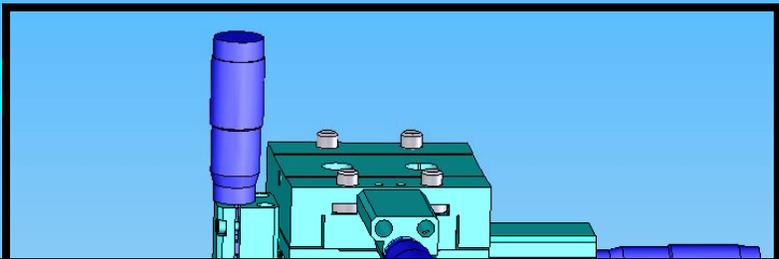
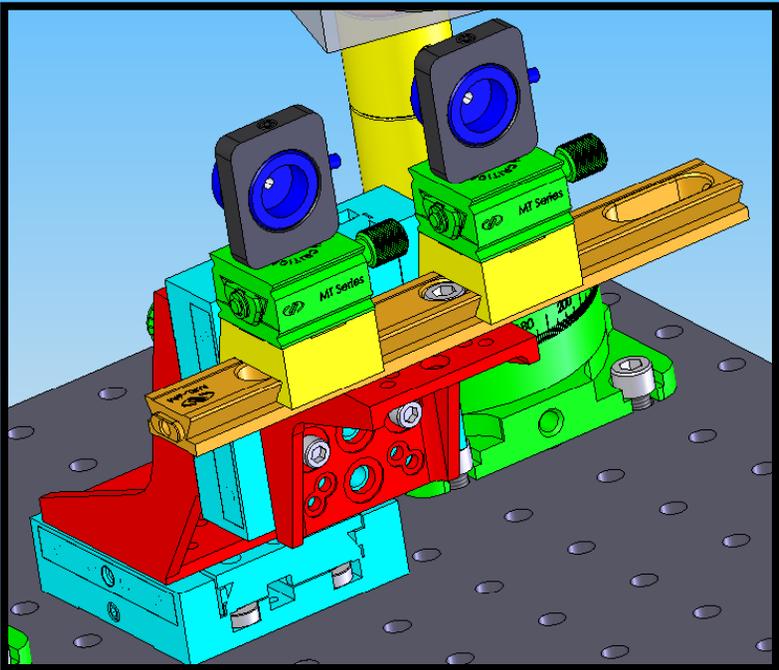


Confocal Acoustic Holography Microscope

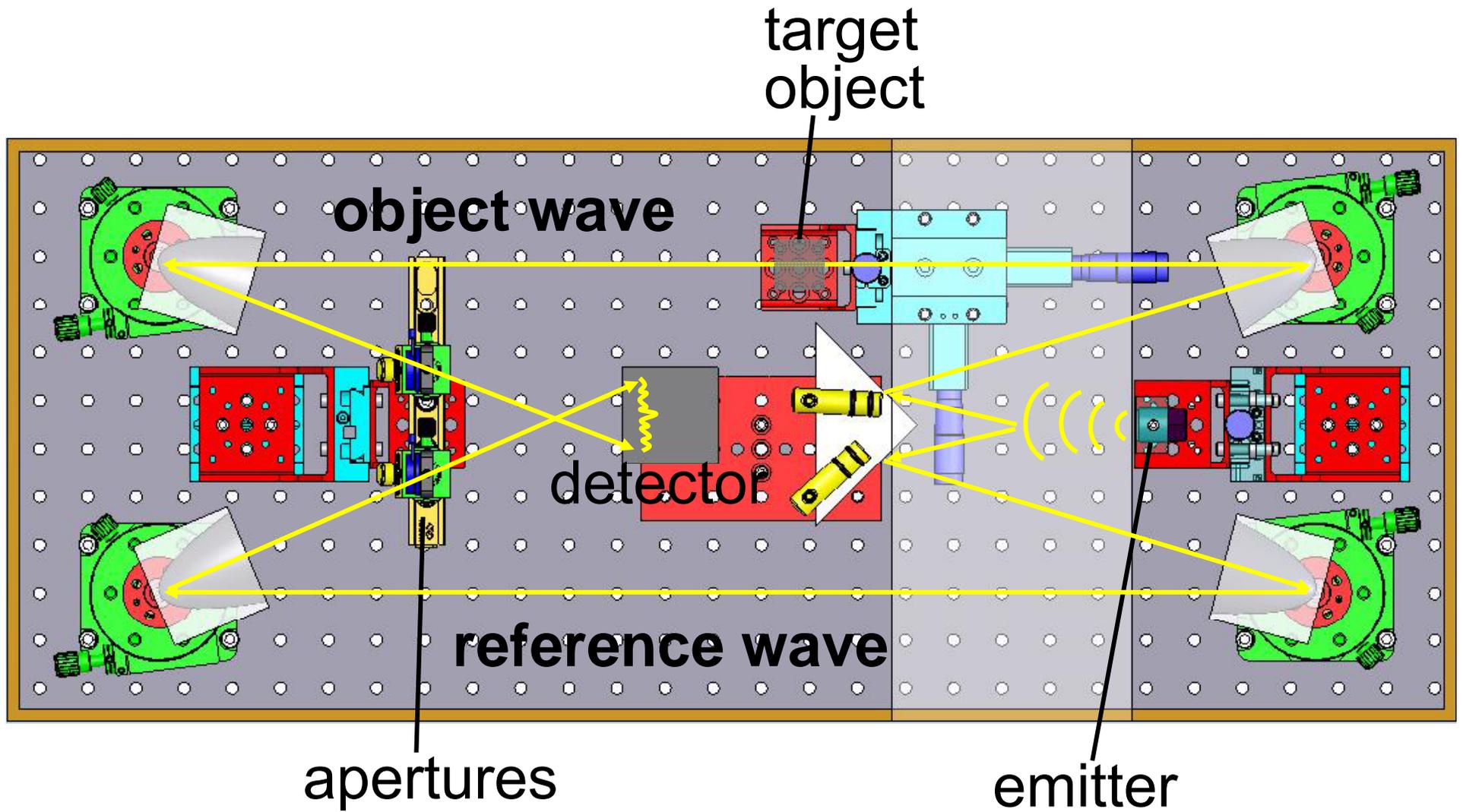
Stefan Atalick



D Mo

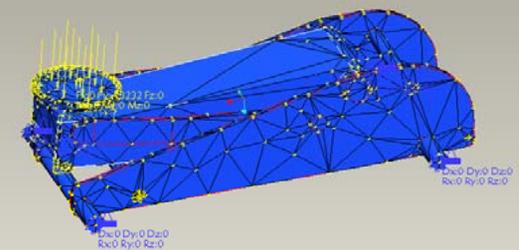
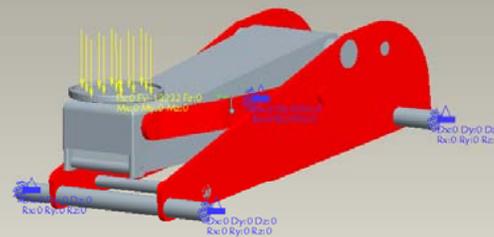
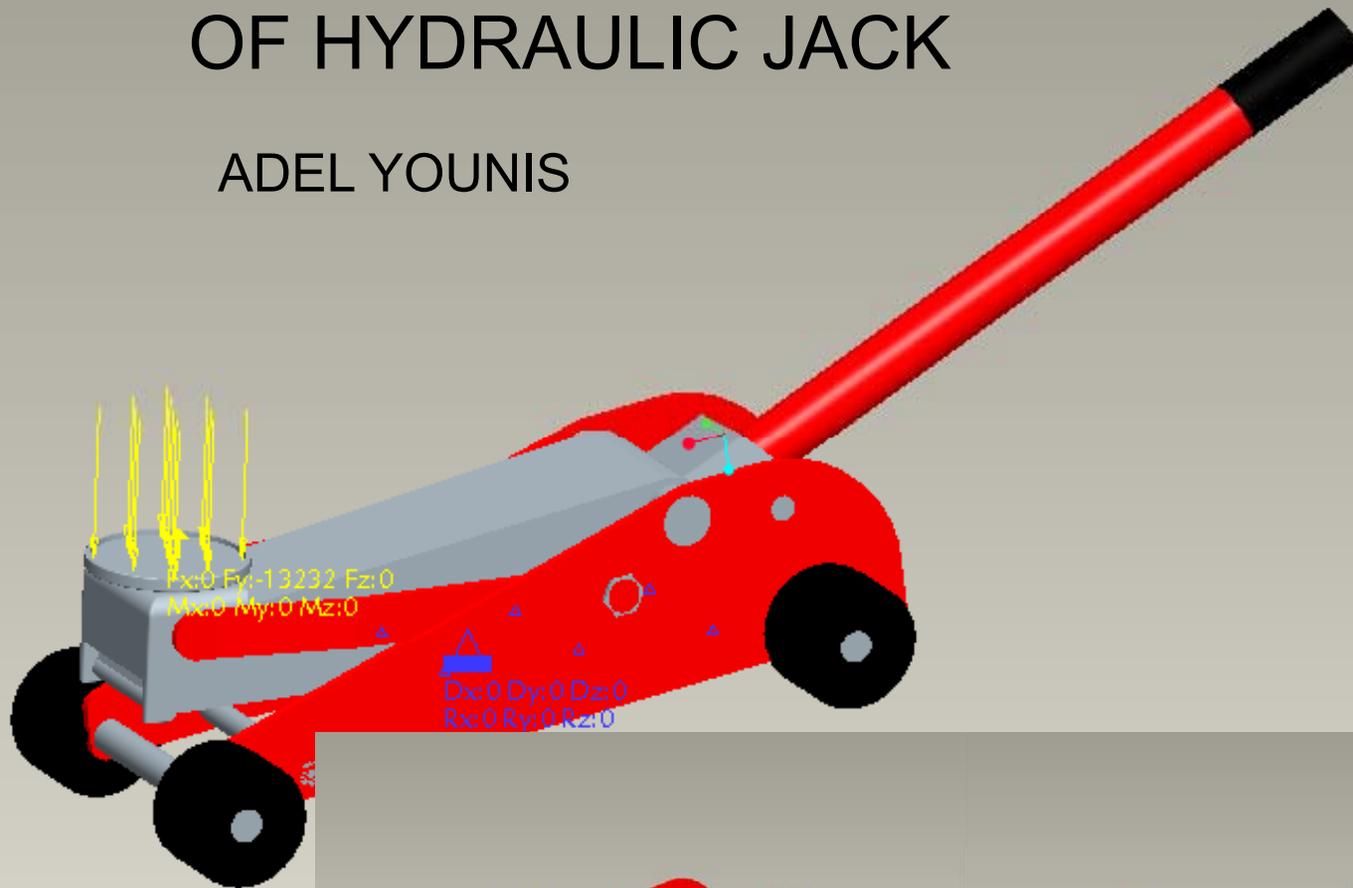


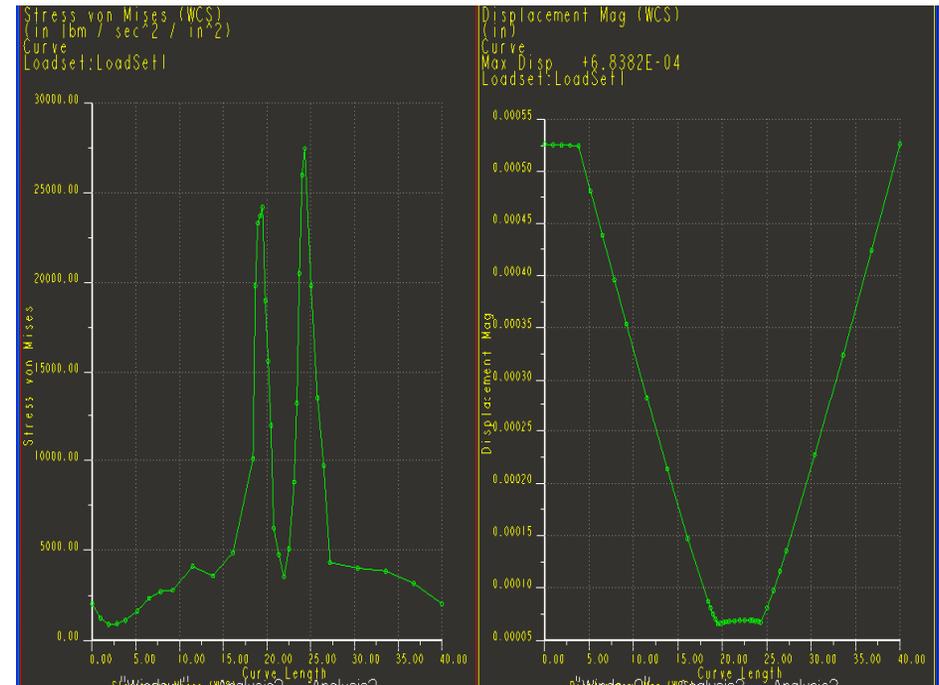
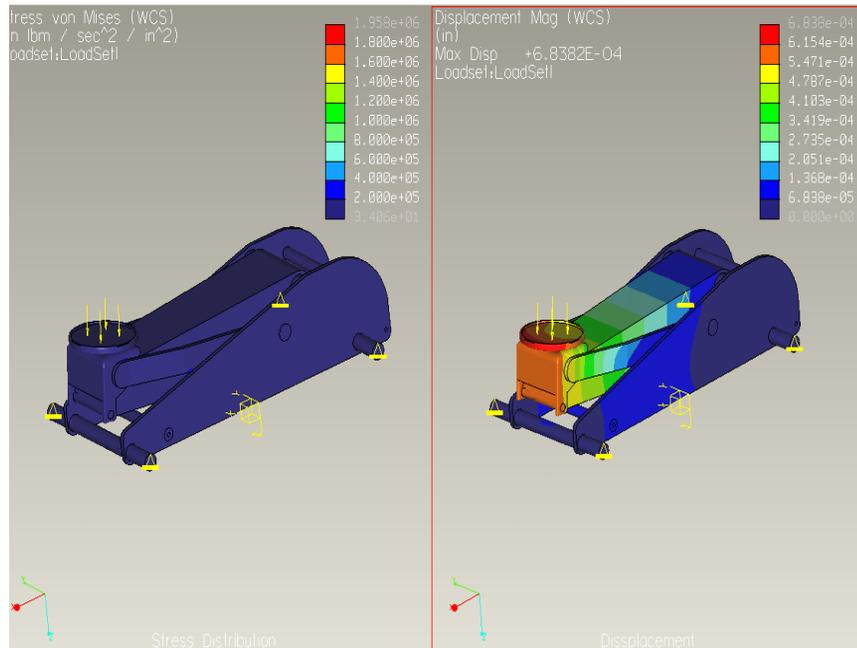
CAD Model



3-D MODELING AND DESIGN OPTIMIZATION OF HYDRAULIC JACK

ADEL YOUNIS





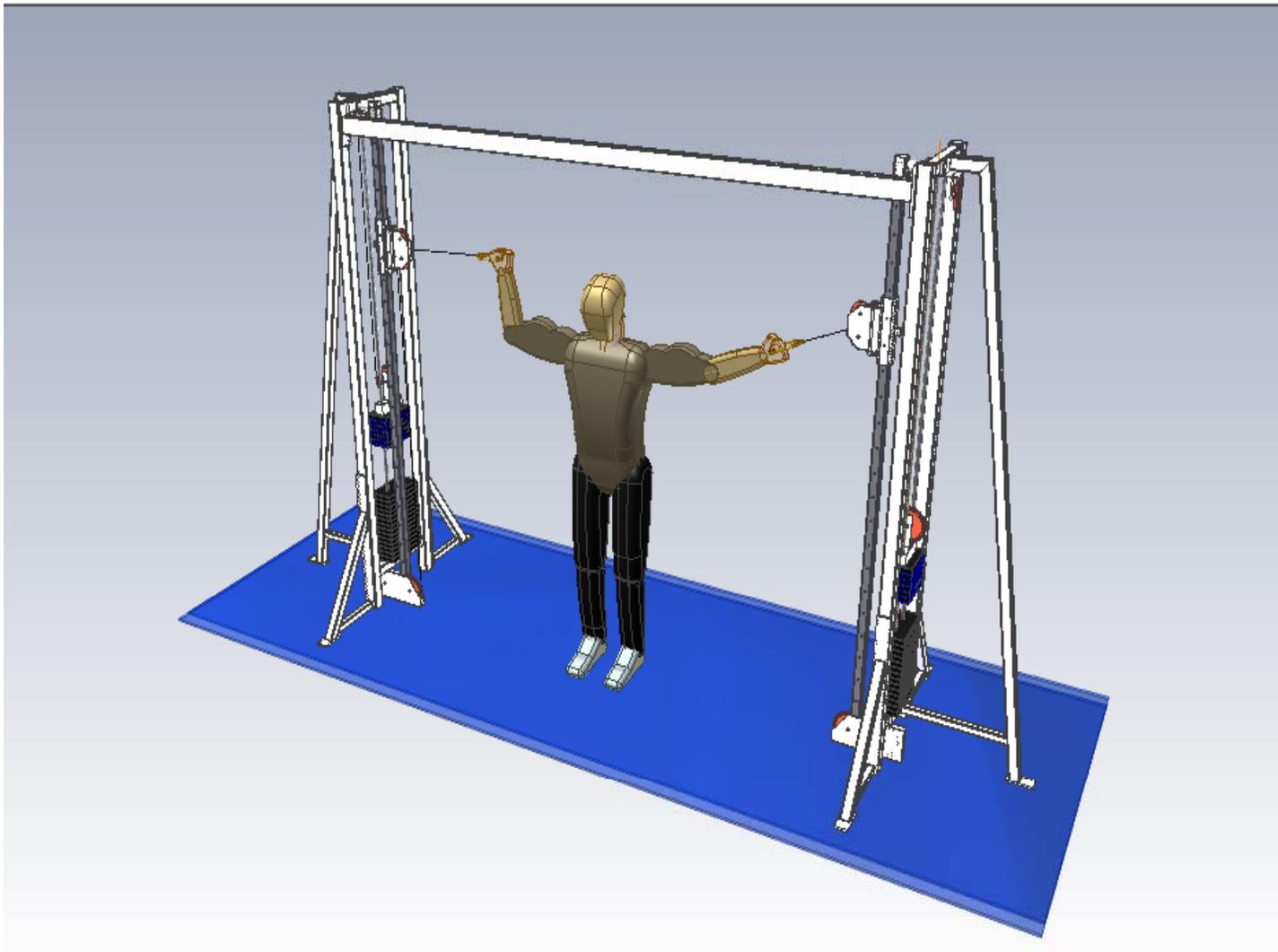
- The model showed low maximum stresses ($\sigma = 1.958e+06$ lbm/sec²/in²) under the design load.
- The design optimization result by selecting the pin diameter $d = 1.5''$ of the lifting arm also proved to be the Best Design:

d_{72} (Pin diameter)=1.5''

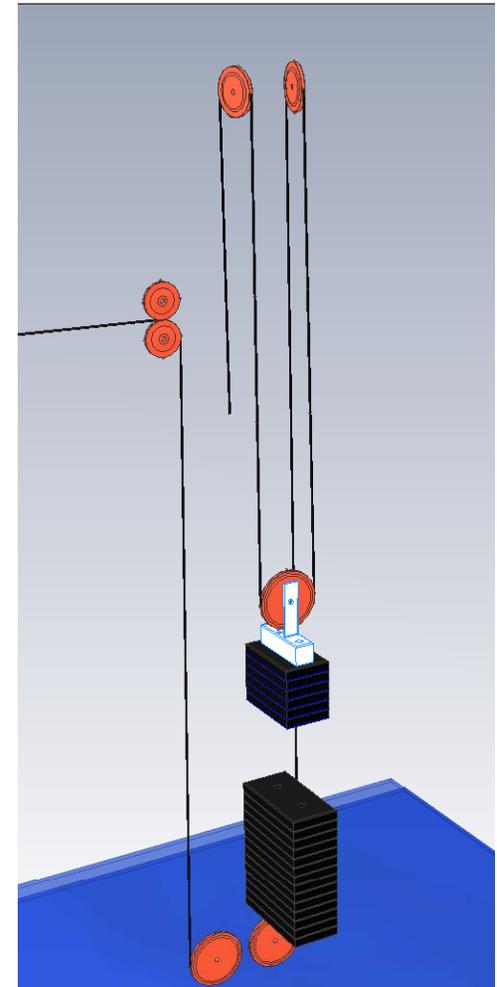
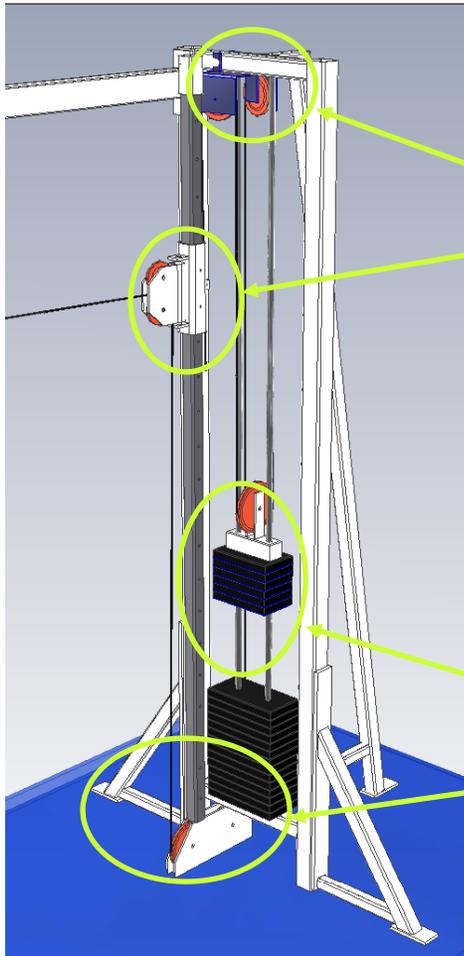
Goal: 1.1809e+02

Universal Cable Weight Machine

Hamid Abdollahi and Richard Chan



Model



Process

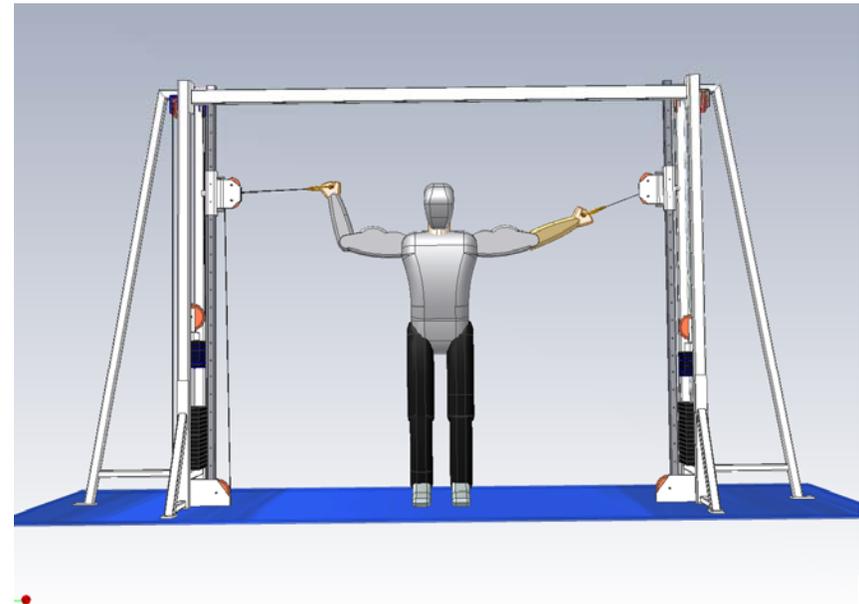
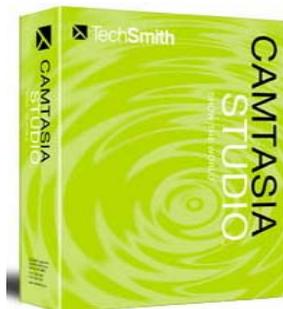
Modeling and Assembly using
Inventor 5.0

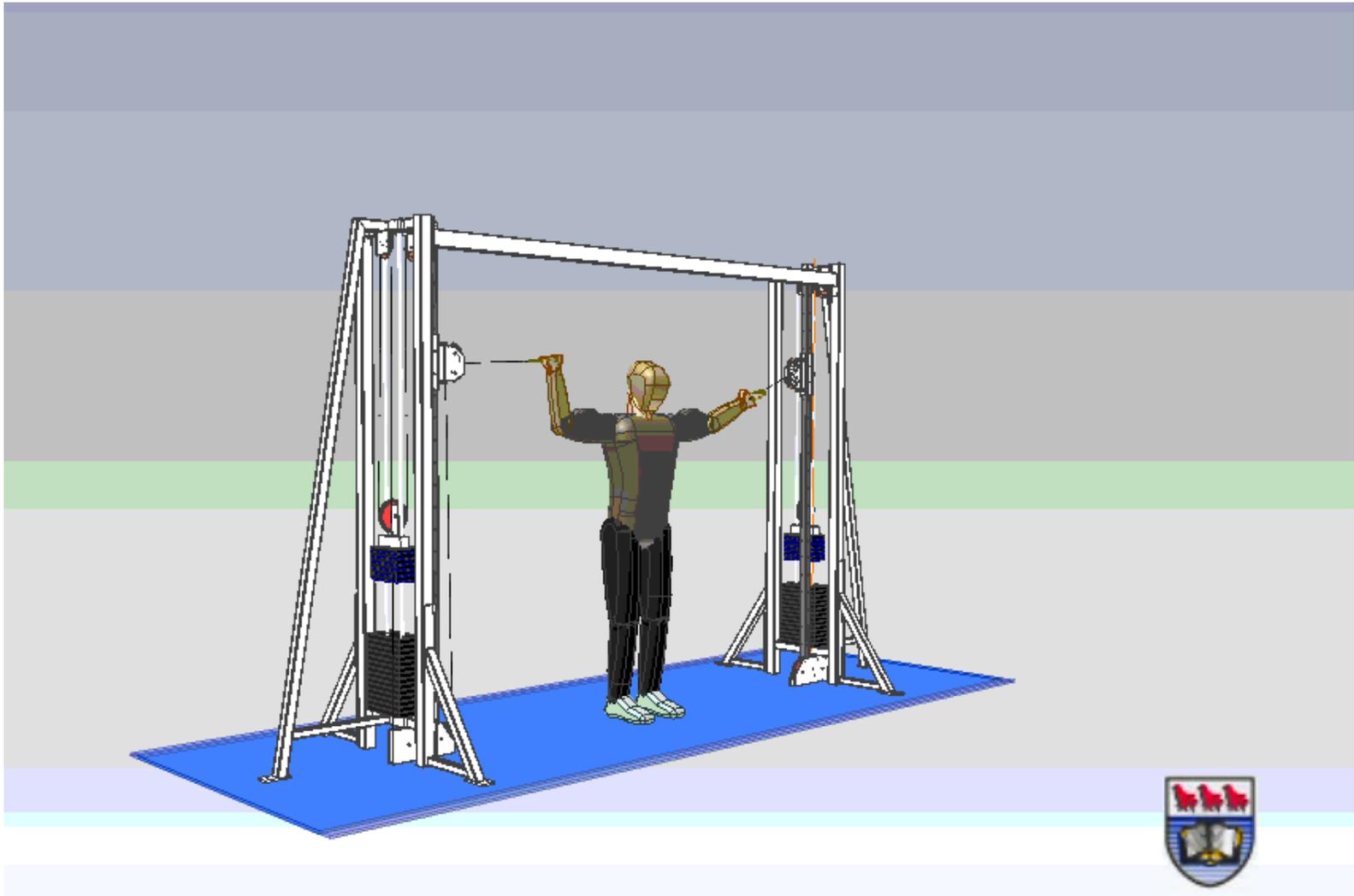


ANSYS IGES reader converts **IGES**
information into Parasolid data

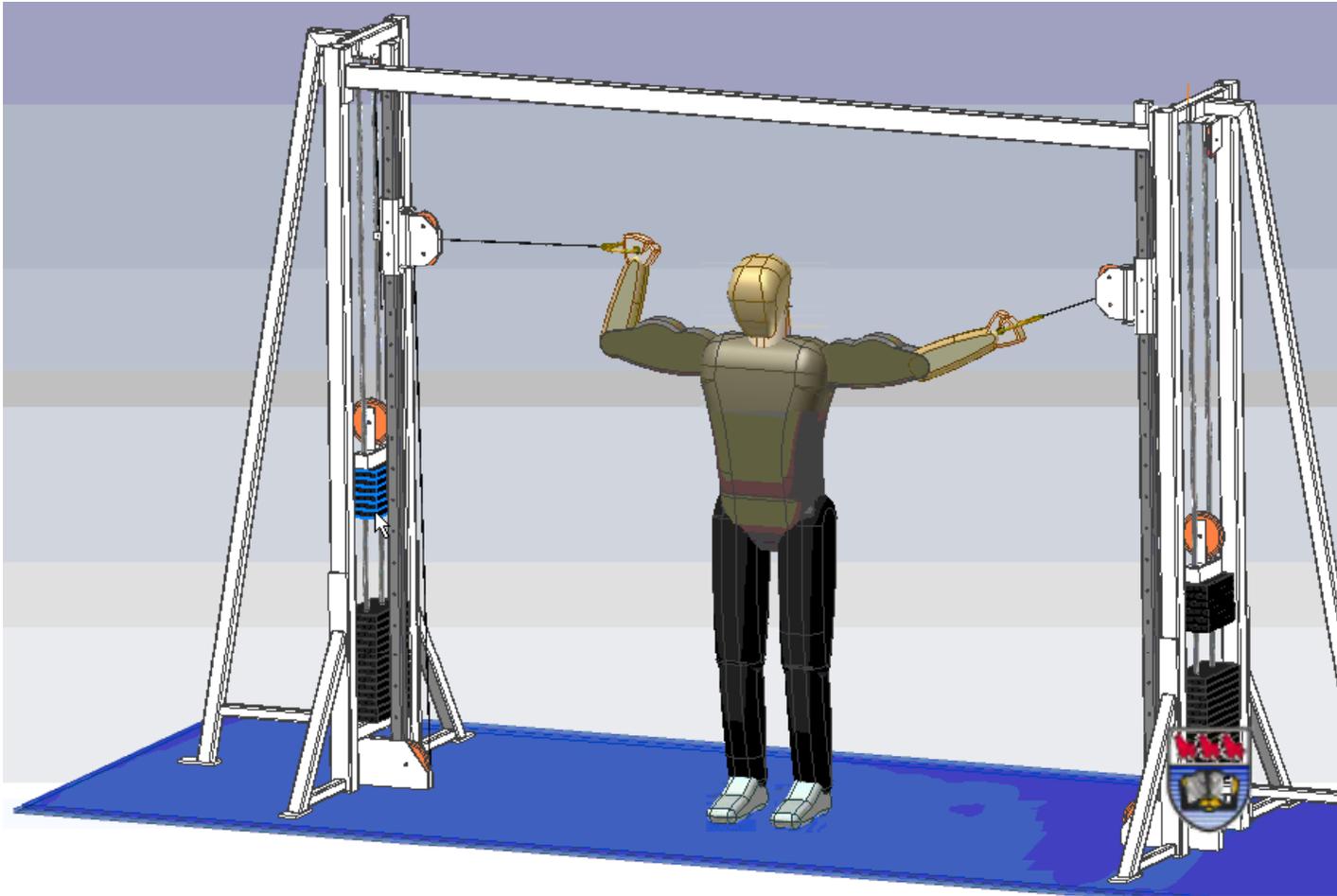


CAMTASIA: Complete solution for
recording, editing and publishing
screen videos





Animation Simulation



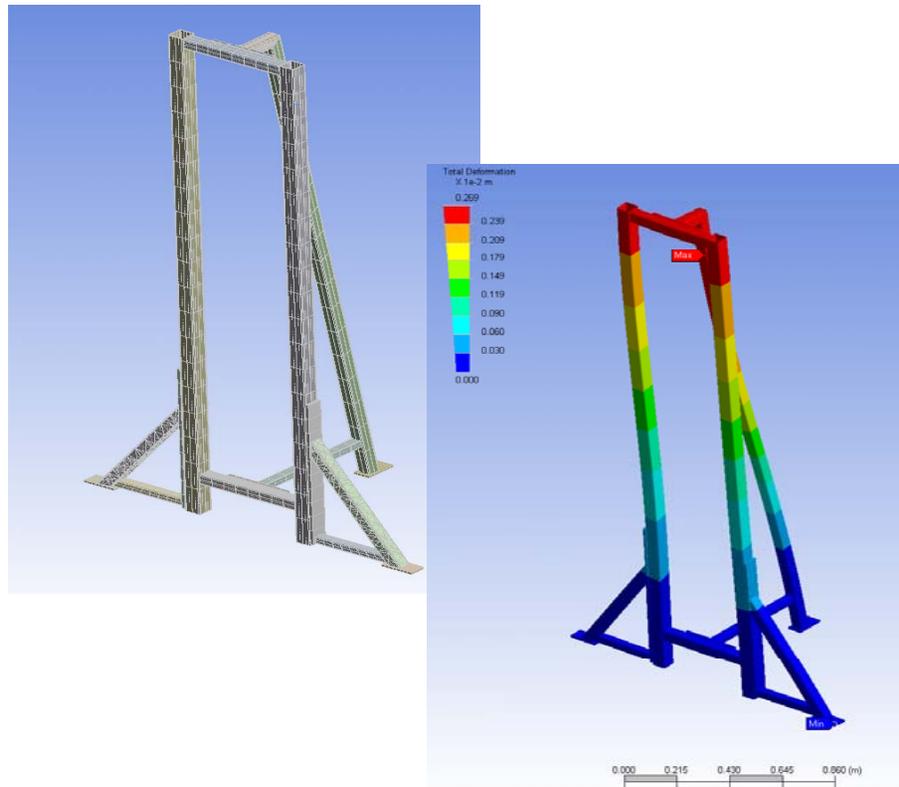
ANSYS

ANSYS Workbench is a desktop simulation tool

- Improved version from Classical Ansys
- Multiphysics functionality
- Powerful Meshing processor
- Integrated CFD solver

Steps:

- Geometry creation
- Meshing
- Defining BCs
- Solving
- Post processing

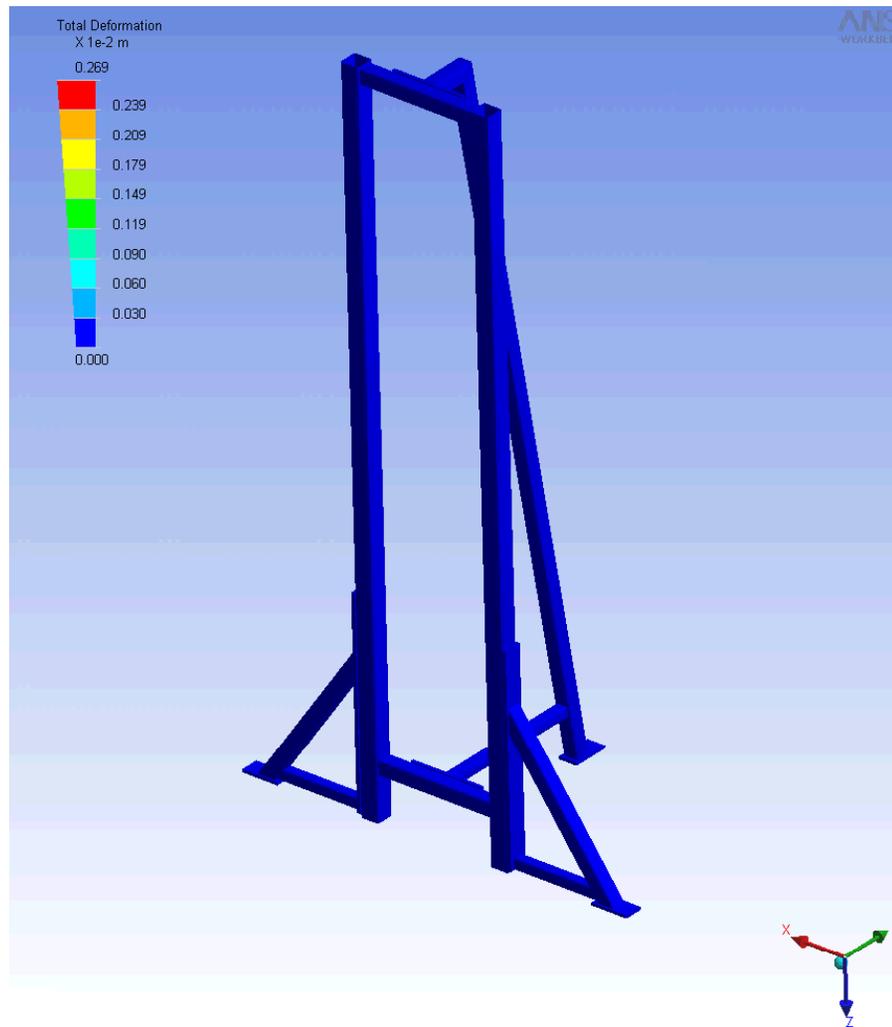


Boundary Condition

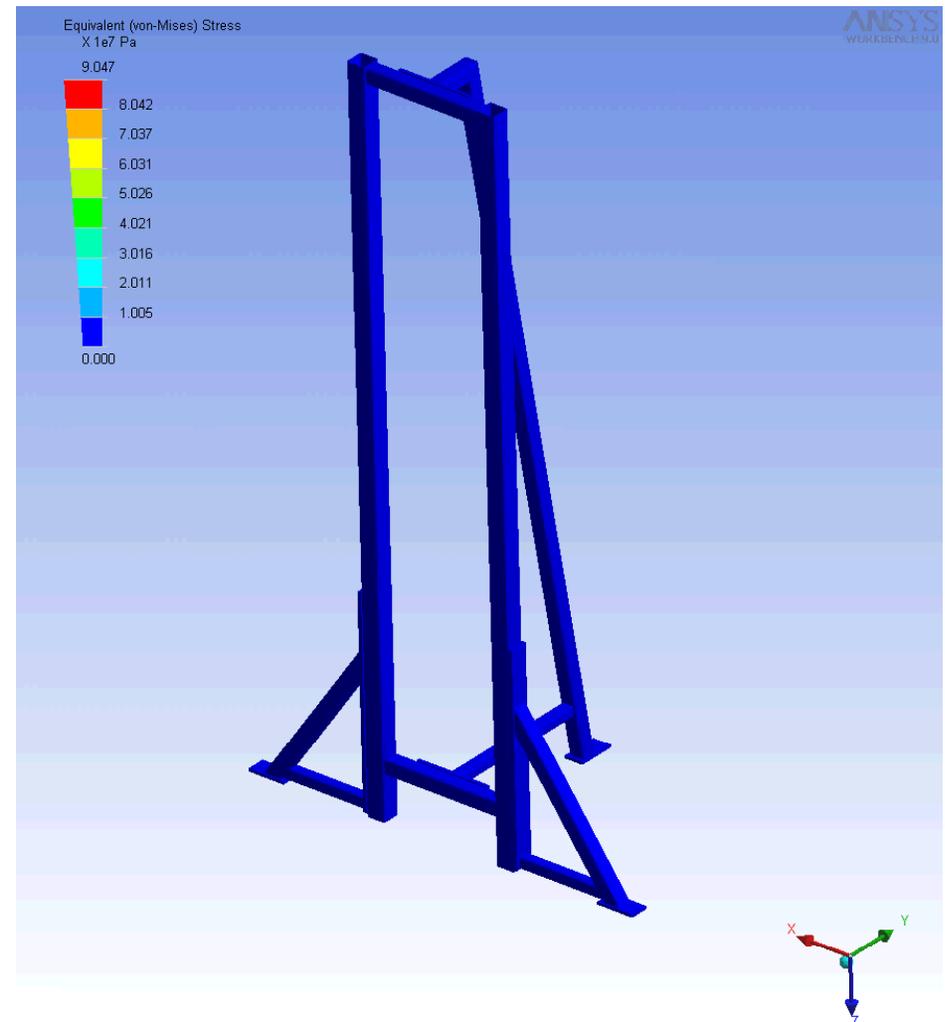
	Acceleration
	Standard Earth Gravity
	Rotational Velocity
	Pressure
	Force
	Remote Force
	Bearing Load
	Bolt
	Moment
	Fixed Support
	Given Displacement
	Remote Displacement
	Frictionless Support
	Compression Only Support
	Cylindrical Support
	Convection
	Given Temperature
	Internal Heat Generation
	Heat Flux
	Heat Flow
	Perfectly Insulated
	Magnetic Flux Parallel
	Conductor
	Motion Loads...
	Commands
	Outline Branch...
	Figure
	Comment

Ansys Results

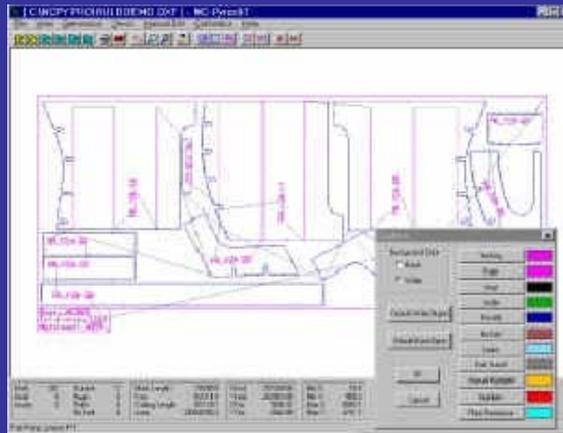
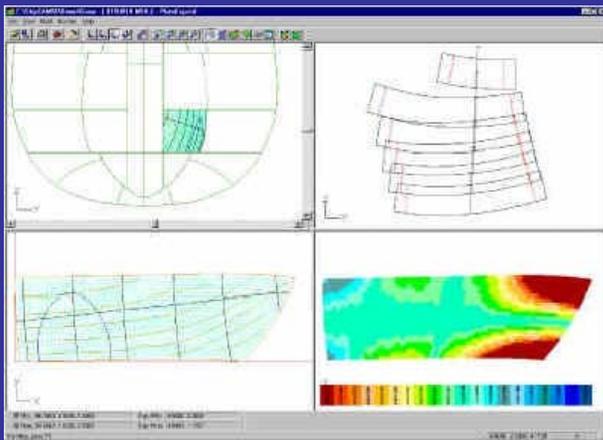
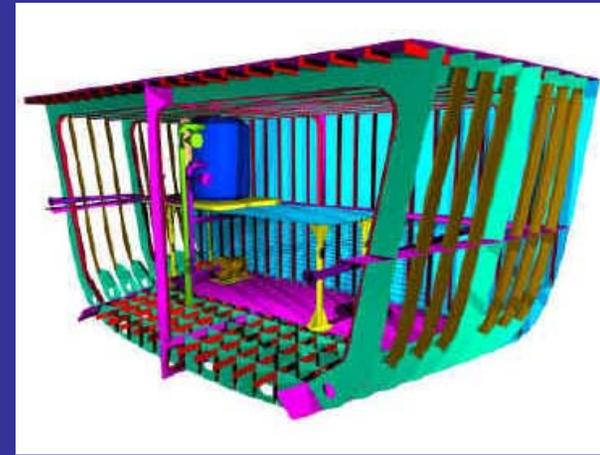
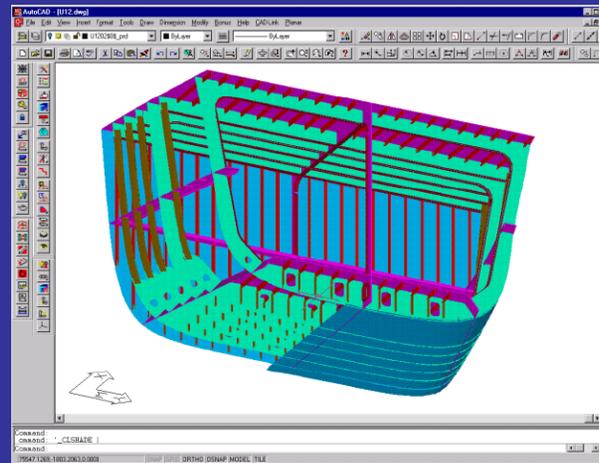
Deformation



Stress



CAD Applications through Interactive Graphical Programming in AutoCAD



Interactive Graphics Programming in CAD

General Requirement

One option of the final project is to develop an AutoCAD ADS [Interactive Graphical Program](#). You can pick up a subject of your own choice, develop the 3D interactive graphics program within AutoCAD using ADS, and present the results to the class.

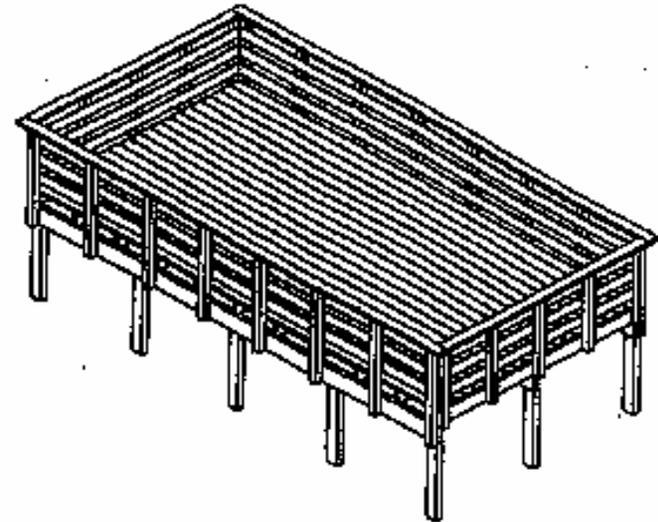
AutoLISP and ARX might be used as alternative programming environments with the permission from the instructor. The project can be of any types within the general scope of engineering applications. However, interactive graphical programming must be an evident part of the project.

Example Projects

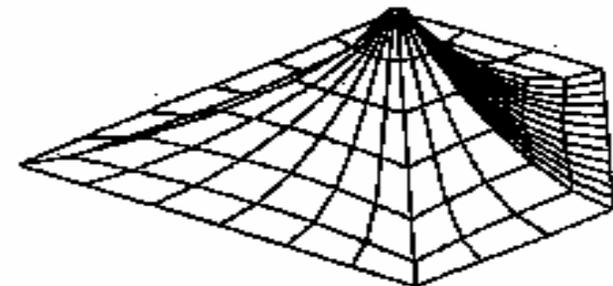
The following is a list of some of the *MECH4101520* projects done by previous students. The graphical outputs of some projects are attached.

Design Automation

- An Interactive Deck Design and Visualization Program Using AutoCAD and API (3D ADS)
- An Interactive Program for Tent Cutting Pattern Generation Using GKS
- Automated Bolt Design in AutoCAD, Bolt-CAD
- An Interactive Program for Designing A Tension Structure in AutoCAD
- A General Logo Making Program Using AutoCAD and ADS
- An Interactive Logo Design Program in Borland C
- Interactive Camshaft Design and Simulation
- Gear Pair Design and Simulation Using ADS and API
- A Program for Automated Geometric Tolerance Specification and Dimension Chain Database Formation in AutoCAD Environment

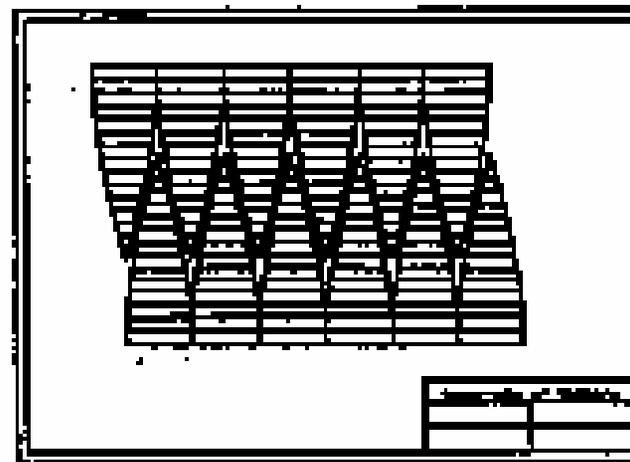
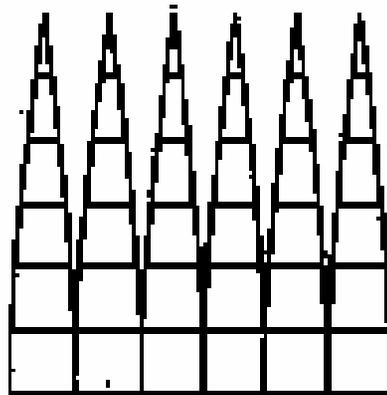
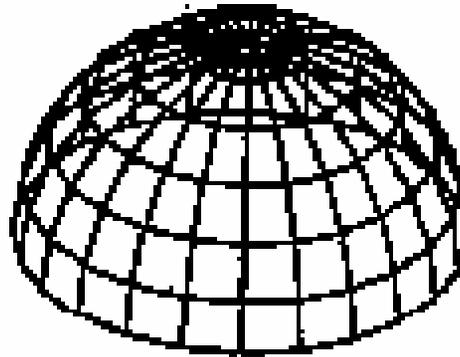


Interactive Deck Design



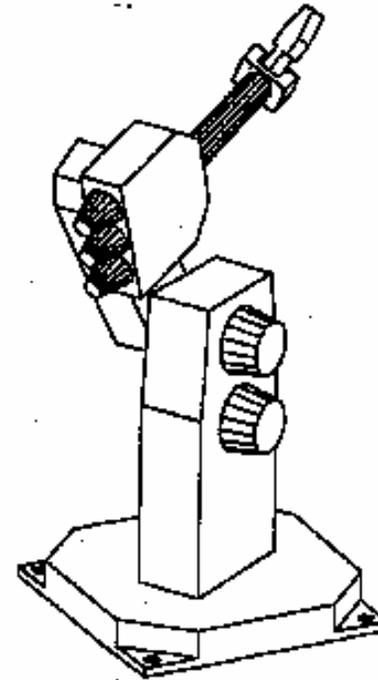
Tension Structure Design

Tent Cutting Pattern Generation

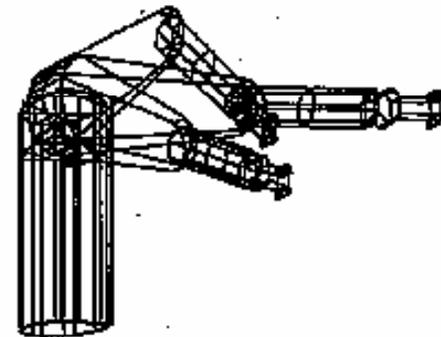


Computer Animation

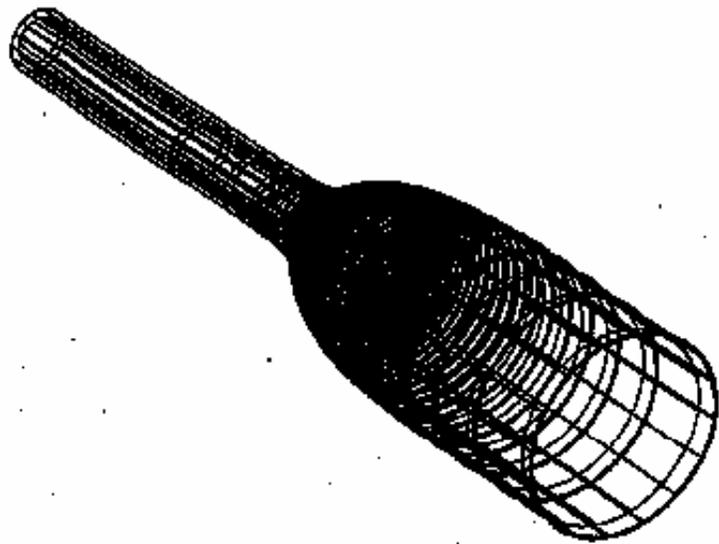
- An Interactive Robot Solid Modeling and Animation Program Using AutoCAD
- Interactive Robot Animation Using PHIGS
- Robot Simulation Using GKS
- Animation of a Four Cylinder Engine
- Visualization of Satellite Orbit
- Interactive Vehicle Control and Simulation
- Animation of Axisymmetric Potential Flow about a Rankine Half-Body of Revolution Fluid Flow Modeling of a Rankine Half Body and a Doublet



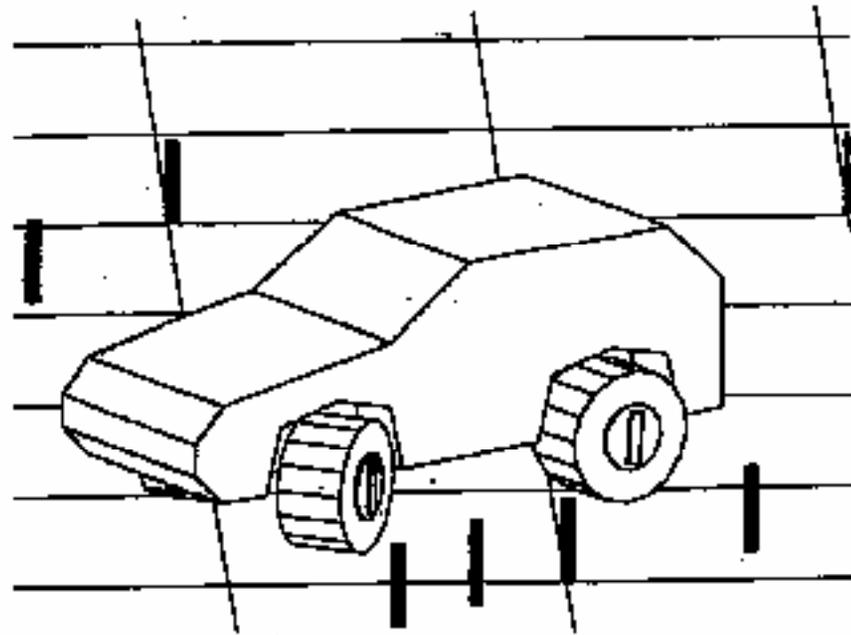
Robot Animation I



Robot Animation II



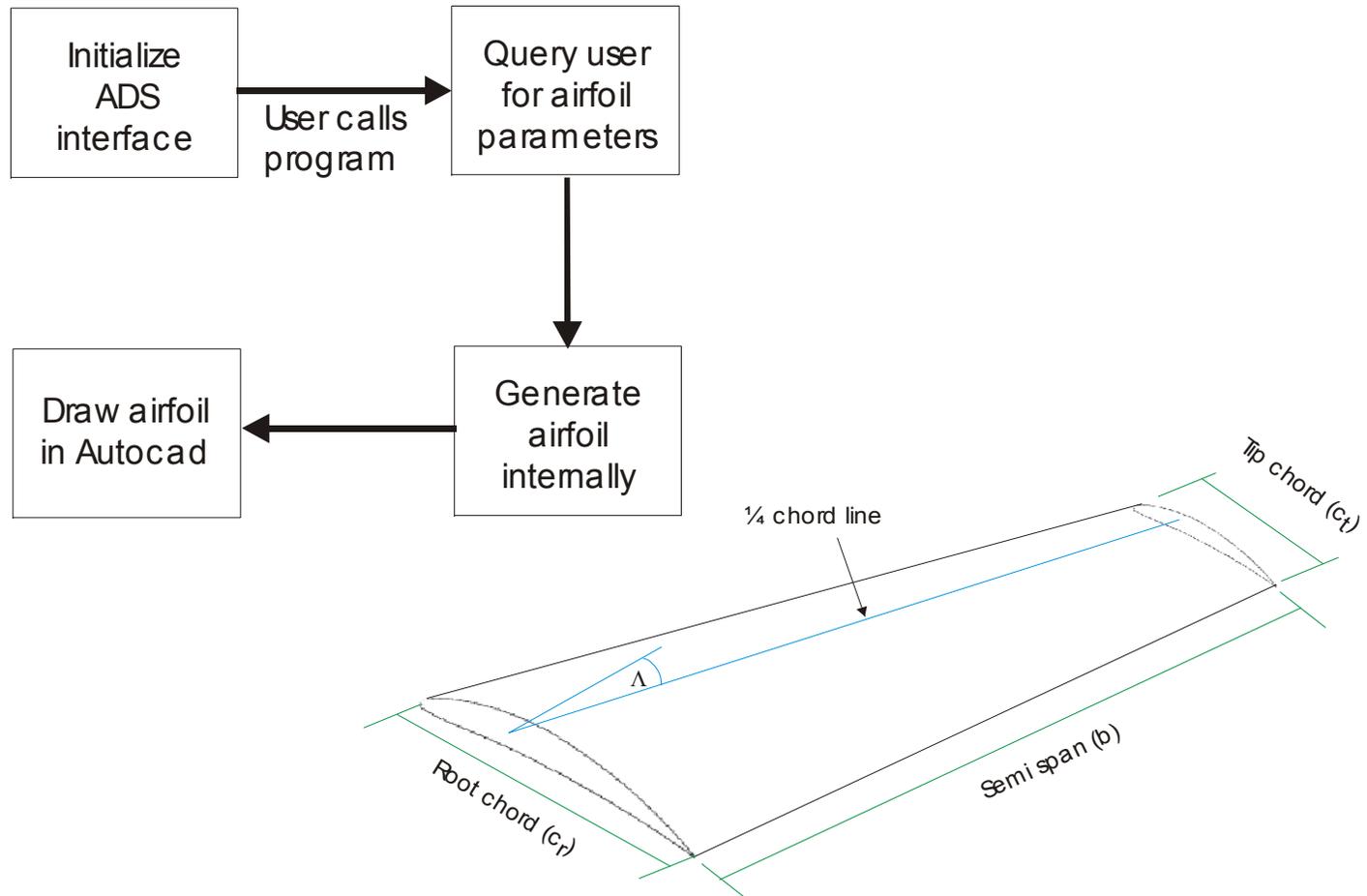
Flow Visualization



Interactive Vehicle Control and Simulation

Airfoil Generation Using AutoCAD™ ADS Programming

Gonçalo Pedro



Airfoil Generation Using AutoCAD™

Gonçalo Pedro

